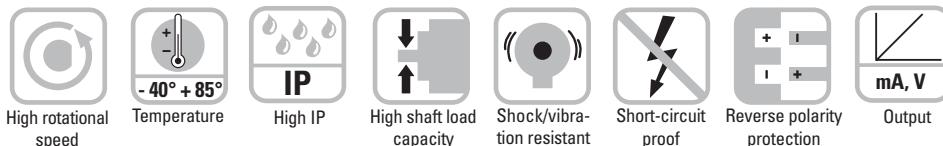


# Rotary Measuring Technology

## Magnetic measurement system

### Absolute Singleturn Encoder Type 3670



#### Rugged

- Ensures long service life and reliability of the application, no wear  
Non-contact measuring system
- Stays sealed even when subjected to harsh everyday use. Offers security against failures in the field  
Solid die-cast housing with up to IP 69K protection
- Can be used for a wide temperature range without additional expense.  
Wide temperature range (-40 °C ... +85 °C)
- Increased ability to withstand vibration and installation errors. Eliminates machine downtime and repairs.  
High shock resistance (> 500g) and vibration resistance (>30g)
- Can be used in outdoor applications with large fluctuations in temperature.  
Resistant against humidity and condensation.




#### Versatile

- Interface: 9-Bit SSI, 4 ... 20 mA, 0 ... 10 V  
One size available for different applications
- Measuring range: 45°; 90°; 180°; 360°:  
Suitable measuring range available for different applications
- Enables simple installation  
Reference point can be identified via LED (green)
- Easy diagnosis in case of fault condition  
Error indication via LED (red)
- Enables simple installation  
Torque stop slot and synchro flange available

#### Compact

- Can be used where space is tight  
Overall diameter of only 36 mm
- Compact encoder, suitable for large shafts  
Blind hollow shaft up to 10 mm, shaft up to 6,35 mm

#### Mechanical characteristics:

Max. speed:	6000 min <sup>-1</sup>
Starting torque	< 0,06 Nm
Weight:	appr. 0,2 kg
Protection acc. to EN 60 529:	IP 67 (IP 69k on request)
Arbeitstemperaturbereich:	-40 °C ... +85 °C
Materials:	Shaft: stainless steel, Flange: aluminium, Housing: die cast zinc, Cable: PUR
Shock resistance acc. to DIN-IEC 68-2-27:	5000 m/s <sup>2</sup> , 6 ms
Vibration resistance acc. to DIN-IEC 68-2-6:	300 m/s <sup>2</sup> , 10 ... 2000 Hz
Permanent shock resistance acc. to DIN-IEC 68-2-29	1000 m/s <sup>2</sup> , 2 ms
Vibration (broad-band random) to DIN-IEC 68-2-64	5 ... 2500 Hz, 100 m/s <sup>2</sup> - rms

# Rotary Measuring Technology

## Magnetic measurement system

**Kubler**

### Absolute Singleturn Encoder Type 3670

#### Electrical characteristics SSI Interface:

##### Sensor:

Supply voltage:	5 ... 30 V DC <sup>1)</sup>
Current consumption (w/o output load):	typ 22 mA, max. 41 mA
Reverse polarity protection at power supply (Ub):	Yes
Measuring range:	360°
Resolution/Code:	9 Bit/Binary
Linearity (25 °C)	<1.0 %
Repeat accuracy:	<0.2 %
Data refresh rate:	typ 100 µs
Status LED:	Green, reference point at 2,1°

##### SSI interface

Clock speed:	100 kHz ... 1 MHz
Output driver:	RS 485
Monoflop time typ./max.:	16 µs/20 µs
Short circuit proof outputs:	Yes <sup>2)</sup>
Permissible load/channel	typ. 120 Ohm (corresponding RS 485)

1) The supply voltage at the encoder input must not be less than 4.75 V (5 V - 5%)

2) Short circuit to 0V or to output, only one channel at a time, supply voltage correctly applied

