

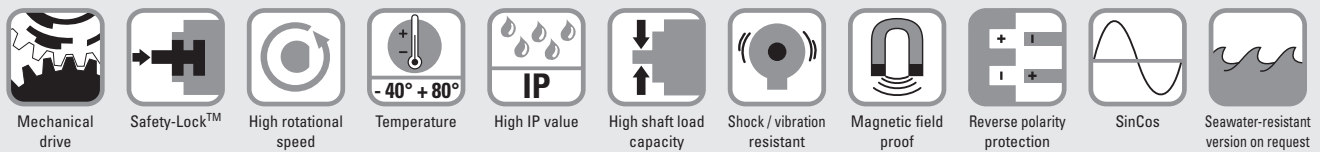
# Absolute Encoders – Multiturn

**Standard, optical**      **Sendix 5863 / 5883 (Shaft / Hollow shaft)**      **SSI / BiSS**



The Sendix 5863 and 5883 multiturn encoders with SSI or BiSS interface and optical sensor technology can achieve a resolution of max. 29 bits.

A through hollow shaft up to 14 mm and a blind hollow shaft up to 15 mm are available, as well as versions with additional SinCos or RS422 incremental track.



## Reliable

- Tried-and-tested in applications with the highest demands, such as in wind energy or mobile automation
- Absolutely reliable operation in areas with strong magnetic fields, thanks to mechanical gear with optical sensor technology
- Rugged die-cast housing, remains sealed even in harsh everyday use
- -40°C up to +90°C: use in wide temperature range. Protection IP67

## Versatile

- Available with SSI or BiSS interface and combined with SinCos incremental signals
- The right fixing solution or type of connection available for every application.
- SET button and LED for simple start-up

Absolute Encoders  
Multiturn

**Order code**      **8.5863** . XXXX . XX2X  
**Shaft version**      Type      a b c d e f g h

If for each parameter of an encoder the underlined preferred option is selected, then the delivery time will be 10 working days for a maximum of 10 pieces. Qts. up to 50 pcs. of these types generally have a delivery time of 15 working days.



<p><b>a Flange</b>  <u>1 = clamping flange, ø 58 mm, IP65</u>  <u>2 = synchro flange, ø 58 mm, IP65</u>          3 = clamping flange, ø 58 mm, IP67          4 = synchro flange, ø 58 mm, IP67          5 = square flange, 63,5 mm (2,5"), IP65          7 = square flange, 63,5 mm (2,5"), IP67</p> <p><b>b Shaft (ø x L), with flat</b>  <u>1 = 6 x 10 mm<sup>1)</sup></u>  <u>2 = 10 x 20 mm<sup>2)</sup></u>          3 = 6,35 x 22,2 mm (1/4" x 7/8")          4 = 9,5 x 22,2 mm (3/8" x 7/8")</p>	<p><b>c Interface / Power supply</b>          1 = SSI or BiSS / 5 V DC  <u>2 = SSI or BiSS / 10 ... 30 V DC</u>          3 = SSI or BiSS, 2048 ppr SinCos / 5 V DC          4 = SSI or BiSS, 2048 ppr SinCos / 10 ... 30 V DC          5 = SSI or BiSS / 5 V DC, with sensor output for monitoring the voltage on the encoder          6 = SSI or BiSS, 2048 ppr SinCos / 5 V DC, with sensor output for monitoring the voltage on the encoder          7 = SSI or BiSS and 2048 ppr incremental signals RS422 (TTL-comp.) / 5 V DC          8 = SSI or BiSS and 2048 ppr incremental signals RS422 (TTL-comp.) / 10 ... 30 V DC          9 = SSI or BiSS and 2048 ppr incremental signals RS422 (TTL-comp.) / 5 V DC, with sensor output for monitoring the voltage on the encoder</p>	<p><b>d Type of connection</b>          1 = axial cable (1 m PVC)  <u>2 = radial cable (1 m PVC)</u>          3 = M23 connector, 12-pin, axial  <u>4 = M23 connector, 12-pin, radial</u>          5 = M12 connector, 8-pin, axial<sup>3)</sup>          6 = M12 connector, 8-pin, radial<sup>3)</sup></p> <p><b>e Code</b>          B = SSI, Binary          C = BiSS, Binary  <u>G = SSI, Gray</u></p> <p><b>f Resolution<sup>4)</sup></b>          A = 10 bit ST + 12 bit MT          1 = 11 bit ST + 12 bit MT          2 = 12 bit ST + 12 bit MT  <u>3 = 13 bit ST + 12 bit MT</u>          4 = 14 bit ST + 12 bit MT          7 = 17 bit ST + 12 bit MT</p>	<p><b>g Inputs / Outputs<sup>4)</sup></b>  <u>2 = SET, DIR input</u>          additional status output</p> <p><b>h Options (Service)</b>          1 = no option          2 = status LED  <u>3 = SET button and status LED</u></p> <p><i>optional on request</i>          - Ex 2/22          - seawater-resistant          - special cable length</p>
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1) Preferred type only in conjunction with Flange type 2  
 2) Preferred type only in conjunction with Flange type 1  
 3) Can be combined only with output circuits 1 and 2  
 4) Resolution, preset value and counting direction factory-programmable

