4

Controls – Soft Starters and Solid-State Switching Devices



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Technical Information

can be found at

 $\frac{www.siemens.com/industrial-controls/}{support}$

under Product List

- Technical Specifications

under Entry List

- Updates
- Downloads
- FAQ
- Manuals/Operating instructions
- Characteristic curves
- Certificates

and at

www.siemens.com/industrial-controls/configurators

- Configurators

Controls — **Soft Starters and Solid-State Switching Devices**

Introduction

Overview





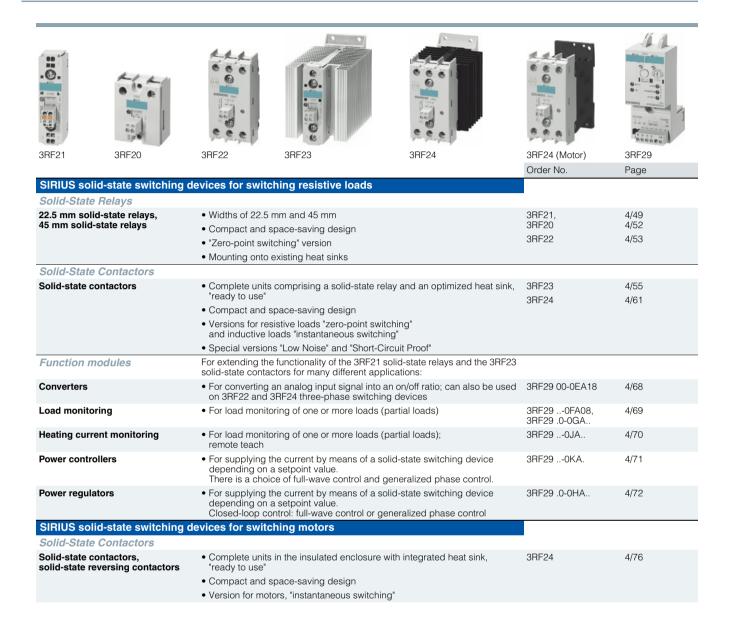


| 2DI | MOU | |
|-----|-----|--|

| 3RW30 | 3RW40 | 3RW44 | | |
|--------------|-------------------|--|-----------|------|
| | | | Order No. | Page |
| 3RW Soft S | tarters | | | |
| 3RW soft st | arters for standa | ard applications | _ | |
| 3RW30 soft s | tarters | SIRIUS 3RW30 soft starters for soft starting of three-phase asynchronous motors Performance range of up to 55 kW (at 400V) | 3RW30 | 4/8 |
| 3RW40 soft s | tarters | SIRIUS 3RW40 soft starters with the integral functions Solid-state motor overload and intrinsic device protection and adjustable current limiting for the soft starting and stopping of three-phase asynchronous motors Performance range of up to 250 kW (at 400 V) | 3RW40 | 4/13 |
| 3RW soft st | arters for high-f | eature applications | | |
| 3RW44 soft s | tarters | In addition to soft starting and soft ramp-down, the solid-state SIRIUS 3RW44 soft starters provide numerous functions for higher-level requirements Performance range Up to 710 kW (at 400 V) in inline circuit and up to 1200 kW (at 400 V) in inside-delta circuit | 3RW44 | 4/24 |

Controls – Soft Starters and Solid-State Switching Devices

Introduction



Soft Starters and Solid-State Switching Devices

General data

Overview

SIRIUS 3RW Soft Starters



SIRIUS 3RW soft starters permit soft starting and smooth rampdown of three-phase asynchronous motors. Depending on the scope of functions required it is possible to choose between:

- Soft starters for Standard applications
- Soft starters for high-feature applications

SIRIUS 3RW - Service-proven in many applications

Functions of the SIRIUS soft starters include:

- Soft starting and smooth ramp-down
- Stepless starting
- Torque control and limitation

Cost-efficient operation

The advantages of SIRIUS soft starters at a glance:

- Reduction of current peaks
- Avoidance of mains voltage fluctuations during starting
- Reduced load on the power supply network
- Reduction of the mechanical load in the operating mechanism
- Considerable space savings and reduced wiring compared with conventional starters
- Maintenance-free switching
- Very easy handling
- Fits perfectly in the SIRIUS modular system

SIRIUS 3RF2 solid-state switching devices



The SIRIUS 3RF2 solid-state switching devices reliably switch a wide range of different loads with alternating voltages in 50 and 60 Hz systems.

Solid-state switching devices for resistive loads

- Solid-State Relays
- Solid-State Contactors
- Function modules

Solid-state switching devices for switching motors

- Solid-State Contactors
- Solid-state reversing contactors

SIRIUS 3RF2 - for almost unending activity

Conventional electromechanical controlgear is often overtaxed by the rise in the number of switching operations. A high switching frequency results in frequent failure and short replacement cycles. However, this does not have to be the case, because with the latest generation of our SIRIUS 3RF2 solid-state switching devices we provide you with solid-state relays and contactors with a particularly long endurance - for almost unending activity even under the toughest conditions and under high mechanical load, but also in noise-sensitive areas.

Proved time and again in service

SIRIUS 3RF2 solid-state switching devices have firmly established in industrial applications. They are used above all in applications where loads are switched frequently – mainly with resistive load controllers, with the control of electrical heat or the control of valves and motors in conveyor systems. In addition to its use in areas with high switching frequencies, their silent switching means that SIRIUS is also ideally suited for use in noise-sensitive areas, such as offices or hospitals.

The most reliable solution for any application

Compared to mechanical controlgear, our SIRIUS 3RF2 solid-state switching devices stand out due to their considerably longer service life. Thanks to the high product quality, their switching is extremely precise, reliable and, above all, insusceptible to faults. With its variable connection methods and a wide spread of control voltages, the SIRIUS 3RF2 family is universally applicable. Depending on the individual requirements of the application, our modular controlgear can also be quite easily expanded by the addition of standardized function modules.

General data

Soft Starters and Solid-State Switching Devices

Ideal for operation with heating control systems

The 3RF2 solid-state switching devices can be used for example in the SIPLUS HCS300I heating control system. They are optimally connected to the digital output module of the HCS300I by means of preassembled cables. This saves considerable wiring outlay in the control circuit and shortens mounting time.



The HCS300I is a modular heating control system for the optimization of plastic processing machines. It enables individual solutions for many different heating control applications. With each basic unit it is possible to use up to four 6-channel digital outputs to control solid-state switching devices and four 4-channel temperature measuring modules. Current or current-and-voltage measuring modules can be used to monitor the loads. Communication with the higher-level control system is through Profibus DP

See also www.siemens.de/heizungssteuerung

Also for switching motors

In order to achieve higher productivity, the switching frequency is continuously increased. It is no problem for our SIRIUS solid-state contactors to switch motors. With induction motors up to 7.5 kW, they can reliably withstand even the highest switching frequencies. Even a continuous change in the direction of rotation is possible with the solid-state reversing contactors. Both versions can be perfectly combined with components from the SIRIUS modular system. Connecting with SIRIUS motor starter protectors or SIRIUS overload relay can be implemented without any further steps.

Always on the sunny side with SIRIUS

Because SIRIUS 3RF2 offers even more:

- The space-saving and compact side-by-side mounting ensure reliable operation up to an ambient temperature of +60 °C.
- Thanks to fast configuration and the ease of mounting and start-up, you save not only time but also expenses.

Connection methods

The devices are available with screw terminals (box terminals), spring-type terminals or ring terminal lugs.

- Screw terminals
- Spring-type terminals
- Ring terminal lug connections

The terminals are indicated in the selection and ordering data by orange backgrounds.

Selection and ordering data

Inscription labels for all series

| | Designation | Labeling area (W x H) | Color | DT | Order No. | Price per PU | PU (UNIT, SET, M) | PS* | PG | Weight per PU approx. |
|---|---------------------------------------|--------------------------|---------------------|----|----------------|-----------------|-------------------------|------------|-----|-----------------------|
| | | mm x mm | | | | | | | | kg |
| Blank labels | | | | | | | | | | |
| | Unit labeling plates for "SIRIUS" 1) | 10 x 7 | Pastel turquoise | D | 3RT19 00-1SB10 | | 100 | 816 units | 101 | 0.100 |
| | | 20 x 7 | Pastel turquoise | С | 3RT19 00-1SB20 | | 100 | 340 units | 101 | 0,200 |
| 0_014296 | Labels for sticking for SIRIUS | 19 x 6 | Pastel turquoise | D | 3RT19 00-1SB60 | | 100 | 3060 units | 101 | 0.100 |
| Unit labeling plates (1 frame = 20 units) | | 19 x 6 | Zinc yellow | С | 3RT19 00-1SD60 | | 100 | 3060 units | 101 | 0.100 |

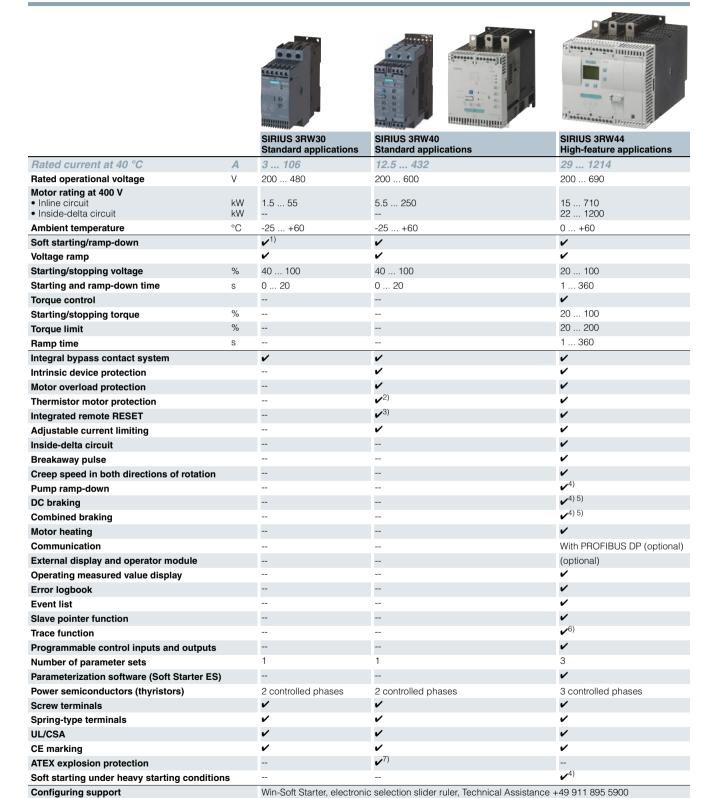
Computer labeling system for individual inscription of unit labeling plates available from: murrplastik Systemtechnik GmbH, D-71570 Oppenweiler, Germany www.murrplastik.de

^{*} You can order this quantity or a multiple thereof.

General data

SIRIUS 3RW Soft Starters

Overview



[✔] Function is available; -- Function is not available.

You can find further information on the Internet at: www.siemens.com/softstarter

¹⁾ Only soft starting available for 3RW30.

²⁾ Optional up to size S3 (device variant).
3) Available for 3RW40 2. to 3RW40 4.; optional for 3RW40 5. and 3RW40 7...
4) Calculate soft starter and motor with size allowance where required.

⁵⁾ Not possible in inside-delta circuit.

⁶⁾ Trace function with Soft Starter ES software.

⁷⁾ Use upstream disconnect mechanism

General data

Selection aid for soft starters

| Application | SIRIUS 3RW30 Standard applications | SIRIUS 3RW40 Standard applications | SIRIUS 3RW44 High-feature applications |
|---|---------------------------------------|---------------------------------------|---|
| Normal starting (CLASS 10) | | | |
| Pumps | • | • | • |
| Pumps with special pump ramp-down (to prevent water hammer) | | | • |
| Heat pumps | • | • | • |
| Hydraulic pumps | 0 | • | • |
| Presses | О | • | • |
| Conveyor belts | 0 | • | • |
| Roller conveyors | О | • | • |
| Screw conveyors | 0 | • | • |
| Escalators | | • | • |
| Piston compressors | | • | • |
| Screw compressors | | • | • |
| Small fans ¹⁾ | | • | • |
| Centrifugal blowers | | • | • |
| Bow thrusters | | • | • |
| | | | |
| Heavy starting (CLASS 20) | | | |
| Stirrer | | О | • |
| Extruders | | 0 | • |
| Lathes | | О | • |
| Milling machines | | О | • |
| | | | |
| Very heavy starting (CLASS 30) | | | |
| Large fans ²⁾ | | | • |
| Circular saws/bandsaws | | | • |
| Centrifuges | | | • |
| Mills | | | • |
| Breakers | | | • |
| | | | |

recommended soft starter, O possible soft starter

Boundary conditions

| Туре | Maximum starting time | Current limiting % | Starts per hour 1/h |
|--------------------------------|-----------------------|--------------------|------------------------|
| Normal starting (CLASS 10) | | | |
| • 3RW30 | 3 | 300 | 20 |
| • 3RW40/44 | 10 | 300 | 5 |
| Heavy starting (CLASS 20) | | | |
| • 3RW40 2., 3RW40 3., 3RW40 4. | 20 | 300 | 5 |
| • 3RW40 5., 3RW40 7., 3RW44 | 40 | 350 | 1 |
| Very heavy starting (CLASS 30) | | | |
| • 3RW44 | 60 | 350 | 1 |

The quoted motor ratings are only approximate values. The soft starter should always be designed on the basis of the motor current (rated operational current). In the event of deviating conditions, it may be necessary to choose a larger device.

Motor rating data are based on DIN 42973 (kW) and NEC 96/UL 508 (hp).

Benefits

The advantages of the SIRIUS soft starters at a glance:

- Soft starting and smooth ramp-down (only soft starting available for 3RW30)
- Stepless starting
- Reduction of current peaks
- Avoidance of mains voltage fluctuations during starting
- Reduced load on the power supply network

- Reduction of the mechanical load in the operating mechanism
- Considerable space savings and reduced wiring compared with conventional starters
- Maintenance-free switching
- Very easy handling
- Fits perfectly in the SIRIUS modular system

¹⁾ The mass inertia of the fan is <10 times the mass inertia of the motor

²⁾ The mass inertia of the fan is \geq 10 times the mass inertia of the motor

3RW30, 3RW40 for Standard Applications

3RW30

Overview

The SIRIUS 3RW30 soft starters reduce the motor voltage through variable phase control and increase it in ramp-like mode from a selectable starting voltage up to mains voltage. During starting, these devices limit the torque as well as the current and prevent the shocks which arise during direct starts or wye-delta starts. In this way, mechanical loads and mains voltage dips can be reliably reduced.