#### Terminal assignment:

Sig.:	0V	+Ub	0 V Sens	+Ub Sens	+T	-T	+D	-D
Col.:	WH	BN	BU	RD	GN	YE	GY	PK

#### Electrical characteristics current interface 4 ... 20 mA:

##### Sensor:

Supply voltage:	18 ... 30 V DC
Current consumption (w/o output load):	typ 25 mA, max. 42 mA
Reverse polarity protection at power supply (Ub):	Yes
Measuring range:	45°, 90°, 180° or 360° (see also table „measuring range“)
Linearity (25 °C)	<1.0 % (360 ° measurement range)
Repeat accuracy:	<0.2 % (360 ° measurement range)
Status LED:	Green: reference point at 2.1° Red: sensor break detection, Control power supply

##### 4 ... 20 mA current loop

Output load: max. 500 ohms at 24 V DC

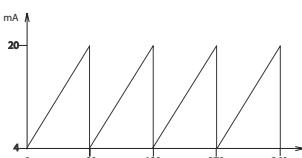
Settling time: < 1 ms ( $R_{load} = 400$  Ohm, 25 °C)

Short-circuit proof outputs: when the supply voltage is correctly applied, then output to output is short-circuit protected. But not output to 0 V or to +Ub

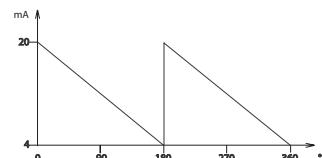
Supply voltage and sensor output signal are not galvanically isolated.

#### Example (output signal profile):

for range 90° cw



for range 180 ° ccw



#### Terminal assignment:

Sig.:	0V	+Ub	+I	-I
Col.:	WH	BN	GN	YE

#### Electrical characteristics voltage interface 0 ... 10 V:

##### Sensor:

Supply voltage:	20 ... 30 V DC
Current consumption:	typ 27 mA, max. 47 mA
(w/o output load):	
Reverse polarity protection at power supply (Ub):	Yes
Measuring range:	45°, 90°, 180° or 360° (see also table „measuring range“)
Linearity(25 °C)	<1.0 % (360 ° measurement range)
Repeat accuracy:	<0.2 % (360 ° measurement range)
Status LED:	Green: reference point at 2.1°

##### 0 ... 10 V voltage output

Current output: max. 10 mA

Settling time: < 1 ms ( $R_{load} = 1$  KOhm, 25 °C)

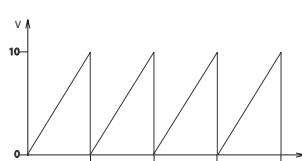
Short-circuit proof outputs: Yes<sup>2)</sup>

Supply voltage and sensor output signal are not galvanically isolated.

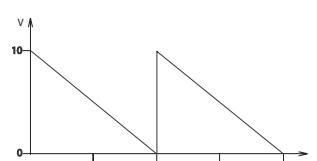
2) Short circuit to 0V or to output, only one channel at a time, supply voltage correctly applied

#### Example (output signal profile):

for range 90° cw



for range 180 ° ccw



#### Terminal assignment:

Sig.:	0V	+Ub	+Uo	-Uo
Col.:	WH	BN	GN	YE

#### General characteristics:

Conforms to CE requirements acc. to EN 61000-6-1, EN 61000-6-4, EN 61000-6-3 and EN 61000-4-8 (behaviour under magnetic influence).