# Absolute Encoders – Multiturn

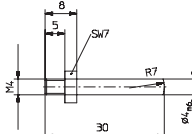
## Standard, optical      Sendix 5863 / 5883 (Shaft / Hollow shaft)      SSI / BiSS

<b>Order code</b> <b>Hollow shaft</b>	<b>8.5883</b> Type	<b>.XXXX.XX2X</b> a b c d e f g h	If for each parameter of an encoder the <u>underlined preferred option</u> is selected, then the delivery time will be 10 working days for a maximum of 10 pieces. Qts. up to 50 pcs. of these types generally have a delivery time of 15 working days.	<b>10 by 10</b>
<b>a Flange</b>	<b>c Output circuit / Power supply</b>	<b>d Type of connection</b>	<b>g Inputs / Outputs <sup>1)</sup></b>	
1 = with torque stop set, IP65 2 = with torque stop set, IP67 3 = with stator coupling, ø 65, IP65 4 = with stator coupling, ø 65, IP67 <b>5 = with stator coupling, ø 63, IP65</b> 6 = with stator coupling, ø 63, IP67	1 = SSI or BiSS / 5 V DC <b>2 = SSI or BiSS / 10 ... 30 V DC</b> 3 = SSI or BiSS, 2048 ppr SinCos / 5 V DC 4 = SSI or BiSS, 2048 ppr SinCos / 10 ... 30 V DC 5 = SSI or BiSS / 5 V DC, with sensor output for monitoring the voltage on the encoder 6 = SSI or BiSS, 2048 ppr SinCos / 5 V DC, with sensor output for monitoring the voltage on the encoder 7 = SSI or BiSS and 2048 ppr incremental signals RS422 (TTL-comp.) / 5 V DC 8 = SSI or BiSS and 2048 ppr incremental signals RS422 (TTL-comp.) / 10 ... 30 V DC 9 = SSI or BiSS and 2048 ppr incremental signals RS422 (TTL-comp.) / 5 V DC, with sensor output for monitoring the voltage on the encoder	2 = radial cable (1 m PVC) <b>4 = M23 connector, 12-pin, radial</b> 6 = M12 connector, 8-pin, radial <sup>2)</sup> <b>E = tangential cable outlet</b> <u>cable length 1 m (PVC cable)</u>	<b>2 = SET, DIR input</b> additional status output <b>h Options (Service)</b> 1 = no option 2 = status LED <b>3 = SET button and Status LED</b>	
<b>b Hollow shaft</b>		<b>e Code</b> B = SSI, Binary C = BiSS, Binary <b>G = SSI, Gray</b>	<b>i Resolution <sup>1)</sup></b> A = 10 bit ST + 12 bit MT 1 = 11 bit ST + 12 bit MT 2 = 12 bit ST + 12 bit MT <b>3 = 13 bit ST + 12 bit MT</b> 4 = 14 bit ST + 12 bit MT 7 = 17 bit ST + 12 bit MT	<i>optional on request</i> - Ex 2/22 - seawater-resistant - special cable length
3 = ø 10 mm <b>4 = ø 12 mm</b> 5 = ø 14 mm 6 = ø 15 mm (Blind hollow shaft) 8 = ø 9.52 mm [3/8"] 9 = ø 12.7 mm [1/2"]				