Soft starting reduces the stress on the connected equipment and results in lower wear and therefore longer periods of trouble-free production. The selectable start value means that the soft starters can be adjusted individually to the requirements of the application in question and unlike wye-delta starters are not restricted to two-stage starting with fixed voltage ratios.

The SIRIUS 3RW30 soft starters are characterized above all by their small space requirements. Integrated bypass contacts mean that no power loss has to be taken into the bargain at the power semiconductors (thyristors) after the motor has started up. This cuts down on heat losses, enabling a more compact design and making external bypass circuits superfluous.

Various versions of the SIRIUS 3RW30 soft starters are available:

- Standard version for fixed-speed three-phase motors, sizes S00, S0, S2 and S3, with integrated bypass contact system
- Version for fixed-speed three-phase motors in a 22.5 mm enclosure without bypass

Soft starters rated up to 55 kW (at 400 V) for standard applications in three-phase networks are available. Extremely small sizes, low power losses and simple commissioning are just three of the many advantages of this soft starter.

Functionality

The space required by the compact SIRIUS 3RW30 soft starter is often only about one third of that required by a contactor assembly for wye-delta starting of comparable rating. This not only saves space in the control cabinet and on the standard mounting rail but also does away completely with the wiring work needed for wye-delta starters. This is notable in particular for higher motor ratings which are only rarely available as fully wired solutions.

At the same time the number of cables from the starter to the motor is reduced from six to three. Compact dimensions, short start-up times, easy wiring and fast commissioning make themselves felt as clear-cut cost advantages.

The <u>bypass contacts</u> of these soft starters are protected during operation by an integrated solid-state arc quenching system. This prevents damage to the bypass contacts in the event of a fault, e.g.brief disconnection of the control voltage, mechanical shocks or life-related component defects on the coil operating mechanism or main contact spring.

The new series of devices comes with the "polarity balancing" control method, which is designed to prevent direct current components in two-phase controlled soft starters. On two-phase controlled soft starters the current resulting from superimposition of the two controlled phases flows in the uncontrolled phase. This results for physical reasons in an asymmetric distribution of the three phase currents during the motor ramp-up. This phenomenon cannot be influenced, but in most applications it is non-critical

Controlling the power semiconductors results not only in this asymmetry, however, but also in the previously mentioned direct current components which can cause severe noise generation on the motor at starting voltages of less than 50 %. The control method used for these soft starters eliminates these direct current components during the ramp-up phase and prevents the braking torque which they can cause.

It creates a motor ramp-up that is uniform in speed, torque and current rise, thus permitting a particularly gentle, two-phase starting of the motors. At the same time the acoustic quality of the starting operation comes close to the quality of a three-phase controlled soft starter. This is made possible by the on-going dynamic harmonizing and balancing of current half-waves of different polarity during the motor ramp-up. Hence the name "polarity balancing".

- Soft starting with voltage ramp; the starting voltage setting range U_s is 40 % to 100 % and the ramp time t_R can be set from 0 s to 20 s
- Integrated bypass contact system to minimize power loss
- Setting with two potentiometers
- · Simple mounting and commissioning
- Mains voltages 50/60 Hz, 200 to 480 V
- Two control voltage versions 24 V AC/DC and 110 to 230 V AC/DC
- Wide temperature range from -25 °C to +60 °C
- The built-in auxiliary contact ensures user-friendly control and possible further processing within the system (for status graphs see Page 4/12)

Application

The 3RW30 soft starters are suitable for soft starting of three-phase asynchronous motors.

Due to two-phase control, the current is kept at minimum values in all three phases throughout the entire starting time. Due to continuous voltage influencing, the current and torque peaks which are unavoidable in the case of wye-delta starters for instance do not occur.

Application areas

See "Selection aid for soft starters" on Page 4/7.

3RW30, 3RW40 for Standard Applications

3RW30











| 3RW30 18 | 3-1BB14 | | 3R | W30 28-1BB | 14 | | 3RW30 | 38-1BB | 14 | | 3RW30 47-1BB14 | | 3RW30 | 03-2CB | 54 | |
|---|--------------------|---------------------------------------|---------------------------|--------------------------------------|-------------------|-------------------------|---------------|--------|------------|-------------|----------------------------------|--------|----------------------|------------------|-----|-----------------|
| Ambient t | emperat | ure 40 °C | | Ambient to | emperat | ure 50 ° | С | | Size | DT | Order No. | Price | PU | PS* | PG | Weigh |
| Rated opera-tional current $I_{\rm e}^{1)}$ | tion mo | power of otors for r ional volt | rated | Rated operational current $I_e^{1)}$ | motors | power of for rate by Ue | | | | | | per PU | (UNIT, SET, M) | | | per P approx |
| | 230 V | 400 V | 500 V | | 200 V | 230 V | 460 V | 575 V | | | | | | | | |
| А | kW | kW | kW | А | hp | hp | hp | hp | | | | | | | | |
| Rated o | peratio | nal vol | tage <i>U_e</i> | ₉ 200 48 | 0 V ²⁾ | | | | | | | | | | | |
| With scr | ew term | inals | | | | | | | | | | | | | | |
| 3.6 6.5 9 | 0.75 1.5 2.2 | 1.5 3 4 | | 3 4.8 7.8 | 0.5 1 2 | 0.5 1 2 | 1.5 3 5 | | S00 S00 | > | 3RW30 13-1BB□4 3RW30 14-1BB□4 | | 1 | 1 unit 1 unit | 131 | 0.58 |
| 9 12.5 | 3 | 4 5.5 | | 7.0 11 | 3 | 3 | ა 7.5 | | S00 S00 | > | 3RW30 16-1BB□4 3RW30 17-1BB□4 | | 1 | 1 unit 1 unit | | 0.58 |
| 17.6 | 4 | 5.5 7.5 | | 17 | 3 | 3 | 7.5 10 | | S00 | | 3RW30 17-1BB□4 3RW30 18-1BB□4 | | | 1 unit | | 0.58 |
| • With spr | ring-type | terminal | ls | | | | | | | | | | | | | |
| 3.6 | 0.75 | 1.5 | | 3 | 0.5 | 0.5 | 1.5 | | S00 | В | 3RW30 13-2BB□4 | | 1 | 1 unit | 131 | 0.58 |
| 6.5 | 1.5 | 3 | | 4.8 | 1 | 1 | 3 | | S00 | В | 3RW30 14-2BB□4 | | 1 | 1 unit | | 0.58 |
| 9 | 2.2 | 4 | | 7.8 | 2 | 2 | 5 | | S00 | В | 3RW30 16-2BB□4 | | | 1 unit | | 0.5 |
| 12.5 17.6 | 3 4 | 5.5 7.5 | | 11 17 | 3 3 | 3 3 | 7.5 10 | | S00 S00 | B B | 3RW30 17-2BB□4 3RW30 18-2BB□4 | | | 1 unit 1 unit | | 0.58 0.58 |
| • With scr | ew term | inals | | | | | | | | | | | | | | |
| 25 | 5.5 | 11 | | 23 | 5 | 5 | 15 | | S0 | • | 3RW30 26-1BB□4 | | | 1 unit | | 0.69 |
| 32 38 | 7.5 11 | 15 18.5 | | 29 34 | 7.5 10 | 7.5 10 | 20 25 | | S0 S0 | | 3RW30 27-1BB□4 3RW30 28-1BB□4 | | | 1 unit 1 unit | | 0.69 |
| With spr | | | | 34 | 10 | 10 | 25 | | 30 | | 3NW30 20-10014 | | ' | i uiiit | 131 | 0.0 |
| 25 | 5.5 | 11 | | 23 | 5 | 5 | 15 | | S0 | В | 3RW30 26-2BB□4 | | 1 | 1 unit | 121 | 0.69 |
| 32 | 7.5 | 15 | | 29 | 7.5 | 7.5 | 20 | | S0 | В | 3RW30 27-2BB□4 | | | 1 unit | | 0.69 |
| 38 | 11 | 18.5 | | 34 | 10 | 10 | 25 | | S0 | В | 3RW30 28-2BB□4 | | 1 | 1 unit | 131 | 0.69 |
| With scr | ew or sp | oring-type | e termina | als | | | | | | | | | | | | |
| 45 | 11 | 22 | | 42 | 10 | 15 | 30 | | S2 | | 3RW30 36-□BB□4 | | | 1 unit | | 1.20 |
| 63 72 | 18.5 22 | 30 37 | | 58 62 | 15 20 | 20 20 | 40 40 | | S2 S2 | | 3RW30 37-□BB□4 3RW30 38-□BB□4 | | | 1 unit 1 unit | | 1.20 1.20 |
| • With scr | | | e termina | | | | | | | | | | | | | |
| 80 | 22 | 45 | | 73 | 20 | 25 | 50 | | S3 | • | 3RW30 46-□BB□4 | | 1 | 1 unit | 131 | 1.71 |
| 106 | 30 | 55 | | 98 | 30 | 30 | 75 | | S3 | > | 3RW30 47-□BB□4 | | 1 | 1 unit | 131 | 1.71 |
| Order No | . supple | ment for | r connec | ction types | | | | | | | | | | | | |
| With scrWith spr | | | ls ³⁾ | | | | | | | | 1 2 | | | | | |
| Order No | . supple | ment for | r rated c | ontrol supp | ly volta | ge <i>U</i> s | | | | | | | | | | |
| • 24 V AC | | | | | | | | | | | 0 | | | | | |
| 110 2 | 30 V AC | /DC | | | | | | | | | 1 | | | | | |

• 110 ... 230 V AC/DC

Soft starters for easy starting conditions and high switching frequency, rated operational voltage $U_{\rm e}$ 200 ... 400 V, Rated control supply voltage $U_{\rm s}$ 24 ... 230 V AC/DC

| 3 | 0.55 | 1.1 | | 2.6 | 0.5 | 0.5 | | | 22.5 mm |
|---|------|-----|--|-----|-----|-----|--|--|---------|
|---|------|-----|--|-----|-----|-----|--|--|---------|

- With screw terminals
- With spring-type terminals
- 2) Soft starter with screw terminals: delivery time class } (preferred type).

Selection of the soft starter depends on the rated motor current.

Please observe the notes for the selection of soft starters on

The SIRIUS 3RW30 solid-state soft starters are designed for easy starting conditions. $J_{Load} < 10 \times J_{Motor}$. In the event of deviating conditions or increased switching frequency, it may be necessary to choose a larger device.

Siemens recommends the use of the selection and simulation program Win-Soft Starter. For information about rated currents for ambient temperatures > 40 °C, see "Technical specifications".

3RW30 03-1CB54

3RW30 03-2CB54

3) Main circuit connection: screw terminals.

1 1 unit 131

1 1 unit 131

0.207

0.188

^{*} You can order this quantity or a multiple thereof.

SIRIUS 3RW Soft Starters 3RW30, 3RW40 for Standard Applications

3RW30

| - | | | | | | | | |
|---|---|---|---|---|----------|-----|---|---|
| Α | 0 | ~ | C | C | α | Pi. | 0 | C |
| | | | | | | | | |

| Accessories | | | | | | | | | | | | |
|------------------------|---|---|---------------------------|---------------------|---------------------------------------|-------------|--------------------------------|-----------------|----------------------------|------------------|------------|-----------------------------|
| | Conducto | or cross-se | ction | Tighten- | For motor | DT | Order No. | Price | PU | PS* | PG | Weight |
| | Solid or | | AWG cables, | ing torque | starter protectors Size | | | per PU | | . 0 | . 3 | per PU approx. |
| | mm² | mm ² | AWG | Nm | | | | | | | | kg |
| Three-phase feeder to | | | 71110 | 14111 | | | | | | | | ng |
| 3RV19 25-5AB | 2.5 25 | 4 16 | 12-4 | 4 | S00 (3RW30 1.) S0 (3RW30 2.) | X | 3RV29 25-5AB | | 1 | 1 unit | 101 | 0.043 |
| | For soft si | tarters Size | | breakers | | DT | Order No. | Price per PU | PU (UNIT, SET, M) | PS* | PG | Weight per PU approx. |
| Auxiliary terminals | | | | | | | | | | | | kg |
| Auxiliary terminais | Auvilian | terminals | 2-polo | | | | | | | | | |
| | 3RW30 4 | | , s-pole | | | В | 3RT19 46-4F | | 1 | 1 unit | 101 | 0.035 |
| Covers for soft starte | | . 00 | | | | | 011110 40 41 | | | Tanit | 101 | 0.000 |
| Notes of the second | Additiona | nits require . S2 | tection to | be fitted a | t the box termi | - • | 3RT19 36-4EA2 3RT19 46-4EA2 | | 1 1 | 1 unit 1 unit | 101 101 | 0.020 0.025 |
| and the same | For comp protection | lying with to be if box term equired pe | the phase minal is rer | clearance: moved | bar connections and as touch | | 3RT19 46-4EA1 | | 1 | 1 unit | 101 | 0.040 |
| Link modules to moto | or starter | protecto | rs ¹⁾ | | | | | | | | | |
| Link modules to mote | | rew termin | | | | | | | | | | |
| | 3RW30 1. | | S00 | | | Α | 3RA29 21-1BA00 | | 1 | 1 unit | 101 | 0.001 |
| | 3RW30 2. | | S0 | | | Α | 3RA29 21-1BA00 | | 1 | 1 unit | 101 | 0.001 |
| | 3RW30 36 | | S2 | | | > | 3RA19 31-1AA00 | | 1 | 1 unit | 101 | 0.042 |
| | 3RW30 4 | | S3 | | | • | 3RA19 41-1AA00 | | 1 | 1 unit | 101 | 0.090 |
| | • With sp | ring-type t | erminals | | | | | | | | | |
| | 3RW30 1. | | S00 | | | Α | 3RA29 11-2GA00 | | 1 | 1 unit | 101 | 0.038 |
| | 3RW30 2. | S0 | S0 | | | Α | 3RA29 21-2GA00 | | 1 | 1 unit | 101 | 0.072 |
| Operating instruction | s ²⁾ | | | | | | | | | | | |
| | For soft st | tarters | | | | | | | | | | |
| | 3RW30 1. 3RW30 2 3RW30 3 3RW30 4 | S0 S2 | | | | | 3ZX10 12-0RW30-2DA1 | | | | | |

Can be used in size S0 up to maximum 32 A.
 Can be used in size S00/S0 only for 3RV2 motor starter protectors.
 The operating instructions are included in the scope of supply.