# Rotary Measuring Technology

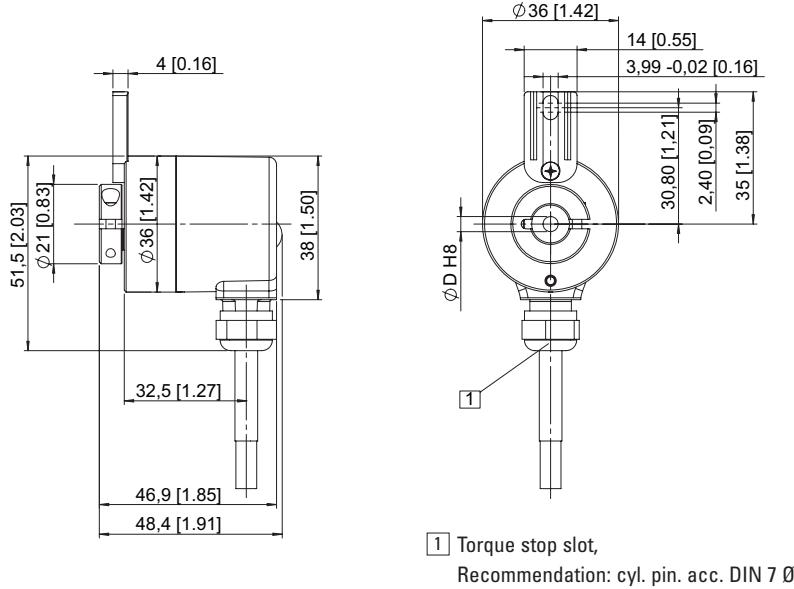
## Magnetic measurement system



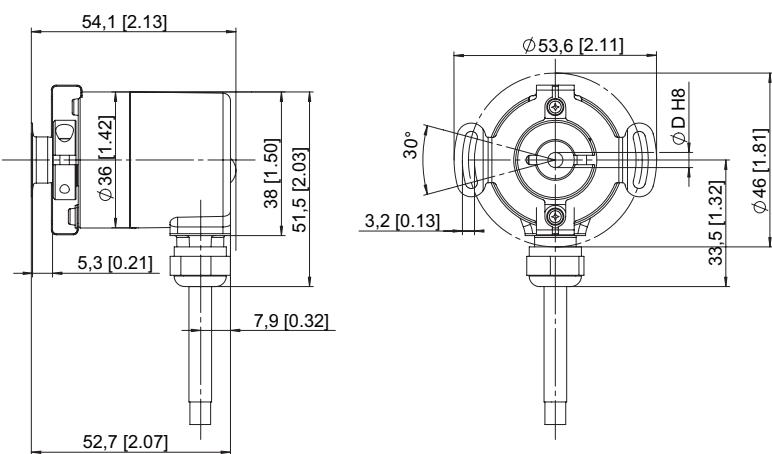
### Absolute Singleturn Encoder Type 3670

#### Dimensions

$\varnothing$  36 mm, Flange with long torque stop



$\varnothing$  36 mm, Synchro flange



# Rotary Measuring Technology

## Magnetic measurement system

**Kubler**

### Absolute Singleturn Encoder Type 3670

Order code:

8 . 3 6 7 0 . X X X X . X X X X<sup>1)</sup>

Type

Flange

2 = Flange with long torque stop  
5 = **Flange with stator coupling**

Hollow shaft

2 = **ø 6 mm**  
3 = ø 6,35 (1/4")  
4 = ø 8 mm  
6 = ø 10 mm

Output circuit / Power supply

2 = SSI/5 ... 30 V DC  
3 = 4 ... 20 mA/18 ... 30 V DC  
4 = 0 ... 10 V DC/20 ... 30 V DC

Option 1  
1 = IP 67 (IP 69k on request)

Option 2  
1 = **Count direction cw\***  
2 = Count direction ccw\*

Code type and division  
use corresponding table

Type of connection  
2 = **Cable radial (1 m PUR)**

\*cw = increasing code values when shaft turning clockwise (cw). Top view on shaft.

1) Series delivery as from February 2007

Preferred types are  
indicated in **bold**

#### Code type and division:

SSI interface

B9 = 9 Bit binary

Current interface 4 ... 20 mA

45 = 45° measurement range  
90 = 90° measurement range  
18 = 180° measurement range  
**36 = 360° measurement range**

Voltage interface 0 ... 10 V

45 = 45° measurement range  
90 = 90° measurement range  
18 = 180° measurement range  
**36 = 360° measurement range**

#### Measuring range:

Measuring range:	360°	180°	90°	45°
Internal resolution (Measuring range):	9 Bit	8 Bit	7 Bit	6 Bit
	512 steps	256 steps	128 steps	64 steps
Interfaces:	SSI	—	—	—
	4 ... 20 mA			
	0 ... 10 V			