### Mounting accessory for shaft encoders

<b>Coupling</b>	Bellows coupling ø 19 mm for shaft 6 mm	<b>8.0000.1101.0606</b>
	Bellows coupling ø 19 mm for shaft 10 mm	<b>8.0000.1101.1010</b>

### Mounting accessory for hollow shaft encoders

<b>Cylindrical pin, long</b> for torque stops		With fixing thread	<b>8.0010.4700.0000</b>
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### Connection Technology

<b>Connector, self-assembly</b>	M12	<b>05.CMB-8181-0</b>
	M23	<b>8.0000.5012.0000</b>
<b>Cordset, pre-assembled with 2 m PVC cable</b>	M12	<b>05.WAKS8-2/P00</b>
	M23	<b>8.0000.6901.0002.0031</b>

Further accessories can be found in the Accessories section or in the Accessories area of our website at: [www.kuebler.com/accessories](http://www.kuebler.com/accessories).  
Additional connectors can be found in the Connection Technology section or in the Connection Technology area of our website at: [www.kuebler.com/connection\\_technology](http://www.kuebler.com/connection_technology).

### Mechanical characteristics

<b>Max. speed, shaft version</b>		<b>Moment of inertia</b>	
without shaft seal (IP65) up to 70°C	12 000 min <sup>-1</sup> , 10 000 min <sup>-1</sup> (continuous)	Shaft version	4.0 x 10 <sup>-6</sup> kgm <sup>2</sup>
without shaft seal (IP65) up to T <sub>max</sub>	8 000 min <sup>-1</sup> , 5 000 min <sup>-1</sup> (continuous)	Hollow shaft version	7.0 x 10 <sup>-6</sup> kgm <sup>2</sup>
with shaft seal (IP67) up to 70°C	11 000 min <sup>-1</sup> , 9 000 min <sup>-1</sup> (continuous)	<b>Load capacity of shaft</b>	radial 80 N
with shaft seal (IP67) up to T <sub>max</sub>	8 000 min <sup>-1</sup> , 5 000 min <sup>-1</sup> (continuous)		axial 40 N
<b>Max. speed, hollow shaft version</b>		<b>Weight</b>	approx. 0.45 kg
without shaft seal (IP65) up to 70°C	9 000 min <sup>-1</sup> , 6 000 min <sup>-1</sup> (continuous)	<b>Protection EN 60 529</b>	housing side IP67
without shaft seal (IP65) up to T <sub>max</sub>	6 000 min <sup>-1</sup> , 3 000 min <sup>-1</sup> (continuous)		shaft side IP65, opt. IP67
with shaft seal (IP67) up to 70°C	8 000 min <sup>-1</sup> , 4 000 min <sup>-1</sup> (continuous)	<b>EX approval for hazardous areas</b>	optional Zone 2 and 22
with shaft seal (IP67) up to T <sub>max</sub>	4 000 min <sup>-1</sup> , 2 000 min <sup>-1</sup> (continuous)	<b>Working temperature range</b>	-40°C ... +90°C <sup>3)</sup>
<b>Starting torque, shaft version</b>		<b>Materials</b>	shaft / hollow shaft stainless steel
without shaft seal (IP65)	< 0.01 Nm		flange aluminium
with shaft seal (IP67)	< 0.05 Nm		housing zinc die-cast housing
<b>Starting torque, hollow shaft version</b>			cable PVC
without shaft seal (IP65)	< 0.03 Nm	<b>Shock resistance acc. EN 60068-2-27</b>	2500 m/s <sup>2</sup> , 6 ms
		<b>Vibration resistance acc. EN 60068-2-6</b>	100 m/s <sup>2</sup> , 55 ... 2000 Hz

1) Resolution, preset value and counting direction factory-programmable  
2) Can be combined only with output circuits 1 and 2  
3) Cable version: -30°C ... +75°C