SIRIUS 3RW Soft Starters 3RW30, 3RW40 for Standard Applications

3RW30

| | Version | Functionality Functions | Use | DT | Order No. | Price per PU | PU (UNIT, SET, M) | PS* | PG | Weight per PU approx. |
|--|-------------------------------------|---|---|-------------|-----------------------|-------------------------------|----------------------------|----------|-----|-----------------------------|
| Covers and push-in I | ugs (only for 3F | RW30 03) | | | | | | | | - Ng |
| | | For securing against unauthorized adjustment of setting knobs | For devices with 1 or 2 CO contacts | > | 3RP1 902 | | 1 | 5 units | 101 | 0.004 |
| 3RP1 902 3RP1 903 | Push-in lugs for screw fixing | | For devices with 1 or 2 CO contacts | • | 3RP1 903 | | 1 | 10 units | 101 | 0.002 |
| | | | | | | | | | | |
| | Version | | | DT | Order No. | Price per PU | PU (UNIT, SET, M) | PS* | PG | Weight per PU approx. |
| | | | | | | | | | | kg |
| Operating device for for size S00 and S0 | spring-type terr | ninals | | | | | | | | |
| | | | | | Spring-type terminals | $\stackrel{\infty}{\boxplus}$ | | | | |
| | Screwdrivers Also suitable for t | he TE terminals | | Α | 3RA29 08-1A | | 1 | 1 unit | 101 | 0.045 |

3RW30, 3RW40 for Standard Applications

3RW30

More information

Application examples for normal starting (Class 10)

Normal starting Class 10 (up to 20 s with 300 % $I_{\rm n\ motor}$). The soft starter rating can be selected to be as high as the rating of the motor used

| Application | | Conveyor belt | Roller conveyor | Compressor | Small fans ¹⁾ | Pump | Hydraulic pump |
|---|---|---------------|-----------------|------------|--------------------------|------|----------------|
| Starting parameters | | | | | | | |
| Voltage ramp and current limiting | | | | | | | |
| Starting voltage | % | 70 | 60 | 50 | 40 | 40 | 40 |
| Starting time | S | 10 | 10 | 20 | 20 | 10 | 10 |

¹⁾ The mass inertia of the fan is <10 times the mass inertia of the motor

These tables present sample set values and device sizes. They are intended only for the purposes of information and are not binding. The set values depend on the application in question and must be optimized during commissioning.

The soft starter dimensions should be checked where necessary with the Win-Soft Starter software or with the help of Technical Assistance.

Configuration

The 3RW solid-state motor controllers are designed for easy starting conditions. In the event of deviating conditions or increased switching frequency, it may be necessary to choose a larger device. For accurate dimensioning, use the Win-Soft Starter selection and simulation program

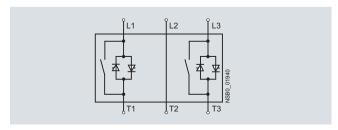
If necessary, an overload relay for heavy starting must be selected where long starting times are involved. PTC sensors are

No capacitive elements are permitted in the motor feeder between the SIRIUS 3RW soft starter and the motor (e.g. no reactive-power compensation equipment). In addition, neither static systems for reactive-power compensation nor dynamic PFC (Power Factor Correction) must be operated in parallel during starting and ramp-down of the soft starter. This is important to prevent faults arising on the compensation equipment and/or the

All elements of the main circuit (such as fuses, controls and overload relays) should be dimensioned for direct starting, following the local short-circuit conditions. Fuses, controls and overload relays must be ordered separately. Please observe the maximum switching frequencies specified in the technical specifications

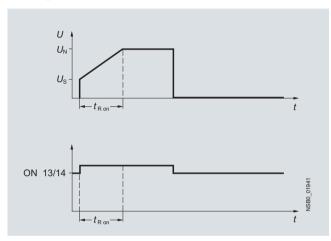
When induction motors are switched on, voltage drops occur as a rule on starters of all types (direct starters, wye-delta starters, soft starters). The infeed transformer must always be dimensioned such that the voltage dip when starting the motor remains within the permissible tolerance. If the infeed transformer is dimensioned with only a small margin, it is best for the control voltage to be supplied from a separate circuit (independently of the main voltage) in order to avoid the potential switching off of the soft starter

Power electronics schematic circuit diagram



A bypass contact system is already integrated in the 3RW30 soft starter and therefore does not have to be ordered separately.

Status graphs



Manual for SIRIUS 3RW30/40

Besides containing all important information on configuring. commissioning and servicing, the manual also contains example circuits and the technical specifications for all devices.

Win-Soft Starter selection and simulation program

With this software, you can simulate and select all Siemens soft starters, taking into account various parameters such as mains properties, motor and load data, and special application requirements.

The software is a valuable tool, which makes complicated, lengthy manual calculations for determining the required soft starters superfluous.

The Win-Soft Starter selection and simulation program can be downloaded from:

www.siemens.com/softstarter > Software

You can find more information about soft starters on the Internet likewise at:

www.siemens.com/softstarter

Training course for SIRIUS soft starters (SD-SIRIUSO)

Siemens offers a 2-day training course on the SIRIUS solid-state soft starters to keep customers and own personnel up-to-date on configuring, commissioning and maintenance issues.

Please direct enquiries and applications to:

Training Center for Automation and Industrial Solution Gleiwitzer Strasse 555 D-90475 Nürnberg Telephone: +49 911 895 3202

Telefax: +49 911 895 3275

E-mail: ingeborg.hoier@siemens.com www.siemens.com/sitrain-cd

3RW30, 3RW40 for Standard Applications

3RW40

Overview

SIRIUS 3RW40 soft starters have all the same advantages as the 3RW30 soft starters.

The SIRIUS 3RW40 soft starters are characterized above all by their small space requirements. Integrated bypass contacts mean that no power loss has to be taken into the bargain at the power semiconductors (thyristors) after the motor has started up. This cuts down on heat losses, enabling a more compact design and making external bypass circuits superfluous.

At the same time this soft starter comes with additional integrated functions such as adjustable current limiting, motor overload and intrinsic device protection, and optional thermistor motor protection. The higher the motor rating, the more important these functions because they make it unnecessary to purchase and install protection equipment such as overload relays.

Internal intrinsic device protection prevents the thermal overloading of the thyristors and the power section defects this can cause. As an option the thyristors can also be protected by semiconductor fuses from short-circuiting.

Thanks to integrated status monitoring and fault monitoring, this compact soft starter offers many different diagnostics options. Up to four LEDs and relay outputs permit differentiated monitoring and diagnostics of the operating mechanism by indicating the operating state as well as for example mains or phase failure, missing load, non-permissible tripping time/class setting, thermal overloading or device faults.

Soft starters rated up to 250 kW (at 400 V) for standard applications in three-phase networks are available. Extremely small sizes, low power losses and simple start-up are just three of the many advantages of the SIRIUS 3RW40 soft starters.

"Increased safety" type of protection EEx e according to ATEX directive 94/9/EC

The 3RW40 soft starter sizes S0 to S12 are suitable for the starting of explosion-proof motors with "increased safety" type of protection EEx e.

See "Appendix" -> "Standards and approvals"-> "Type overview of approved devices for potentially explosive areas (ATEX explosion protection)".

Functionality

The space required by the compact SIRIUS 3RW40 soft starter is often only about one third of that required by a contactor assembly for wye-delta starting of comparable rating. This not only saves space in the control cabinet and on the standard mounting rail but also does away completely with the wiring work needed for wye-delta starters. This is notable in particular for higher motor ratings which are only rarely available as fully wired solutions.

At the same time the number of cables from the starter to the motor is reduced from six to three. Compact dimensions, short start-up times, easy wiring and fast commissioning make themselves felt as clear-cut cost advantages.

The <u>bypass contacts</u> of these soft starters are protected during operation by an integrated solid-state arc quenching system. This prevents damage to the bypass contacts in the event of a fault, e.g.brief disconnection of the control voltage, mechanical shocks or life-related component defects on the coil operating mechanism or main contact spring.

The starting current of particularly powerful operating mechanisms can place an unjustifiable load on the local supply system. Soft starters reduce this starting current by means of their voltage ramp. Thanks to the adjustable current limiting, the SIRIUS 3RW40 soft starter takes even more pressure off the supply system. It leaves the set start ramp during the ramp-up – the ramp gradient is fixed by the starting voltage and the ramp time – as soon as the selected current limit is reached. From this moment the voltage of the soft starter is controlled so that the current supplied to the motor remains constant. This process is ended either by completion of the motor ramp-up or by tripping by the intrin-

sic device protection or the motor overload protection. As the result of this function the actual motor ramp-up can well take longer than the ramp time selected on the soft starter.

Thanks to the integrated motor overload protection according to IEC 60947-4-2 there is no need of an additional overload relay on the new soft starters. The rated motor current, the setting of the overload tripping time (Class times) and the reset of the motor overload protection function can be adjusted easily and quickly. Using a 4-step rotary potentiometer it is possible to set different overload tripping times on the soft starter. In addition to Class 10, 15 and 20 it is also possible to switch off the motor overload protection if a different motor management control device is to be used for this function, e.g. with connection to PROFIBUS.

Device versions with thermistor motor protection evaluation are available up to a rating of 55 kW (at 400 V). A "Thermoclick" measuring probe can be connected directly, as can a PTC of type A. Thermal overloading of the motor, open-circuits and short-circuits in the sensor circuit all result in the direct disconnection of the soft starter. And if ever the soft starter trips, various reset options are available the same as with intrinsic device protection and motor load protection: manually with the reset button, automatically or remotely through brief disconnection of the control voltage.

The new series of devices comes with the "polarity balancing" control method, which is designed to prevent direct current components in two-phase controlled soft starters. On two-phase controlled soft starters the current resulting from superimposition of the two controlled phases flows in the uncontrolled phase. This results for physical reasons in an asymmetric distribution of the three phase currents during the motor ramp-up. This phenomenon cannot be influenced, but in most applications it is non-critical.

Controlling the power semiconductors results not only in this asymmetry, however, but also in the previously mentioned direct current components which can cause severe noise generation on the motor at starting voltages of less than 50 %.

The control method used for these soft starters eliminates these direct current components during the ramp-up phase and prevents the braking torque which they can cause. It creates a motor ramp-up that is uniform in speed, torque and current rise, thus permitting a particularly gentle, two-phase starting of the motors. At the same time the acoustic quality of the starting operation comes close to the quality of a three-phase controlled soft starter. This is made possible by the on-going dynamic harmonizing and balancing of current half-waves of different polarity during the motor ramp-up. Hence the name "polarity balancing".

Application

The SIRIUS 3RW40 solid-state soft starters are used for the soft starting and stopping of three-phase asynchronous motors.

Due to two-phase control, the current is kept at minimum values in all three phases throughout the entire starting time and disturbing direct current components are eliminated in addition. This not only enables the two-phase starting of motors up to 250 kW (at 400 V) but also avoids the current and torque peaks which occur e. g. with wye-delta starters.

Application areas

See "Selection aid for soft starters" on Page 4/7.

3RW30, 3RW40 for Standard Applications

3RW40

Selection and ordering data

SIRIUS 3RW40 for normal starting (CLASS 10)







3RW40 38-1BB14



3RW40 47-1RR14

| | | 3RW40 | 28-1BB | 14 | | | 3 | RW40 3 | 38-1BB14 | 4 | | | 3RW | 40 47- | 1BB14 |
|--------------------------------------|------------------------|-------------------------|-----------------------------|--------------------------------------|---------------------|---------------------|-----------------------|----------------------|--------------------------|------------------|--|----------------------|--------------------------------------|--------------------------|----------------------------------|
| Ambient to | emperati | ure 40 °C | | Ambient t | empera | ture 50 | °C | | Size | DT | Normal starting (CLASS 10) | PU | PS* | PG | Weight |
| Rated operational current $I_e^{1)}$ | Rated p | ower of informated | opera- | Rated operational current I_e^{-1} | Rated | power of | of induc ed opera | | | | , | (UNIT, SET, M) | | | per PU approx. |
| | 230 V | 400 V | 500 V | | 200 V | 230 V | 460 V | 575 V | | | Order No. Price | | | | |
| Α | kW | kW | kW | А | hp | hp | hp | hp | | | per PU | | | | kg |
| Rated o | peratio | nal volta | age <i>U</i> _e 2 | 200 480 | (V ²) | | | | | | | | | | |
| With scr | ew termi | nals | | | | | | | | | | | | | |
| 12.5 25 32 38 | 3 5.5 7.5 11 | 5.5 11 15 18.5 | | 11 23 29 34 | 3 5 7.5 10 | 3 5 7.5 10 | 7.5 15 20 25 | | S0 S0 S0 S0 | A A A | 3RW40 24-1BB□4 3RW40 26-1BB□4 3RW40 27-1BB□4 3RW40 28-1BB□4 | 1 1 1 1 | 1 unit 1 unit 1 unit 1 unit | 131 131 131 131 | 0.770 0.770 0.770 0.770 |
| • With spr | ring-type | terminals | 3 | · | | | | | | | | | | | |
| 12.5 25 32 38 | 3 5.5 7.5 11 | 5.5 11 15 18.5 | | 11 23 29 34 | 3 5 7.5 10 | 3 5 7.5 10 | 7.5 15 20 25 | | \$0 \$0 \$0 \$0 | B B B | 3RW40 24-2BB□4 3RW40 26-2BB□4 3RW40 27-2BB□4 3RW40 28-2BB□4 | 1 1 1 1 | 1 unit 1 unit 1 unit 1 unit | 131 131 131 131 | 0.770 0.770 0.770 0.770 |
| With scr | ew or sp | ring-type | terminals | | | | | | | | | | | | |
| 45 63 72 | 11 18.5 22 | 22 30 37 | | 42 58 62 | 10 15 20 | 15 20 20 | 30 40 40 | | S2 S2 S2 | > > | 3RW40 36-□BB□4 3RW40 37-□BB□4 3RW40 38-□BB□4 | 1 1 1 | 1 unit 1 unit 1 unit | 131 131 131 | 1.350 1.350 1.350 |
| With scr | | ring-type | terminals | | | | | | | | | | | | |
| 80 106 | 22 30 | 45 55 | | 73 98 | 20 30 | 25 30 | 50 75 | | S3 S3 | > | 3RW40 46-□BB□4 3RW40 47-□BB□4 | 1 1 | 1 unit 1 unit | 131 131 | 1.900 1.900 |
| Rated o | peratio | nal volta | age <i>U</i> _e 4 | 100 600 | V | | | | | | | | | | |
| With scr | ew termi | | | i | | | | | | | | | | | |
| 12.5 25 32 38 | | 5.5 11 15 18.5 | 7.5 15 18.5 22 | 11 23 29 34 | | | 7.5 15 20 25 | 10 20 25 30 | S0 S0 S0 S0 | B B B | 3RW40 24-1BB□5 3RW40 26-1BB□5 3RW40 27-1BB□5 3RW40 28-1BB□5 | 1 1 1 1 | 1 unit 1 unit 1 unit 1 unit | 131 131 131 131 | 0.770 0.770 0.770 0.770 |
| With spr | ring-type | | | i | | | | | | | | | | | |
| 12.5 25 32 38 | | 5.5 11 15 18.5 | 7.5 15 18.5 22 | 11 23 29 34 | | | 7.5 15 20 25 | 10 20 25 30 | S0 S0 S0 S0 | B B B | 3RW40 24-2BB□5 3RW40 26-2BB□5 3RW40 27-2BB□5 3RW40 28-2BB□5 | 1 1 1 1 | 1 unit 1 unit 1 unit 1 unit | 131 131 131 131 | 0.770 0.770 0.770 0.770 |
| With scr | ew or sp | ring-type | terminals | | | | | | | | | | | | |
| 45 63 72 | | 22 30 37 | 30 37 45 | 42 58 62 | | | 30 40 40 | 40 50 60 | S2 S2 S2 | B B B | 3RW40 36-□BB□5 3RW40 37-□BB□5 3RW40 38-□BB□5 | 1 1 1 | 1 unit 1 unit 1 unit | 131 131 131 | 1.350 1.350 1.350 |
| • With scr | ew or sp | ring-type | terminals | | | | | | | | | | | | |
| 80 106 | | 45 55 | 55 75 | 73 98 | | | 50 75 | 60 75 | S3 S3 | B B | 3RW40 46-□BB□5 3RW40 47-□BB□5 | 1 1 | 1 unit 1 unit | 131 131 | 1.900 1.900 |
| • With scr • With spr | rew termi ring-type | nals terminals | 33) | | 14 | 11 | | | | | 1 2 | | | | |
| | | ment for | rated cor | ntrol suppl | y volta | ge U _s | | | | | | | | | |
| • 24 V AC • 110 2 | | /DC | | | | | | | | | 0 1 | | | | |

1) Stand-alone installation without auxiliary fan.

Note:

Selection of the soft starter depends on the rated motor current.

Please observe the notes for the selection of soft starters on Page 4/7.

The SIRIUS 3RW40 solid-state soft starters are designed for easy starting conditions. $J_{\rm Load} < 10 \times J_{\rm Motor}$. In the event of deviating conditions or increased switching frequency, it may be

necessary to choose a larger device. Siemens recommends the use of the selection and simulation program Win-Soft Starter. For information about rated currents for ambient temperatures > 40 °C, see "Technical specifications".

3) Main circuit connection: screw terminals.

²⁾ Soft starter with screw terminals: delivery time class ▶ (preferred type).

3RW40 38-1TB04

SIRIUS 3RW Soft Starters

3RW30, 3RW40 for Standard Applications

3RW40



3RW40 28-1TB04





3RW40 47-1TB04

| Ambient to | emperati | ure 40 °C | | Ambient | tempera | ture 50 | °C | | Size | DT | Normal starting (CLASS 10 | | PS* | PG | Weight |
|--------------------------------------|-----------------------|--|-------------------------|--------------------------------------|---------------------|--------------------------------------|-----------------------|----------------------|----------------------|--------------|--|----------------------|--------------------------------------|--------------------------|----------------------------------|
| Rated operational current $I_e^{1)}$ | motors | power of in for rated oltage $U_{\rm e}$ | opera- | Rated operational current $I_e^{1)}$ | motors | power of for rate e <i>U</i> e | | | | | | (UNIT, SET, M) | | | per PU approx. |
| | 230 V | 400 V | 500 V | | | 230 V | | 575 V | | | Order No. Pric | | | | |
| A | kW | kW | kW | Α 40 | hp | hp | hp | hp | | | perr | J | | | kg |
| Rated o with the rated co | ermisto | r motor | protecti | on, | | | | | | | | | | | |
| • With scr | ew termi | inals | | | | | | | | | | | | | |
| 12.5 25 32 38 | 3 5.5 7.5 11 | 5.5 11 15 18.5 | | 11 23 29 34 | 3 5 7.5 10 | 3 5 7.5 10 | 7.5 15 20 25 | | S0 S0 S0 S0 | * * * | 3RW40 24-1TB04 3RW40 26-1TB04 3RW40 27-1TB04 3RW40 28-1TB04 | 1 1 1 1 | 1 unit 1 unit 1 unit 1 unit | 131 131 131 131 | 0.770 0.770 0.770 0.770 |
| • With spr | | | | 1 | | | | | | _ | | | | | . ==. |
| 12.5 25 32 38 | 3 5.5 7.5 11 | 5.5 11 15 18.5 | | 11 23 29 34 | 3 5 7.5 10 | 3 5 7.5 10 | 7.5 15 20 25 | | S0 S0 S0 S0 | B B B | 3RW40 24-2TB04 3RW40 26-2TB04 3RW40 27-2TB04 3RW40 28-2TB04 | 1 1 1 1 | 1 unit 1 unit 1 unit 1 unit | 131 131 131 131 | 0.770 0.770 0.770 0.770 |
| With scr | ew or sp | ring-type | terminals | | | | | | | | | | | | |
| 45 63 72 | 11 18.5 22 | 22 30 37 | | 42 58 62 | 10 15 20 | 15 20 20 | 30 40 40 | | S2 S2 S2 | A | 3RW40 36-□TB04 3RW40 37-□TB04 3RW40 38-□TB04 | 1 1 1 | 1 unit 1 unit 1 unit | 131 131 131 | 1.350 1.350 1.350 |
| • With scr | rew or sp | ring-type | terminals | | | | | | | | | | | | |
| 80 106 | 22 30 | 45 55 | | 73 98 | 20 30 | 25 30 | 50 75 | | S3 S3 | > | 3RW40 46-□TB04 3RW40 47-□TB04 | 1 1 | | 131 131 | 1.900 1.900 |
| Rated o with the rated co | rmisto ontrol s | r motor upply v | protecti | on, | | | | | | | | | | | |
| With scr | ew termi | | | i | | | | | | | | | | | |
| 12.5 25 32 38 | | 5.5 11 15 18.5 | 7.5 15 18.5 22 | 11 23 29 34 | | | 7.5 15 20 25 | 10 20 25 30 | S0 S0 S0 S0 | B B B | 3RW40 24-1TB05 3RW40 26-1TB05 3RW40 27-1TB05 3RW40 28-1TB05 | 1 1 1 1 | 1 unit 1 unit 1 unit 1 unit | 131 131 131 131 | 0.770 0.770 0.770 0.770 |
| With spr | ring-type | terminals | 3 | | | | | | | | | | | | |
| 12.5 25 32 38 | | 5.5 11 15 18.5 | 7.5 15 18.5 22 | 11 23 29 34 | | | 7.5 15 20 25 | 10 20 25 30 | S0 S0 S0 S0 | B B B | 3RW40 24-2TB05 3RW40 26-2TB05 3RW40 27-2TB05 3RW40 28-2TB05 | 1 1 1 1 | 1 unit 1 unit 1 unit 1 unit | 131 131 131 131 | 0.770 0.770 0.770 0.770 |
| With scr | rew or sp | | | | | | | | | | | | | | |
| 45 63 72 | | 22 30 37 | 30 37 45 | 42 58 62 | | | 30 40 40 | 40 50 60 | S2 S2 S2 | B B B | 3RW40 36-□TB05 3RW40 37-□TB05 3RW40 38-□TB05 | 1 1 1 | 1 unit 1 unit 1 unit | 131 131 131 | 1.350 1.350 1.350 |
| With scr | ew or sp | ring-type | terminals | | | | | | | | | | | - | |
| 80 106 Order No | | 45 55 | 55 75 | 73 98 | | | 50 75 | 60 75 | S3 S3 | B B | 3RW40 46-□TB05 3RW40 47-□TB05 | 1 | 1 unit 1 unit | 131 131 | 1.900 1.900 |

Order No. supplement for connection types

- With screw terminals
- With spring-type terminals³⁾ 1) Stand-alone installation without auxiliary fan.

Note:

Selection of the soft starter depends on the rated motor current.

Please observe the notes for the selection of soft starters on Page 4/7.

The SIRIUS 3RW40 solid-state soft starters are designed for easy starting conditions. $J_{Load} < 10 \text{ x } J_{Motor}$. In the event of deviating conditions or increased switching frequency, it may be necessary to choose a larger device. Siemens recommends the

use of the selection and simulation program Win-Soft Starter. For information about rated currents for ambient temperatures > 40 °C, see "Technical specifications".

3) Main circuit connection: screw terminals.

²⁾ Soft starter with screw terminals: delivery time class ▶ (preferred type).

^{*} You can order this quantity or a multiple thereof.

3RW30, 3RW40 for Standard Applications

3RW40





3RW40 76-6BB44

| Ambient t | Ambient temperature 40 °C Rated Rated power of induction | | | | | | | | Size | DT | Normal starting (CL/ | ASS 10) | PU | PS* | PG | Weight |
|--------------------------------------|--|------------|-----------------------------|--------------------------------------|-------------------|--|------------|------------|------|--------|----------------------------------|---------|----------------------|------------------|------------|-------------------|
| Rated operational current I_e^{-1} | motors | for rated | opera- | Rated operational current I_e^{-1} | motors | power of for rate of the second secon | | | | | | | (UNIT, SET, M) | | | per PU approx. |
| | 230 V | 400 V | 500 V | | 200 V | 230 V | 460 V | 575 V | | | Order No. | Price | | | | |
| Α | kW | kW | kW | Α | hp | hp | hp | hp | | | | per PU | | | | kg |
| Rated o | peratio | nal volt | age <i>U</i> _e 2 | 200 460 | (V ²) | | | | | | | | | | | |
| • With sc | rew or sp | ring-type | terminals | 3 | | | | | | | | | | | | |
| 134 | 37 | 75 | | 117 | 30 | 40 | 75 | | S6 | В | 3RW40 55-□BB□4 | | 1 | 1 unit | 131 | 4.900 |
| 162 | 45 | 90 | | 145 | 40 | 50 | 100 | | | В | 3RW40 56-□BB□4 | | 1 | 1 unit | 131 | 6.900 |
| With sc | rew or sp | ring-type | terminals | 8 | | | | | | | | | | | | |
| 230 | 75 | 132 | | 205 | 60 | 75 | 150 | | S12 | В | 3RW40 73-□BB□4 | | 1 | 1 unit | 131 | 8.900 |
| 280 | 90 | 160 | | 248 | 75 | 100 | 200 | | | В | 3RW40 74-□BB□4 | | 1 | 1 unit | 131 | 8.900 |
| 356 | 110 132 | 200 250 | | 315 385 | 100 125 | 125 150 | 250 300 | | | B B | 3RW40 75-□BB□4 3RW40 76-□BB□4 | | 1 | 1 unit 1 unit | 131 | 8.900 |
| 432 | | | | | | 150 | 300 | | | ь | 3RW40 /0-LIBBLI4 | | 1 | 1 unit | 131 | 8.900 |
| | | | | 100 600 |) V = / | | | | | | | | | | | |
| With sc | rew or sp | 0 , . | | 1 | | | | | | | | | | | | |
| 134 162 | | 75 90 | 90 110 | 117 145 | | | 75 100 | 100 150 | S6 | B B | 3RW40 55-□BB□5 3RW40 56-□BB□5 | | 1 | 1 unit 1 unit | 131 131 | 4.900 6.900 |
| | | | | | | | 100 | 150 | | ט | 3HW40 30-11DD113 | | 1 | i ullit | 101 | 0.900 |
| • With sc | rew or sp | | | 1 | | | 450 | | | _ | | | | | | 0.05- |
| 230 280 | | 132 160 | 160 200 | 205 248 | | | 150 200 | 200 250 | S12 | B B | 3RW40 73-□BB□5 3RW40 74-□BB□5 | | 1 | 1 unit 1 unit | 131 131 | 8.900 8.900 |
| 356 | | | 250 250 | 315 | | | | 300 | | | 3RW40 74-□BB□5 | | | 1 unit | | 8.900 |
| 356 432 | | 200 250 | 250 315 | 385 | | | 250 300 | 300 400 | | B B | 3RW40 75-□BB□5 | | | 1 unit 1 unit | 131 131 | 8.900 |

Order No. supplement for connection types⁴⁾

- With spring-type terminals
- With screw terminals

Order No. supplement for the rated control supply voltage $U_{\rm s}^{\,5)}$

- 115 V AC
- 230 V AC
- 1) Stand-alone installation.
- 2) Soft starter with screw terminals: delivery time class ► (preferred type).
- 3) Soft starter with screw terminals: delivery time class A.
- 4) Main circuit connection: busbar connection.
- 5) Control by way of the internal 24 V DC supply and direct control by means of PLC possible.

Note:

Selection of the soft starter depends on the rated motor current.

Please observe the notes for the selection of soft starters on Page 4/7.

The SIRIUS 3RW40 solid-state soft starters are designed for easy starting conditions. $J_{\rm Load} < 10~{\rm x}~{\rm J}_{\rm Motor}$. In the event of deviating conditions or increased switching frequency, it may be necessary to choose a larger device. Siemens recommends the use of the selection and simulation program Win-Soft Starter. For information about rated currents for ambient temperatures $> 40~{\rm ^{\circ}C}$, see "Technical specifications".