# Absolute Encoders – Multiturn

<b>Standard, optical</b>	<b>Sendix 5863 / 5883 (Shaft / Hollow shaft)</b>	<b>SSI / BiSS</b>
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General electrical characteristics	
<b>Power supply</b>	5 V DC + 5% or 10 ... 30 V DC
<b>Current consumption</b> (no load) 5 V DC	max. 80 mA
10 ... 30 V DC	max. 50 mA
<b>Reverse connection of the supply voltage (U<sub>B</sub>)</b>	yes (at 10 ... 30 V DC)
<b>UL-certified</b>	File 224618
<b>CE compliant acc. to</b>	EN 61000-6-2, EN 61000-6-4 and EN 61000-6-3
<b>RoHS compliant acc. to</b>	EU guideline 2002/95/EG

General interface characteristics	
<b>Output driver</b>	RS485 transceiver type
<b>Permissible load / channel</b>	max. 20 mA
<b>Signal level</b>	high typ. 3.8 V low at I <sub>Load</sub> = 20 mA typ. 1.3 V
<b>Short circuit proof outputs</b>	yes <sup>1)</sup>

SSI Interface	
<b>Singleturn resolution</b>	10 ... 14 bit and 17 bit <sup>2)</sup>
<b>Number of revolutions</b>	4096 (12 bit)
<b>Code</b>	Binary or Gray
<b>SSI clock rate</b>	≤ 14 bit 50 kHz ... 2 MHz ≥ 15 bit 50 kHz ... 125 kHz
<b>Monoflop time</b>	≥ 15 μs
<small>Note: If the clock starts cycling within the monoflop time, a second data transfer starts with the same data. If the clock starts cycling after the monoflop time, the data transfer starts with the new values. The update rate is dependent on the clock speed, data length and monoflop-time.</small>	
<b>Data refresh rate</b>	< 1 μs up to 14 bit 4 μs for 15 ... 17 bit
<b>Status and Parity bit</b>	on request

BiSS Interface	
<b>Singleturn resolution</b>	10 ... 14 bit and 17 bit, Programmable at the customer <sup>2)</sup>
<b>Number of revolutions</b>	4096 (12 bit)
<b>Code</b>	Binary
<b>Clock rate</b>	up to 10 MHz
<b>Max. update rate</b>	< 10 μs, depends on the clock rate and the data length
<b>Data refresh rate</b>	≤ 1 μs
<b>Note::</b>	<ul style="list-style-type: none"> <li>– Bidirectional, programmable parameters are: resolution, code, direction, alarms and warnings</li> <li>– Multi-cyclic data output, e.g. for temperature</li> <li>– CRC data verification</li> </ul>

SET input or SET button	
<b>Input</b>	active high
<b>Input type</b>	comparator
<b>Signal level</b>	high min: 60 % of +V (supply voltage) max: +V low max: 25 % of +V (supply voltage)
<b>Input current</b>	< 0.5 mA
<b>Min. pulse duration (SET)</b>	10 ms
<b>Timeout after SET signal</b>	14 ms
<b>Response time (DIR input)</b>	1 ms

The encoder can be set to zero at any position by means of a HIGH signal on the SET input or by pressing the optional SET button (with a pencil, ball-point pen or similar). Other preset values can be factory-programmed. The SET input has a signal processing time of approx. 1 ms. Once the SET function has been triggered, the encoder requires an internal processing time of approx. 15 ms before the new position data can be read. During this time the status output is at LOW.

Status output and LED	
<b>Output driver</b>	Open Collector, internal pull up resistor 22 kOhm
<b>Permissible load</b>	max. 20 mA
<b>Signal level</b>	high +V low < 1 V
<b>Active</b>	low
<small>The optional LED (red) and the status output serve to display various alarm or error messages. In normal operation the LED is OFF and the status output is HIGH (Open Collector with int. pull-up 22k).</small>	
<small>An active status output (LOW) displays:</small>	
<ul style="list-style-type: none"> <li>– Sensor error, singleturn or multiturn (soiling, glass breakage etc.)</li> <li>– LED fault (failure or ageing)</li> <li>– over- or under-temperature</li> </ul>	
<small>In the SSI mode, the fault indication can only be reset by switching off the power-supply to the device.</small>	

DIR input	
A HIGH signal switches the direction of rotation from the default CW to CCW. This function can also be factory-programmed to be inverted. If DIR is changed when the device is already switched on, then this will be interpreted as an error. The LED will come ON and the status output will switch to LOW.	