2 6

3RW30, 3RW40 for Standard Applications

3RW40

SIRIUS 3RW40 for heavy starting (CLASS 20)













| 3RW40 2 | 8-1BB1 |
|---------|--------|
|---------|--------|

14 3RW40 28-1TB04

3RW40 38-1BB14

3RW40 38-1TB04

3RW40 47-1BB14

3RW40 47-1TB04

| Ambient t | temperati | ure 40 °C | | Ambient t | empera | ture 50 ' | °C | | Size | DT | Heavy starting (CLAS | SS 20) | PU | PS* | PG | Weight |
|--------------------------------------|-----------|-------------------------|-----------------------------|--------------------------------------|-------------------|-----------|-------------------|-------|------|----|----------------------|----------|----------------------|-----|-----|-------------------|
| Rated operational current I_e^{-1} | Rated p | oower of i for rated | nduction opera- | Rated operational current $I_e^{1)}$ | Rated | power of | of inducted opera | | 3.20 | 21 | (02) | , | (UNIT, SET, M) | . 0 | . 3 | per PU approx. |
| | 230 V | 400 V | 500 V | | 200 V | 230 V | 460 V | 575 V | | | Order No. | Price | | | | |
| Α | kW | kW | kW | Α | hp | hp | hp | hp | | | | per PU | | | | kg |
| Rated o | peratio | nal volt | age <i>U</i> _e 2 | 200 480 | (V ²) | | | | | | | | | | | |
| With sci | rew or sp | ring-type | terminals | | | | | | | | | | For DT e | | | ı |
| 12.5 | 3 | 5.5 | | 11 | 3 | 3 | 7.5 | | S0 | | 3RW40 26-□□B□4 | | correspo | | | |
| 25 | 5.5 | 11 | | 23 | 5 | 5 | 15 | | S0 | | 3RW40 27-□□B□4 | | for norm | | | data |
| 32 | 7.5 | 15 | | 29 | 7.5 | 7.5 | 20 | | S2 | | 3RW40 36-□□B□4 | | | | | |
| 38 | 11 | 18.5 | | 34 | 10 | 10 | 25 | | S2 | | 3RW40 37-□□B□4 | | | | | |
| 45 | 11 | 22 | | 42 | 10 | 15 | 30 | | S2 | | 3RW40 37-□□B□4 | | | | | |
| 63 | 18.5 | 30 | | 58 | 15 | 20 | 40 | | S3 | | 3RW40 47-□□B□4 | | | | | |
| 72 | 22 | 37 | | 62 | 20 | 20 | 40 | | S3 | | 3RW40 47-□□B□4 | | | | | |
| Rated o | peratio | nal volt | age <i>U</i> _e 4 | l <mark>00 6</mark> 00 | V | | | | | | | | | | | |
| With sci | rew or sp | ring-type | terminals | ; | | | | | | | | | | | | |
| 12.5 | | 5.5 | 7.5 | 11 | - | | 7.5 | 10 | S0 | | 3RW40 26-□□B□5 | | | | | |
| 25 | | 11 | 15 | 23 | | | 15 | 20 | S0 | | 3RW40 27-□□B□5 | | | | | |
| 32 | | 15 | 18.5 | 29 | | | 20 | 25 | S2 | | 3RW40 36-□□B□5 | | | | | |
| 38 | | 18.5 | 22 | 34 | | | 25 | 30 | S2 | | 3RW40 37-□□B□5 | | | | | |
| 45 | | 22 | 30 | 42 | | | 30 | 40 | S2 | | 3RW40 37-□□B□5 | | | | | |
| 63 | | 30 | 37 | 58 | - | | 40 | 50 | S3 | | 3RW40 47-□□B□5 | | | | | |
| 72 | | 37 | 45 | 62 | | | 40 | 60 | S3 | | 3RW40 47-□□B□5 | | | | | |
| Order No | . supple | ment for | connecti | on types | | | | | | | | | | | | |

- With screw terminals
- With spring-type terminals³⁾

Order No. supplement for thermistor motor protection

- \bullet Thermistor motor protection only with rated control supply voltage $U_{\rm S}$ 24 V AC/DC

Order No. supplement for rated control supply voltage $U_{\rm s}$

- 24 V AC/DC
- 110 ... 230 V AC/DC
- 1) Stand-alone installation without auxiliary fan.
- ²⁾ Soft starter with screw terminals: delivery time class ▶ (preferred type).

Selection of the soft starter depends on the rated motor current.

Please observe the notes for the selection of soft starters on

The SIRIUS 3RW40 solid-state soft starters are designed for easy starting conditions. $J_{Load} < 10 \times J_{Motor}$. In the event of deviating conditions or increased switching frequency, it may be necessary to choose a larger device. Siemens recommends the use of the selection and simulation program Win-Soft Starter. For information about rated currents for ambient temperatures > 40 °C, see "Technical specifications".

³⁾ Main circuit connection: screw terminals.

^{*} You can order this quantity or a multiple thereof.

3RW30, 3RW40 for Standard Applications

3RW40

Amb

Rate

opera

tiona

rent i





3RW40 76-6BB44

S6

| Mineral . | | -: | | |
|-----------|----------|------|-----|---|
| - | | 0 | | |
| | 0 10 | 60 | 1 | J |
| imi | 11111111 | mi | | |
| 3RV | /40 5 | 6-6B | B44 | |
| | | | | |

kW

| ient te | emperatu | re 40 °C | | Ī |
|--|-------------------------------------|------------|-------|---|
| d a- I cur- I _e 1) | Rated po motors for tional vo | or rated o | | |
| e' | 000 1/ | 400 \/ | 500 W | |

Ambient temperature 50 °C tional current $I_e^{1)}$

460 V²⁾

20

25

Rated power of induction motors for rated operational voltage U_e 200 V 230 V 460 V 575 V hp hp

50

DT Heavy starting (CLASS 20) Order No.

3RW40 55-□BB□4

3RW40 55-□BB□4

3RW40 56-□BB□4

3RW40 73-□BB□4

3RW40 74-□BB□4

3RW40 75-□BB□4

3RW40 76-□BB□4

(UNIT, SET, M)

Weight per PU approx.

Price per PU

kg

| Rated o | peration | ıal volta | ige <i>U_e 2</i> | 00 4 |
|-------------|-----------|------------|----------------------------|------|
| • With scre | ew or spr | ing-type t | terminals | |
| 80 | 22 | 45 | | 73 |
| 106 | 30 | 55 | | 98 |
| 134 | 37 | 75 | | 117 |

kW

kW

| 106 | 30 | 55 | 98 | 25 | 30 | 60 | S6 |
|-----|-----|-----|-----------------------|-----|-----|-----|---------|
| 134 | 37 | 75 | 117 | 30 | 40 | 75 | S6 |
| 162 | 45 | 90 | 145 | 40 | 50 | 100 | S12 |
| 230 | 75 | | 205 248 315 | 60 | 75 | 150 | S12 |
| 280 | 90 | 160 | 248 | 75 | 100 | 200 | S12 |
| 356 | 110 | 200 | 315 | 100 | 125 | 250 | S12 |

For DT etc. for the corresponding Order No. see Selection and ordering data for normal starting

Rated operational voltage U_e 400 ... 600

| • With s | screw or | | | | | | | | |
|----------|----------|-----|-----|-----|------|-----|-----|-----|----------------|
| 80 | | 45 | 55 | 73 | | 50 | 60 | S6 | 3RW40 55-□BB□5 |
| 106 | | 55 | 75 | 98 | | 60 | 75 | S6 | 3RW40 55-□BB□5 |
| 134 | | 75 | 90 | 117 | | 75 | 100 | S6 | 3RW40 56-□BB□5 |
| 162 | | 90 | 110 | 145 | | 100 | 150 | S12 | 3RW40 73-□BB□5 |
| 230 | | 132 | 160 | 205 | | 150 | 200 | S12 | 3RW40 74-□BB□5 |
| 280 | | 160 | 200 | 248 | | 200 | 250 | S12 | 3RW40 75-□BB□5 |
| 356 | | 200 | 250 | 315 | | 250 | 300 | S12 | 3RW40 76-□BB□5 |

Order No. supplement for connection types⁴⁾

- With spring-type terminals
- With screw terminals

Order No. supplement for the rated control supply voltage $U_s^{(5)}$

- 115 V AC
- 230 V AC
- 1) Stand-alone installation.
- ²⁾ Soft starter with screw terminals: delivery time class ▶ (preferred type).
- 3) Soft starter with screw terminals: delivery time class A.
- 4) Main circuit connection: busbar connection.
- ⁵⁾ Control by way of the internal 24 V DC supply and direct control by means of PLC possible.

Selection of the soft starter depends on the rated motor current.

Please observe the notes for the selection of soft starters on Page 4/7.

The SIRIUS 3RW40 solid-state soft starters are designed for easy starting conditions. $J_{\rm Load} < 10~{\rm x}~J_{\rm Motor}$. In the event of deviating conditions or increased switching frequency, it may be necessary to choose a larger device. Siemens recommends the use of the selection and simulation program Win-Soft Starter. For information about rated currents for ambient temperatures > 40 °C, see "Technical specifications".

SIRIUS 3RW Soft Starters 3RW30, 3RW40 for Standard Applications

3RW40

Accessories

| Accessories | | | | | | | | | | | |
|------------------------|----------------------|--|---|---------------------------------------|---|-------------|--------------------------------|--------------------------------|------------------|------------|-----------------------------|
| | | r cross-sect | | Tightening | For motor starter | DT | Order No. Pric | | PS* | PG | Weight per PU |
| | Solid or stranded | Finely stranded with end sleeve | AWG cables, solid or stranded | torque | protectors Size | | per P | SET, M) | | | approx. |
| | mm² | mm² | AWG | Nm | | | | | | | kg |
| Three-phase feeder to | erminals | | | | | | | | | | <u>.</u> |
| 3RV19 25-5AB | 2.5 25 | 4 16 | 12-4 | 4 | \$00 (3RW30 1.) \$0 (3RW30 2.) | X | 3RV29 25-5AB | 1 | 1 unit | 101 | 0.043 |
| | | | | | | | | _ | | | |
| | For soft sta Type | arters Size | Version | | | DT | Order No. Pric | e PU J (UNIT, SET, M) | PS* | PG | Weight per PU approx. |
| | | | | | | | | | | | kg |
| Box terminal blocks t | | | | | | | | | | | |
| | | l and ribbo | | . 2 | | | | | | | |
| | 3RW40 5. | S6 | Up to 70Up to 12 | | | > | 3RT19 55-4G 3RT19 56-4G | 1 | 1 unit 1 unit | 101 101 | 0.230 0.260 |
| | 3RW40 7. | S12 | • Up to 24 | _ | | • | 3RT19 66-4G | 1 | 1 unit | 101 | 0.676 |
| Auxiliary terminals | | | | | | | | | | | |
| | Auxiliary | terminals, | 3-pole | | | | | | | | |
| | 3RW40 4. | S3 | | | | В | 3RT19 46-4F | 1 | 1 unit | 101 | 0.035 |
| Covers for soft starte | | | | | | | | | | | |
| | Additional | | | | ox terminals (2 | | | | | | |
| acata / | 3RW40 3. | S2 | | | | • | 3RT19 36-4EA2 | 1 | 1 unit | 101 | 0.020 |
| 9 9 9 | 3RW40 4. 3RW40 5. | S3 S6 | | | | | 3RT19 46-4EA2 3RT19 56-4EA2 | 1 | 1 unit 1 unit | 101 101 | 0.025 0.030 |
| SIEMENS CO. TO | 3RW40 7. | S12 | | | | • | 3RT19 66-4EA2 | i | 1 unit | 101 | 0.040 |
| A ROLL | Terminal of | cover for c | able lugs a | nd busbar co | nnections | | | | | | |
| 2881 | 3RW40 4. | S3 | | ying with the particular as touch pro | | > | 3RT19 46-4EA1 | 1 | 1 unit | 101 | 0.040 |
| and the | 3RW40 5. 3RW40 7. | S6 S12 | terminal is | | | > | 3RT19 56-4EA1 3RT19 66-4EA1 | 1 | 1 unit 1 unit | 101 101 | 0.070 0.130 |

3RW49 00-0PB10

3RW49 00-0PB00



Sealing covers 3RW40 2. to 3RW40 4.

3RW40 5. and **S6**, 3RW40 7. **S12**

1 1 unit

1 1 unit

0.005

0.010

131

131

3RW30, 3RW40 for Standard Applications

3RW40

| | For soft starters Type Size | Version | DT | Order No. | Price per PU | PU (UNIT, SET, M) | PS* | PG | Weight per PU approx. |
|---------------------------------|---|--|--------------|--|-----------------|----------------------------|----------------------------|-------------------|-------------------------|
| Modules for RESET ¹⁾ |) | | | | | | | | kg |
| Wouldes for RESET | Modules for remote Operating range 0.85 power consumption A ON period 0.2 s 4 switching frequency 6 3RW40 5. and S6, 3RW40 7. S12 | 1.1 × U _s , IC 80 VA, DC 70 W, | * * * | 3RU19 00-2AB71 3RU19 00-2AF71 3RU19 00-2AM71 | | 1 1 1 | 1 unit 1 unit 1 unit | 101 101 101 | 0.066 0.067 0.066 |
| | Mechanical RESET of 3RW40 5. and S6, 3RW40 7. S12 | Resetting plungers, holders and formers Suitable pushbutton IP65, Ø 22 mm, 12 mm stroke Extension plungers | B A | 3RU19 00-1A 3SB30 00-0EA11 3SX13 35 | | 1 1 1 | 1 unit 1 unit 1 unit | 101 102 102 | 0.038 0.020 0.004 |
| | Cable releases with For Ø 6.5 mm holes ir max. control panel thi 3RW40 5. and S6, 3RW40 7. S12 | n the control panel; | * * | 3RU19 00-1B 3RU19 00-1C | | 1 1 | 1 unit 1 unit | 101 101 | 0.063 0.073 |

 $^{^{\}rm 1)}$ Remote RESET already integrated in the 3RW40 2. to 3RW40 4. soft start-

| ers. | | | | | | | | | |
|-----------------------|--|------------------------|----------------------------------|-------------|------------------------|----------------------------|--------|-----|-----------------------------|
| | For soft starter | s Size | Circuit breakers Size | DT | Order No. Price per PU | PU (UNIT, SET, M) | PS* | PG | Weight per PU approx. |
| | | | 7) | | | | | | kg |
| Link modules to moto | | | | | | | | | |
| 11.0 | With screw t | erminal | S | | | | | | |
| M-M M- | 3RW40 2. | S0 | S0 | Α | 3RA29 21-1BA00 | 1 | 1 unit | 101 | 0.001 |
| | 3RW40 36. | S2 | S2 | > | 3RA19 31-1AA00 | 1 | 1 unit | 101 | 0.042 |
| | 3RW40 46., 3RW40 47. | S3 | S3 | > | 3RA19 41-1AA00 | 1 | 1 unit | 101 | 0.090 |
| . 1 | • With spring- | type tei | minals | | | | | | |
| | 3RW40 2. | S0 | S0 | Α | 3RA29 21-2GA00 | 1 | 1 unit | 101 | 0.072 |
| Fans (to increase swi | tching frequence the normal arms of the normal arms | ency a al pos S0 | and for device mountir ition) | ng in | 3RW49 28-8VB00 | 1 | 1 unit | 131 | 0.010 |
| | 3RW40 3., 3RW40 4. | S2, S3 | | > | 3RW49 47-8VB00 | 1 | 1 unit | 131 | 0.020 |
| Operating instruction | | | | | | | | | |
| | For soft starter 3RW40 2. 3RW40 3. 3RW40 4. | S0 S2 S3 | | | 3ZX10 12-0RW40-1AA1 | | | | |
| | 3RW40 5. 3RW40 7. | S6 S12 | | | 3ZX10 12-0RW40-2DA1 | | | | |

Can be used in size S0 up to maximum 32 A.
 Can be used in size S0 only for 3RV2 motor starter protectors.
 The operating instructions are included in the scope of supply.

SIRIUS 3RW Soft Starters 3RW30, 3RW40 for Standard Applications

3RW40

Spare parts

| | For soft starters Type | Size | | DT | Order No. | Price per PU | PU (UNIT, SET, M) | PS* | PG | Weight per PU approx. |
|--|--|--------------|--|-----------------------|--|----------------------------|----------------------------|--------------------------------------|------------|----------------------------------|
| _ | | | | | | | | | | kg |
| Fans | _ | | | | | | | | | |
| | Fans 3RW40 5BB3. 3RW40 5BB4. 3RW40 7BB3. 3RW40 7BB4. | S6 S12 | 115 V AC 230 V AC 115 V AC 230 V AC | > > > | 3RW49 36-8VX30 3RW49 36-8VX40 3RW49 47-8VX30 3RW49 47-8VX40 | | 1 1 1 | 1 unit 1 unit 1 unit 1 unit | 131 131 | 0.300 0.300 0.500 0.500 |
| | Version | | | DT | Order No. | Price per PU | PU (UNIT, SET, M) | PS* | PG | Weight per PU approx. |
| Outside desire for | | ala ala | | | | | | | | kg |
| Operating device for for size S00 and S0 | spring-type tern | ninais | | | | | | | | |
| | | | | | Spring-type terminals | $\overset{\circ}{\square}$ | | | | |
| | Screwdrivers Also suitable for the | ne TE termin | nals | Α | 3RA29 08-1A | | 1 | 1 unit | 101 | 0.045 |

3RW30, 3RW40 for Standard Applications

3RW40

More information

Application examples for normal starting (Class 10)

Normal starting Class 10 (up to 20 s with 350 % $I_{\rm n\ motor}$). The soft starter rating can be selected to be as high as the rating of the motor used.

| Application | | Conveyor belt | Roller conveyor | Compressor | Small fans ¹⁾ | Pump | Hydraulic pump |
|---|--------|--------------------------------|--------------------------------|--------------------------------|--------------------------------|---------------------------------------|---------------------------------------|
| Starting parameters | | | | | | | |
| Voltage ramp and current limiting Starting voltage Starting time Current limit value | % S | 70 10 5 × I _M | 60 10 5 × I _M | 50 10 4 × I _M | 40 10 4 × I _M | 40 10 4 × <i>I</i> _M | 40 10 4 × <i>I</i> _M |
| Ramp-down time | s | 5 | 5 | 0 | 0 | 10 | 0 |

¹⁾ The mass inertia of the fan is <10 times the mass inertia of the motor

Application examples for heavy starting (Class 20)

Heavy starting Class 20 (up to 40 s with 350 % $I_{\rm n\,motor}$). The soft starter has to be selected at least one performance class higher than the motor used.

| Application | | Stirrer | Centrifuge |
|---|--------|--------------------------------------|--------------------------------|
| Starting parameters | | | |
| Voltage ramp and current limiting Starting voltage Starting time Current limit value | % S | 40 20 4× <i>I</i> _M | 40 20 4 × I _M |
| Ramp-down time | | 0 | 0 |

These tables present sample set values and device sizes. They are intended only for the purposes of information and are not binding. The set values depend on the application in question and must be optimized during commissioning. The soft starter dimensions should be checked where necessary

with the Win-Soft Starter software or with the help of Technical Assistance.

3RW30, 3RW40 for Standard Applications

3RW40

Configuration

The 3RW solid-state soft starters are designed for easy starting conditions. In the event of deviating conditions or increased switching frequency, it may be necessary to choose a larger device. For accurate dimensioning, use the Win-Soft Starter selection and simulation program.

Where long starting times are involved, the integrated solid-state overload relay for heavy starting should not be disconnected. PTC sensors are recommended. This also applies for the smooth ramp-down because during the ramp-down time an additional current loading applies in contrast to free ramp-down.

In the case of high switching frequencies in S4 mode, Siemens recommends the use of PTC sensors. For corresponding device versions with integrated thermistor motor protection or separate thermistor evaluation devices see Catalog LV 1.

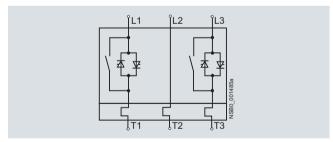
No capacitive elements are permitted in the motor feeder between the SIRIUS 3RW soft starter and the motor (e. g. no reactive-power compensation equipment). In addition, neither static systems for reactive-power compensation nor dynamic PFC (Power Factor Correction) must be operated in parallel during starting and ramp-down of the soft starter. This is important to prevent faults arising on the compensation equipment and/or the soft starter.

All elements of the main circuit (such as fuses and controls) should be dimensioned for direct starting, following the local short-circuit conditions. Fuses, controls and overload relays must be ordered separately. Please observe the maximum switching frequencies specified in the technical specifications.

Note:

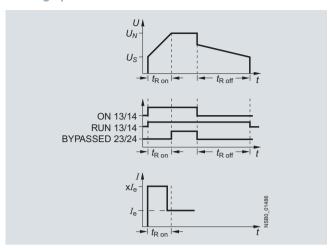
When induction motors are switched on, voltage drops occur as a rule on starters of all types (direct starters, wye-delta starters, soft starters). The infeed transformer must always be dimensioned such that the voltage dip when starting the motor remains within the permissible tolerance. If the infeed transformer is dimensioned with only a small margin, it is best for the control voltage to be supplied from a separate circuit (independently of the main voltage) in order to avoid the potential switching off of the soft starter.

Power electronics schematic circuit diagram



A bypass contact system and solid-state overload relay are already integrated in the 3RW40 soft starter and therefore do not have to be ordered separately.

Status graphs



Manual for SIRIUS 3RW30/40

Besides containing all important information on configuring, commissioning and servicing, the manual also contains example circuits and the technical specifications for all devices.

Win-Soft Starter selection and simulation program

With this software, you can simulate and select all Siemens soft starters, taking into account various parameters such as mains properties, motor and load data, and special application requirements.

The software is a valuable tool, which makes complicated, lengthy manual calculations for determining the required soft starters superfluous.

The Win-Soft Starter selection and simulation program can be downloaded from:

http://www.siemens.com/softstarter > Software

More information can be found on the Internet at: http://www.siemens.com/softstarter

Training course for SIRIUS soft starters (SD-SIRIUSO)

Siemens offers a 2-day training course on the SIRIUS solid-state soft starters to keep customers and own personnel up-to-date on configuring, commissioning and maintenance issues.

Please direct enquiries and applications to:

Training Center for Automation and Industrial Solution Gleiwitzer Strasse 555

D-90475 Nürnberg Telephone: +49 911 895 3202 Telefax: +49 911 895 3275

E-mail: ingeborg.hoier@siemens.com

www.siemens.com/sitrain-cd

3RW44 Soft Starters for High-Feature Applications

3RW44

Overview

In addition to soft starting and soft ramp-down, the solid-state SIRIUS 3RW44 soft starters provide numerous functions for higher-level requirements. They cover a performance range up to 710 kW (at 400 V) in the inline circuit and up to 1200 kW (at 400 V) in the inside-delta circuit.

The SIRIUS 3RW44 soft starters are characterized by a compact design for space-saving and clearly arranged control cabinet layouts. For optimized motor starting and stopping the innovative SIRIUS 3RW44 soft starters are an attractive alternative with considerable savings potential compared to applications with a frequency converter. The new torque control and adjustable current limiting enable the High-Feature soft starters to be used in nearly every conceivable task. They guarantee the reliable avoidance of sudden torque applications and current peaks during motor starting and stopping. This creates savings potential when calculating the size of the switchgear and when servicing the machinery installed. Be it for inline circuits or inside-delta circuits – the SIRIUS 3RW44 soft starter offers savings especially in terms of size and equipment costs.

The bypass contacts already integrated in the soft starter bypass the thyristors after a motor ramp-up is detected. This results in a further great reduction in the heat loss occuring during operation of the soft starter at rated value.

Combinations of various starting, operating and ramp-down possibilities ensure an optimum adaptation to the application-specific requirements. Operation and commissioning can be performed with the menu-controlled keypad and a menu-prompted, multi-line graphic display with background lighting. The optimized motor ramp-up and ramp-down can be effected quickly, easily and reliably by means of just a few settings with a previously selected language. Four-key operation and plain-text displays for each menu point guarantee full clarity at every moment of the parameterization and operation.

Applicable standards

- IEC 60947-4-2
- UL/CSA

Functionality

Equipped with modern, ergonomic user prompting the SIRIUS 3RW44 soft starters can be commissioned quickly and easily using a keypad and a menu-prompted, multi-line grafic display with background lighting. The optimized motor ramp-up and ramp-down can be effected quickly, easily and reliably by means of just a few settings with a selectable language. Four-key operation and plain-text displays for each menu point guarantee full clarity at every moment of the parameterization and operation. During operation and when control voltage is applied, the display field continuously presents measured values and operating values as well as warnings and fault messages. An external display and operator module can be connected by means of a connection cable to the soft starter, thus enabling active indications and the like to be read directly from the control cabinet door.

The SIRIUS 3RW44 soft starters are equipped with optimum functionality. An integral bypass contact system reduces the power loss of the soft starter during operation.

This reliably prevents heating of the switchgear environment. The SIRIUS 3RW44 soft starters have internal intrinsic device protection. This prevents thermal overloading of the power section's thyristors, e. g. due to unacceptably high closing operations

Wiring outlay for installing an additional motor overload relay is no longer needed as the SIRIUS 3RW44 soft starters perform this function too. In addition they offer adjustable trip classes and a thermistor motor protection function. As an option the thyristors can also be protected by SITOR semiconductor fuses from short-circuiting so that the soft starter is still functional after a short-circuit (coordination type 2). And even inrush current peaks are reliably avoided thanks to adjustable current limiting.

As a further option the SIRIUS 3RW44 soft starters can be upgraded with a PROFIBUS DP module. Thanks to their communication capability and their programmable control inputs and relay outputs the SIRIUS 3RW44 soft starters can be very easily and quickly integrated in higher-level controllers.

In addition a creep speed function is available for positioning and setting jobs. With this function the motor can be controlled in both directions of rotation with reduced torque and an adjustable, low speed.

On the other hand the SIRIUS 3RW44 soft starters offer a new, combined DC braking function for the fast stopping of driving loads

Highlights

- Soft starting with breakaway pulse, torque control or voltage ramp, adjustable torque or current limiting as well as any combination of these, depending on load type
- Integrated bypass contact system to minimize power loss
- Various setting options for the starting parameters such as starting torque, starting voltage, ramp-up and ramp-down time, and much more in three separate parameter sets
- Start-up detection
- Inside-delta circuit for savings in terms of size and equipment costs
- Various ramp-down modes selectable: free ramp-down, torque-controlled pump ramp-down, combined DC braking
- Solid-state motor overload and intrinsic device protection
- Thermistor motor protection
- Keypad with a menu-prompted, multi-line graphic display with background lighting
- Interface for communication with the PC for more accurate setting of the parameters as well as for control and monitoring
- · Simple adaptation to the motor feeder
- Simple mounting and commissioning
- Display of operating states and fault messages
- Connection to PROFIBUS with optional PROFIBUS DP module
- External display and operator module
- Mains voltages from 200 to 690 V, 50 to 60 Hz
- Can be used up to 60 °C (derating from 40 °C).

Soft Starter ES parameterization software

Soft Starter ES software is used for the parameterization, monitoring and service diagnostics of SIRIUS 3RW44 High Feature soft starters.

See Chapter "Planning and Configuration with SIRIUS".

Application

The SIRIUS 3RW44 solid-state soft starters are suitable for the torque-controlled soft starting and smooth ramp-down as well as braking of three-phase asynchronous motors.

Application areas

See "Selection aid for soft starters" on Page 4/7.

3RW44 Soft Starters for High-Feature Applications

3RW44

Selection and ordering data

SIRIUS 3RW44 for normal starting (CLASS 10) in inline circuit



Order No. supplement for the rated control supply voltage $U_s^{(2)}$

- 115 V AC
- 230 V AC

Note.

Soft starter selection depends on the rated motor current.

Please observe the notes for the selection of soft starters on Page 4/7.

The 3RW44 solid-state soft starters are designed for normal starting (Class 10). (Inertia load of the overall operating mechanism J_{Load} <10 x J_{Motor}; starting current 350 % x I_e for 20 s or similar load). For any other conditions of use, the devices should be selected using the Win-Soft Starter selection and simulation program. For information about rated currents for ambient temperatures > 40 °C and switching frequency, see "Technical specifications"

³RW44 2 soft starters. ... 3RW44 4. with screw terminals: delivery time class ► (preferred type).