Power-on delay	
After Power-ON the encoder requires a time of approx. 150 ms before valid data can be read.	

Option Incremental outputs (A/B), 2048 ppr		
	SinCos	RS422 TTL-compatible
<b>Max. frequency -3dB</b>	400 kHz	400 kHz
<b>Signal level</b>	1 V <sub>pp</sub> (± 20%)	high: min. 2.5 V low: max. 0.5 V
<b>Short circuit proof</b>	yes	yes

1) Short circuit to 0V or to output, one channel at a time, supply voltage correctly applied  
2) Other options upon request

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### Terminal assignment

for output circuit 1 or 2 and type of connection 1, 2, 3 or 4 (2 control inputs, 1 status output)

Signal:	GND	+V	+C	-C	+D	-D	SET	DIR	Stat	N/C	N/C	N/C	PE
Cable colour:	WH	BN	GN	YE	GY	PK	BU	RD	BK	-	-	-	Shield
M23 connector:	1	2	3	4	5	6	7	8	9	10	11	12	PH

for output circuit 5 and type of connection 1, 2, 3 or 4 (2 control inputs, 1 status output, sensor outputs for voltage)

Signal:	GND	+V	+C	-C	+D	-D	SET	DIR	Stat	N/C	0V sens	+U <sub>B</sub> sens	PE
Cable colour:	WH	BN	GN	YE	GY	PK	BU	RD	BK	-	GY-PK	RD-BU	Shield
M23 connector:	1	2	3	4	5	6	7	8	9	10	11	12	PH

for output circuit 3, 4, 7 or 8 and type of connection 1, 2, 3 or 4 (2 control inputs, incremental track RS422 or SinCos)

Signal:	GND	+V	+C	-C	+D	-D	SET	DIR	A	A inv	B	B inv	PE
Cable colour:	WH	BN	GN	YE	GY	PK	BU	RD	BK	VT	GY-PK	RD-BU	Shield
M23 connector:	1	2	3	4	5	6	7	8	9	10	11	12	PH

for output circuit 6 or 9 and type of connection 1, 2, 3 or 4 (SinCos or incremental track, sensor outputs for voltage)

Signal:	GND	+V	+C	-C	+D	-D	A	A inv	B	B inv	0V sens	+U <sub>B</sub> sens	PE
Cable colour:	WH	BN	GN	YE	GY	PK	BU	RD	BK	VT	GY-PK	RD-BU	Shield
M23 connector:	1	2	3	4	5	6	7	8	9	10	11	12	PH

for output circuit 1 or 2 and type of connection 5 or 6 (2 control inputs)

Signal:	GND	+V	+C	-C	+D	-D	SET	DIR	Shield/PE
M12 connector:	1	2	3	4	5	6	7	8	PH

+V: Encoder Power Supply +V DC

GND: Encoder Power Supply Ground (0V)

+C, -C: Clock signal

+D, -D: Data signal

SET: Set input. The current position is set to zero

DIR: Direction input: If this input is active, the output values are counted backwards (decrease) when the shaft is turning clockwise.

Stat: Status output

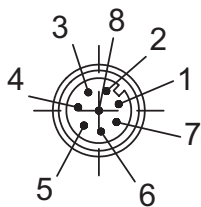
PE: Protective earth

PH: Plug connector housing (shield)

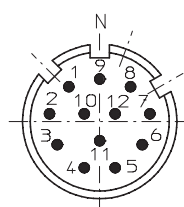
A, Ainv: Sin output (incremental)

B, Binv: Cos output (incremental)

### Top view of mating side, male contact base



M12 connector, 8-pin



M23 connector, 12-pin

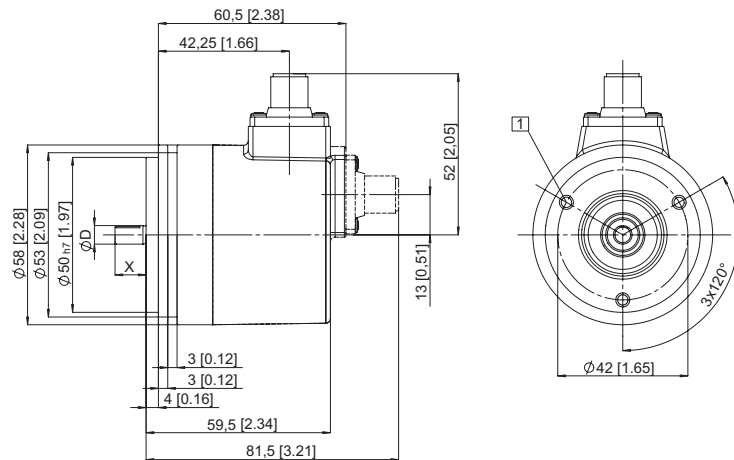
# Absolute Encoders – Multiturn

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## Dimensions shaft version

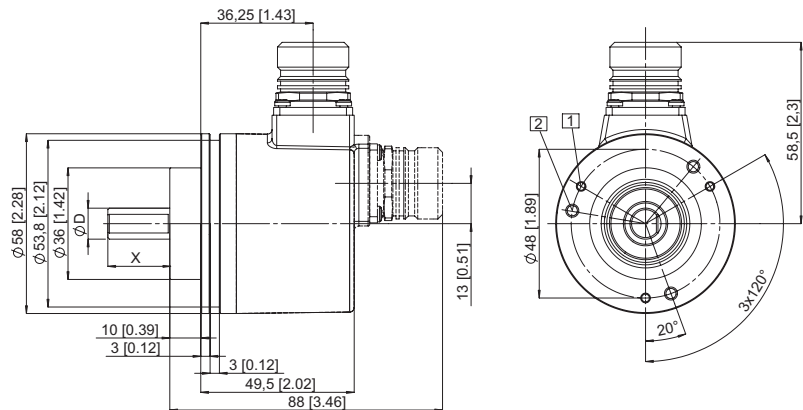
**Synchro flange,  $\varnothing$  58 mm**  
**M12, M23 connector, cable version**  
**Flange type 2 and 4**  
 (Drawing with M12 connector)

1 3 x M4, 6 [0.24] deep

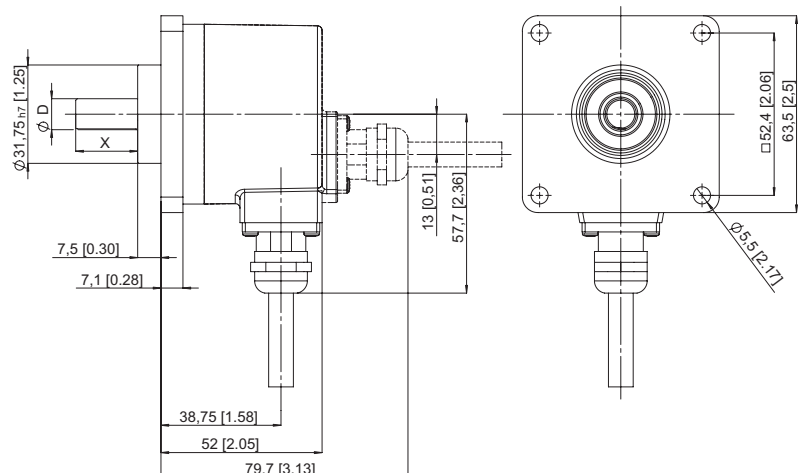


**Clamping flange,  $\varnothing$  58 mm**  
**M12, M23 connector, cable version**  
**Flange type 1 and 3**  
 (Drawing with M23 connector)

1 3 x M3, 6 [0.24] deep  
 2 3 x M4, 8 [0.32] deep



**Square flange,  $\square$  63.5 mm**  
**M12, M23 connector, cable version**  
**Flange type 5 and 7**  
 (Drawing with cable)