²⁾ Control by way of the internal 24 V DC supply and direct control by means of PLC possible

3RW44 Soft Starters for High-Feature Applications

3RW44

| | | |) °C | | | AITIDICITI | temper | ature 5 | 0 0 | | DT | Normal starting (CLA | 33 10) | PU | PS* | PG | Weigh |
|---|---------|------------|-----------------------|---------|----------|------------|---------------------|---------|------------|------------|--------|----------------------------------|-----------------|----------------------|------------------|------------|------------------|
| Rated opera- ional current | | | of induc onal volt | | tors for | | | | | | | in inline circuit | | (UNIT, SET, M) | | | per PL approx |
| | 230 V | 400 V | 500 V | 690 V | | | 200 V | 230 V | 460 V | 575 V | | Order No. | Price per PU | | | | |
| 4 | kW | kW | kW | kW | kW | А | hp | hp | hp | hp | | | per Pu | | | | kg |
| Inline c | ircuit, | | | ional v | /oltage | | 600 V ¹⁾ | | | | | | | | | | |
| 29 | | 15 | 18.5 | | | 26 | | | 15 | 20 | Α | 3RW44 22-□BC□5 | | 1 | 1 unit | 131 | 6.500 |
| 36 47 | | 18.5 22 | 22 30 | | | 32 42 | | | 20 25 | 25 30 | A A | 3RW44 23-□BC□5 3RW44 24-□BC□5 | | 1 | 1 unit 1 unit | 131 131 | 6.500 6.500 |
| 57 | | 30 | 37 | | | 51 | | | 30 | 40 | Α | 3RW44 25-□BC□5 | | 1 | 1 unit | 131 | 6.500 |
| 77 | | 37 | 45 | | | 68 | | | 50 | 50 | Α | 3RW44 26-□BC□5 | | 1 | 1 unit | 131 | 6.500 |
| 93 | | 45 | 55 | | | 82 | | | 60 | 75 | Α | 3RW44 27-□BC□5 | | 1 | 1 unit | 131 | 6.500 |
| Order No | | | for con | nectior | types | | | | | | | | | | | | |
| With soWith sp | | | nals | | | | | | | | | 1 3 | | | | | |
| 113 | | 55 | 75 | | | 100 | | | 75 | 75 | В | 3RW44 34-□BC□5 | | 1 | 1 unit | 131 | 7.900 |
| 134 162 | | 75 90 | 90 110 | | | 117 145 | | | 75 100 | 100 125 | B B | 3RW44 35-□BC□5 3RW44 36-□BC□5 | | 1 | 1 unit 1 unit | 131 131 | 7.900 7.900 |
| | | | | | | | | | | | | | | ' | | | |
| 203 250 | | 110 132 | 132 160 | | | 180 215 | | | 125 150 | 150 200 | B B | 3RW44 43-□BC□5 3RW44 44-□BC□5 | | 1 | 1 unit 1 unit | 131 131 | 11.50 11.50 |
| 230 313 | | 160 | 200 | | | 280 | | | 200 | 250 250 | В | 3RW44 45-□BC□5 | | 1 | 1 unit | 131 | 11.50 |
| 356 | | 200 | 250 | | | 315 | | | 250 | 300 | В | 3RW44 46-□BC□5 | | 1 | 1 unit | 131 | 11.500 |
| 132 | | 250 | 315 | | | 385 | | | 300 | 400 | В | 3RW44 47-□BC□5 | | 1 | 1 unit | 131 | 11.500 |
| 551 | | 315 | 355 | | | 494 | | | 400 | 500 | С | 3RW44 53-□BC□5 | | 1 | 1 unit | 131 | 50.000 |
| 515 | | 355 | 400 | | | 551 | | | 450 | 600 700 | С | 3RW44 54-□BC□5 | | 1 | 1 unit | 131 | 50.000 |
| 593 | | 400 | 500 | | | 615 | | | 500 | | С | 3RW44 55-□BC□5 | | - 1 | 1 unit | 131 | 50.000 |
| 780 380 | | 450 500 | 560 630 | | | 693 780 | | | 600 700 | 750 850 | C | 3RW44 56-□BC□5 3RW44 57-□BC□5 | | 1 | 1 unit 1 unit | 131 131 | 50.000 |
| 970 | | 560 | 710 | | | 850 | | | 750 | 900 | Č | 3RW44 58-□BC□5 | | 1 | 1 unit | 131 | 50.000 |
| 1076 | | 630 | 800 | | | 970 | | | 850 | 1100 | С | 3RW44 65-□BC□5 | | 1 | 1 unit | 131 | 78.000 |
| 1214 | | 710 | 900 | | | 1076 | | | 950 | 1200 | С | 3RW44 66-□BC□5 | | 1 | 1 unit | 131 | 78.000 |

- With screw terminals
- Order No. supplement for the rated control supply voltage $U_{\rm s}^{\ 2)}$
- 115 V AC 230 V AC
- 1) Soft starter with screw terminals: 3RW44 2. ... 3RW44 4. Delivery time class A, 3RW44 5. ... 3RW44 6. Delivery time class B.
- $^{\rm 2)}$ Control by way of the internal 24 V DC supply and direct control by means

Soft starter selection depends on the rated motor current.

Please observe the notes for the selection of soft starters on Page 4/7.

The 3RW44 solid-state soft starters are designed for normal starting (Class 10). (Inertia load of the overall operating mechanism $J_{\rm Load}$ <10 x $J_{\rm Motor}$; starting current 350 % x $I_{\rm e}$ for 20 s or similar load). For any other conditions of use, the devices should be selected using the Win-Soft Starter selection and simulation program. For information about rated currents for ambient temperatures > 40 °C and switching frequency, see "Technical specifications".

3RW44 Soft Starters for High-Feature Applications

3RW44

| 2 1 1 | | |) °C | | | , andrene | temper | ature 5 | 0 % | | DT | Normal starting (CLASS | 5 10) | PU | PS* | PG | Weight |
|-------------------------------|----------|------------|------------|--------------|-----------|---------------------------------------|----------------|------------------|------------|--------------|--------|----------------------------------|-----------------|----------------------|------------------|------------|-------------------|
| Rated opera- ional current | rated o | peration | onal volt | 0 0 | | Rated operational current $I_{\rm e}$ | | e U _e | ed ope | rational | | in inline circuit | | (UNIT, SET, M) | | | per PU approx. |
| | | | 500 V | | 1000 V | | 200 V | 230 V | 460 V | 575 V | | Order No. | Price per PU | | | | |
| 4 | kW | kW | kW | kW | kW | Α | hp | hp | hp | hp | | 1 | Jei FU | | | | kg |
| Inline c | ircuit, | | • | | /oltage | | 90 V | | | | | | | | | | |
| <u>29</u> 36 | | 15 18.5 | 18.5 22 | 30 37 | | 26 32 | | | 15 20 | 20 25 | B B | 3RW44 22-□BC□6 3RW44 23-□BC□6 | | 1 1 | 1 unit 1 unit | 131 131 | 6.500 6.500 |
| 17 | | 22 | 30 | 45 | | 42 | | | 25 | 30 | В | 3RW44 24-□BC□6 | | 1 | 1 unit | 131 | 6.500 |
| 57 77 | | 30 37 | 37 45 | 55 75 | | 51 68 | | | 30 50 | 40 50 | ВВ | 3RW44 25-□BC□6 3RW44 26-□BC□6 | | 1 | 1 unit 1 unit | 131 131 | 6.500 6.500 |
| 93 | | 45 | 55 | 90 | | 82 | | | 60 | 75 | В | 3RW44 27-□BC□6 | | 1 | 1 unit | 131 | 6.500 |
| Order No With sc With sp | rew terr | minals | | inection | types | | | | | | | 1 3 | | | | | |
| 113 | | 55 | 75 | 110 | | 100 | | | 75 | 75 | В | 3RW44 34-□BC□6 | | 1 | 1 unit | 131 | 7.900 |
| 134 162 | | 75 90 | 90 110 | 132 160 | | 117 145 | | | 75 100 | 100 125 | B B | 3RW44 35-□BC□6 3RW44 36-□BC□6 | | 1 1 | 1 unit 1 unit | 131 131 | 7.900 7.900 |
| 203 | | 110 | 132 | 200 | - | 180 | | | 125 | 150 | В | 3RW44 43-□BC□6 | | 1 | 1 unit | 131 | 11.500 |
| 250 313 | | 132 160 | 160 200 | 250 315 | | 215 280 | | | 150 200 | 200 250 | B B | 3RW44 44-□BC□6 3RW44 45-□BC□6 | | 1 1 | 1 unit 1 unit | 131 131 | 11.500 11.500 |
| 356 132 | | 200 250 | 250 315 | 355 400 | | 315 385 | | | 250 300 | 300 400 | B B | 3RW44 46-□BC□6 3RW44 47-□BC□6 | | 1 | 1 unit 1 unit | 131 131 | 11.500 11.500 |
| | | | | | | | | | | | | | | • | | | |
| 551 615 | | 315 355 | 355 400 | 560 630 | | 494 551 | | | 400 450 | 500 600 | СС | 3RW44 53-□BC□6 3RW44 54-□BC□6 | | 1 | 1 unit 1 unit | 131 131 | 50.000 50.000 |
| 593 | | 400 | 500 | 710 | | 615 | | | 500 | 700 | Č | 3RW44 55-□BC□6 | | i | 1 unit | 131 | 50.000 |
| 780 | | 450 | 560 | 800 | | 693 | | | 600 | 750 | С | 3RW44 56-□BC□6 | | 1 | 1 unit | 131 | 50.000 |
| 380 | | 500 | 630 | 900 | | 780 | | | 700 | 850 | С | 3RW44 57-□BC□6 | | 1 | 1 unit | 131 | 50.000 |
| 970 | | 560 | 710 | 1000 | | 850 | | | 750 | 900 | С | 3RW44 58-□BC□6 | | 1 | 1 unit | 131 | 50.000 |
| 1076 1214 | | 630 710 | 800 900 | 1100 1200 | | 970 1076 | | | 850 950 | 1100 1200 | СС | 3RW44 65-□BC□6 3RW44 66-□BC□6 | | 1 1 | 1 unit 1 unit | 131 131 | 78.000 78.000 |
| Order No | o. suppl | lement | for con | nection | types | Ī | | | | | | | | | | | |
| With sp With sc | ring-typ | e termi | | | 71 | | | | | | | 2 6 | | | | | |
| Order No | o. suppl | lement | for the | rated c | ontrol si | upply vol | tage <i>U.</i> | 1) | | | | | | | | | |

- 115 V AC 230 V AC
- 1) Control by way of the internal 24 V DC supply and direct control by means

Soft starter selection depends on the rated motor current.

Please observe the notes for the selection of soft starters on Page 4/7.

The 3RW44 solid-state soft starters are designed for normal starting (Class 10). (Inertia load of the overall operating mechanism $J_{\rm Load}$ <10 x $J_{\rm Motor}$; starting current 350 % x $I_{\rm e}$ for 20 s or similar load). For any other conditions of use, the devices should be selected using the Win-Soft Starter selection and simulation program. For information about rated currents for ambient temperatures > 40 °C and switching frequency, see "Technical specifications".

3RW44

SIRIUS 3RW44 for heavy starting (CLASS 20) in inline circuit

3RW44 Soft Starters for High-Feature Applications

SIRIUS 3RW Soft Starters











50.000

78.000

78.000

78.000

1 unit

1 unit

131

| · heiseleine | mm | | · landas | desired man | | | 1111 ****** | Millian III | | | | a montant were | | | | |
|--|-----------|---------------------------------|----------|-------------|-----------|--|---------------------|-------------|----------|-------|----|---|----------------------------|----------|-----|-----------------------------|
| 3RW44 2 | 27-1BC4 | 4 | 3RW | /44 36-6 | 6BC44 | | 3RW44 | 47-6BC | 244 | | 3 | BRW44 58-6BC44 | 3RW4 | 4 66-6BC | 244 | |
| Ambient Rated opera- tional current I_e | Rated | ature 40 power c operatio | of induc | | otors for | Ambient Rated operational current I _e | Rated | power of | of induc | | DT | Heavy starting (CLASS 20) in inline circuit | PU (UNIT, SET, M) | PS* | PG | Weight per PU approx. |
| | 230 V | 400 V | 500 V | | | | 200 V | 230 V | 460 V | 575 V | | Order No. Price per PU | | | | |
| Α | kW | kW | kW | kW | kW | А | hp | hp | hp | hp | | pei FO | | | | kg |
| Inline o | | | operat | ional | voltage | | 160 V ¹⁾ | | | | | | | | | |
| 29 | 5.5 | 15 | | | | 26 | 7.5 | 7.5 | 15 | | | 3RW44 22-□BC□4 | 1 | 1 unit | 131 | 6.500 |
| 36 | 7.5 | 18.5 | | | | 32 | 10 | 10 | 20 | | | 3RW44 23-□BC□4 | 1 | 1 unit | 131 | 6.500 |
| 47 | 11 | 22 | | | | 42 | 10 | 15 | 25 | | | 3RW44 24-□BC□4 | 1 | 1 unit | 131 | 6.500 |
| 57 | 15 | 30 | | | | 51 | 15 | 15 | 30 | | | 3RW44 25-□BC□4 | 1 | 1 unit | 131 | 6.500 |
| 77 | 18.5 | 37 | | | | 68 | 20 | 20 | 50 | | | 3RW44 27-□BC□4 | 1 | 1 unit | 131 | 6.500 |
| • With so | crew terr | minals | | nectio | n types | | | | | | | 1 3 | | | | |
| 93 | 22 | 45 | | | | 82 | 25 | 25 | 60 | | В | 3RW44 34-□BC□4 | 1 | 1 unit | 131 | 7.900 |
| 113 | 30 | 55 | | | | 100 | 30 | 30 | 75 | | В | 3RW44 35-□BC□4 | 1 | 1 unit | 131 | 7.900 |
| 134 | 37 | 75 | | | | 117 | 30 | 40 | 75 | | В | 3RW44 36-□BC□4 | 1 | 1 unit | 131 | 7.900 |
| 162 | 45 | 90 | | | | 145 | 40 | 50 | 100 | | В | 3RW44 43-□BC□4 | 1 | 1 unit | 131 | 11.500 |
| 203 | 55 | 110 | | | | 180 | 50 | 60 | 125 | | В | 3RW44 45-□BC□4 | 1 | 1 unit | 131 | 11.500 |
| 250 | 75 | 132 | | | | 215 | 60 | 75 | 150 | | В | 3RW44 46-□BC□4 | 1 | 1 unit | 131 | 11.500 |
| 313 | 90 | 160 | | | | 280 | 75 | 100 | 200 | | В | 3RW44 47-□BC□4 | 1 | 1 unit | 131 | 11.500 |
| 356 | 110 | 200 | | | | 315 | 100 | 125 | 250 | | В | 3RW44 47-□BC□4 | 1 | 1 unit | 131 | 11.500 |
| 432 | 132 | 250 | | | | 385 | 125 | 150 | 300 | | С | 3RW44 53-□BC□4 | 1 | 1 unit | 131 | 50.000 |
| 551 | 160 | 315 | | | | 494 | 150 | 200 | 400 | | С | 3RW44 53-□BC□4 | 1 | 1 unit | 131 | 50.000 |
| 615 | 200 | 355 | | | | 551 | 150 | 200 | 450 | | С | 3RW44 55-□BC□4 | 1 | 1 unit | 131 | 50.000 |

Order No. supplement for connection types

400

450

500

560

- With spring-type terminals
- With screw terminals

200

250

315

Order No. supplement for the rated control supply voltage $U_s^{(2)}$

615

693

780

850

200

200

250

300

250

300

350

500

600

700

750

- 115 V AC
- 230 V AC

693

780

880

970

Soft starter selection depends on the rated motor current.

Please observe the notes for the selection of soft starters on Page 4/7.