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**SSI / BiSS**

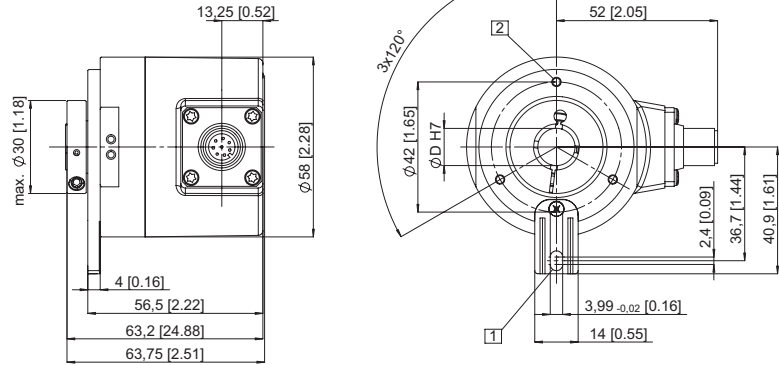
## Dimensions hollow shaft version

**Flange with torque stop set, long, ø 58 mm  
M12, M23 connector, cable version**

**Flange type 1 and 2**

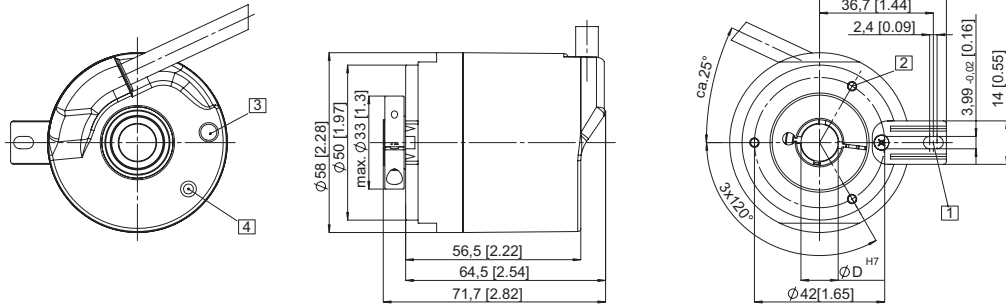
(Drawing with M12 connector)

- 1 Torque stop slot,  
Recommendation: Cylindrical pin DIN7, ø 4 mm
- 2 3 x M3, 6 [0.24] deep



**M12, M23 connector, cable version  
tangential cable outlet**

- 1 Torque stop slot,  
Recommendation:  
Cylindrical pin DIN7, ø 4 mm
- 2 M3, 5.5 [0.21] deep
- 3 Status LED
- 4 4 SET button

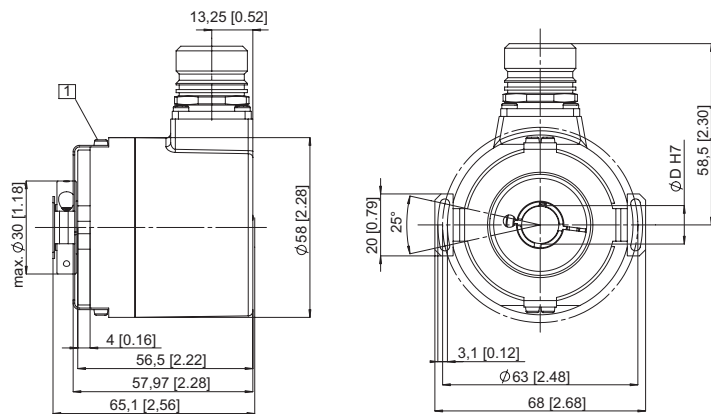


**Flange with stator coupling, ø 58 mm  
M12-, M23-connector, cable version**

**Flange type 5 and 6**

Pitch circle diameter for fixing screws 63 mm  
(Drawing with M23 connector)

- 1 Fixing screws DIN 912 M3 x 8  
(Washer included in delivery)



**Flange with stator coupling, ø 58 mm  
Flange type 3 and 4**

Pitch circle diameter for fixing screws 65 mm  
(Drawing with cable)