The 3RW44 solid-state soft starters are designed for normal starting (Class 10). (Inertia load of the overall operating mechanism $J_{\rm Load}$ <10 x $J_{\rm Motor}$; starting current 350 % x $I_{\rm e}$ for 20 s or similar load). For any other conditions of use, the devices should be selected using the Win-Soft Starter selection and simulation program. For information about rated currents for ambient temperatures > 40 °C and switching frequency, see "Technical specifications".

3RW44 57-□BC□4

3RW44 65-□BC□4

3RW44 65-□BC□4

3RW44 65-□BC□4

2 6

C

 $^{^{\}rm 1)}$ 3RW44 2 soft starters. ... 3RW44 4. with screw terminals: delivery time class ▶ (preferred type).

²⁾ Control by way of the internal 24 V DC supply and direct control by means of PLC possible.

3RW44 Soft Starters for High-Feature Applications

3RW44

| Ambient | | | | | | | | | | | | Heavy starting (CLASS 20) | PU | PS* | PG | Weight |
|---------------------------------|----------|--------|----------|---------|----------|---------------------------------|-------|-----------|-----|-------|---|---------------------------|----------------------|--------|-----|-------------------|
| Rated operational current I_e | | | | | tors for | Rated operational current I_e | | s for rat | | | | in inline circuit | (UNIT, SET, M) | | | per PU approx. |
| | 230 V | | 500 V | | 1000 V | | 200 V | 230 V | | 575 V | | Order No. Price per PU | | | | |
| Α | kW | kW | kW | kW | kW | А | hp | hp | hp | hp | | регго | | | | kg |
| | circuit, | | | ional v | /oltage | 400 6 | 00 V' | | | | | | | | | |
| 29 | | 15 | 18.5 | | | 26 | | | 15 | 20 | Α | 3RW44 22-□BC□5 | 1 | 1 unit | 131 | 6.500 |
| 36 | | 18.5 | 22 | | | 32 | | | 20 | 25 | Α | 3RW44 23-□BC□5 | 1 | 1 unit | 131 | 6.500 |
| 47 | | 22 | 30 | | | 42 | | | 25 | 30 | Α | 3RW44 24-□BC□5 | 1 | 1 unit | 131 | 6.500 |
| 57 | | 30 | 37 | | | 51 | | | 30 | 40 | Α | 3RW44 25-□BC□5 | 1 | 1 unit | 131 | 6.500 |
| 77 | | 37 | 45 | | | 68 | | | 50 | 50 | Α | 3RW44 27-□BC□5 | 1 | 1 unit | 131 | 6.500 |
| • With so | crew ter | minals | | nection | n types | | | | | | | 1 3 | | | | |
| 93 | | 45 | 55 | | | 82 | | | 60 | 75 | В | 3RW44 34-□BC□5 | 1 | 1 unit | 131 | 7.900 |
| 113 | | 55 | 75 | | | 100 | | | 75 | 75 | В | 3RW44 35-□BC□5 | 1 | 1 unit | 131 | 7.900 |
| 134 | | 75 | 90 | | | 117 | | | 75 | 100 | В | 3RW44 36-□BC□5 | 1 | 1 unit | 131 | 7.900 |
| 162 | | 90 | 110 | | | 145 | | | 100 | 125 | В | 3RW44 43-□BC□5 | 1 | 1 unit | 131 | 11.500 |
| 203 | | 110 | 132 | | | 180 | | | 125 | 150 | В | 3RW44 45-□BC□5 | 1 | 1 unit | 131 | 11.500 |
| 250 | | 132 | 160 | | | 215 | | | 150 | 200 | В | 3RW44 46-□BC□5 | 1 | 1 unit | 131 | 11.500 |
| 313 | | 160 | 200 | | | 280 | | | 200 | 250 | В | 3RW44 47-□BC□5 | 1 | 1 unit | 131 | 11.500 |
| 356 | | 200 | 250 | | | 315 | | | 250 | 300 | В | 3RW44 47-□BC□5 | 1 | 1 unit | 131 | 11.500 |
| 432 | | 250 | 315 | | | 385 | | | 300 | 400 | С | 3RW44 53-□BC□5 | 1 | 1 unit | 131 | 50.000 |
| 551 | | 315 | 355 | | | 494 | | | 400 | 500 | С | 3RW44 53-□BC□5 | 1 | 1 unit | 131 | 50.000 |
| 615 | | 355 | 400 | | | 551 | | | 450 | 600 | С | 3RW44 54-□BC□5 | 1 | 1 unit | 131 | 50.000 |
| 693 | | 400 | 500 | | | 615 | | | 500 | 700 | С | 3RW44 57-□BC□5 | 1 | 1 unit | 131 | 50.000 |
| 780 | | 450 | 560 | | | 693 | | | 600 | 750 | С | 3RW44 65-□BC□5 | 1 | 1 unit | 131 | 78.000 |
| 880 | | 500 | 630 | | | 780 | | | 700 | 850 | С | 3RW44 65-□BC□5 | 1 | 1 unit | 131 | 78.000 |
| 970 | | 560 | 710 | | | 850 | | | 750 | 900 | С | 3RW44 65-□BC□5 | 1 | 1 unit | 131 | 78.000 |
| Ouden N | | | . | | | • | | | | | | | | | | |

Order No. supplement for connection types

- With spring-type terminals
- With spring-type term
 With screw terminals

Order No. supplement for the rated control supply voltage $U_s^{(2)}$

- 115 V AC
- 230 V AC

 Soft starter with screw terminals: 3RW44 2. ... 3RW44 4. Delivery time class A, 3RW44 5. ... 3RW44 6. Delivery time class B.

Note:

Soft starter selection depends on the rated motor current.

Please observe the notes for the selection of soft starters on Page 4/7.

The 3RW44 solid-state soft starters are designed for normal starting (Class 10). (Inertia load of the overall operating mechanism $J_{\rm Load}$ <10 x $J_{\rm Motor}$; starting current 350 % x $I_{\rm e}$ for 20 s or similar load). For any other conditions of use, the devices should be selected using the Win-Soft Starter selection and simulation program. For information about rated currents for ambient temperatures > 40 °C and switching frequency, see "Technical specifications".

²⁾ Control by way of the internal 24 V DC supply and direct control by means of PLC possible.

3RW44 Soft Starters for High-Feature Applications

3RW44

| Ambient | t temper | ature 40 | 0 °C | | | Ambient | temper | ature 5 | | DT | | PU | PS* | PG | Weight | |
|---------------------------------|----------|-----------|-----------|---------|---------|---------------------------------|-----------------|----------------------------|------------------|----------|---|------------------------|----------------------|--------|--------|-------------------|
| Rated operational current I_e | rated | operation | onal voli | 5 6 | | Rated operational current I_e | motor voltag | s for rat le <i>U</i> e | of inducted oper | rational | | in inline circuit | (UNIT, SET, M) | | | per PU approx. |
| | 230 V | | 500 V | | 1000 V | | 200 V | | | 575 V | | Order No. Price per PU | | | | |
| A | kW | kW | kW | kW | kW | A | hp | hp | hp | hp | | perio | | | | kg |
| | | | | | | 400 6 | 90 V | | | | | | | | | |
| 29 | | 15 | 18.5 | 30 | | 26 32 | | | 15 20 | 20 | В | 3RW44 22-□BC□6 | 1 | 1 unit | 131 | 6.500 |
| 36 | | 18.5 | 22 | 37 | | 42 | | | 25 | 25 | В | 3RW44 23-□BC□6 | 1 | 1 unit | 131 | 6.500 |
| 47 | | 22 | 30 | 45 | | 42 | | | 25 | 30 | В | 3RW44 24-□BC□6 | 1 | 1 unit | 131 | 6.500 |
| 57 | | 30 | 37 | 55 | | 51 | | | 30 | 40 | В | 3RW44 25-□BC□6 | 1 | 1 unit | 131 | 6.500 |
| 77 | | 37 | 45 | 75 | | 68 | | | 50 | 50 | В | 3RW44 27-□BC□6 | 1 | 1 unit | 131 | 6.500 |
| • With see With see | crew ter | minals | | nection | n types | | | | | | | 1 3 | | | | |
| 93 | | 45 | 55 | 90 | | 82 | | | 60 | 75 | В | 3RW44 34-□BC□6 | 1 | 1 unit | 131 | 7.900 |
| 113 | | 55 | 75 | 110 | | 100 | | | 75 | 75 | В | 3RW44 35-□BC□6 | 1 | 1 unit | 131 | 7.900 |
| 134 | | 75 | 90 | 132 | | 117 | | | 75 | 100 | В | 3RW44 36-□BC□6 | 1 | 1 unit | 131 | 7.900 |
| 162 | | 90 | 110 | 160 | | 145 | | | 100 | 125 | В | 3RW44 43-□BC□6 | 1 | 1 unit | 131 | 11.500 |
| 203 | | 110 | 132 | 200 | | 180 | | | 125 | 150 | В | 3RW44 45-□BC□6 | 1 | 1 unit | 131 | 11.500 |
| 250 | | 132 | 160 | 250 | | 215 | | | 150 | 200 | В | 3RW44 46-□BC□6 | 1 | 1 unit | 131 | 11.500 |
| 313 | | 160 | 200 | 315 | | 280 | | | 200 | 250 | В | 3RW44 47-□BC□6 | 1 | 1 unit | 131 | 11.500 |
| 356 | | 200 | 250 | 355 | | 315 | | | 250 | 300 | В | 3RW44 47-□BC□6 | 1 | 1 unit | 131 | 11.500 |
| 432 | | 250 | 315 | 400 | | 385 | | | 300 | 400 | С | 3RW44 53-□BC□6 | 1 | 1 unit | 131 | 50.000 |
| 551 | | 315 | 355 | 560 | | 494 | | | 400 | 500 | С | 3RW44 53-□BC□6 | 1 | 1 unit | 131 | 50.000 |
| 615 | | 355 | 400 | 630 | | 551 | | | 450 | 600 | С | 3RW44 55-□BC□6 | 1 | 1 unit | 131 | 50.000 |
| 693 | | 400 | 500 | 710 | | 615 | | | 500 | 700 | С | 3RW44 57-□BC□6 | 1 | 1 unit | 131 | 50.000 |
| 780 | | 450 | 560 | 800 | | 693 | | | 600 | 750 | С | 3RW44 65-□BC□6 | 1 | 1 unit | 131 | 78.000 |
| 880 | | 500 | 630 | 900 | | 780 | | | 700 | 850 | С | 3RW44 65-□BC□6 | 1 | 1 unit | 131 | 78.000 |
| 970 | | 560 | 710 | 1000 | | 850 | | | 750 | 900 | С | 3RW44 65-□BC□6 | 1 | 1 unit | 131 | 78.000 |
| Ouder N | | | | | | • | | | | | | | | | | |

Order No. supplement for connection types

- With spring-type terminals
- With screw terminals

Order No. supplement for the rated control supply voltage $U_{\rm s}^{\ 1)}$

- 230 V AC

Soft starter selection depends on the rated motor current.

Please observe the notes for the selection of soft starters on Page 4/7.

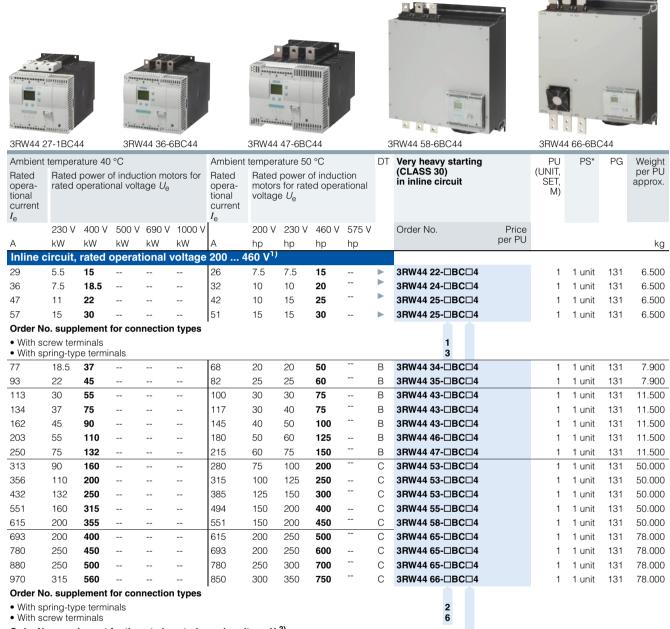
The 3RW44 solid-state soft starters are designed for normal starting (Class 10). (Inertia load of the overall operating mechanism J_{Load} <10 x J_{Motor} ; starting current 350 % x I_{e} for 20 s or similar load). For any other conditions of use, the devices should be selected using the Win-Soft Starter selection and simulation program. For information about rated currents for ambient temperatures > 40 °C and switching frequency, see "Technical specifications".

¹⁾ Control by way of the internal 24 V DC supply and direct control by means of PLC possible.

3RW44 Soft Starters for High-Feature Applications

3RW44

SIRIUS 3RW44 for very heavy starting (CLASS 30) in inline circuit



Order No. supplement for the rated control supply voltage $U_s^{(2)}$

- 115 V AC
- 230 V AC

Note:

Soft starter selection depends on the rated motor current.

Please observe the notes for the selection of soft starters on Page 4/7.

The 3RW44 solid-state soft starters are designed for normal starting (Class 10). (Inertia load of the overall operating mechanism $J_{\rm Load} < 10~{\rm x}~J_{\rm Motor}$; starting current 350 % ${\rm x}~I_{\rm e}$ for 20 s or similar load). For any other conditions of use, the devices should be selected using the Win-Soft Starter selection and simulation program. For information about rated currents for ambient temperatures > 40 °C and switching frequency, see "Technical specifications".

^{1) 3}RW44 2 soft starters. ... 3RW44 4. with screw terminals: delivery time class ▶ (preferred type).

²⁾ Control by way of the internal 24 V DC supply and direct control by means of PLC possible.

3RW44 Soft Starters for High-Feature Applications

3RW44

| Ambient | t temper | ature 40 | O°C | | | Ambient | temper | ature 5 | 0 °C | | DT | | | PU | PS* | PG | Weight |
|---|----------|-----------|-----------|--------------------|----------|------------------|--------|---------|---------|----------|----|---------------------------------|-----------------|----------------|--------|-----|----------------|
| Rated | | | of induc | | tors for | Rated | | | of indu | | | (CLASS 30) in inline circuit | | (UNIT, SET. | | | per PU approx. |
| opera- tional | rated | operation | onal volt | age U _e | | opera- tional | motor | | ted ope | rational | | III IIIIII OII OII OII I | | M) | | | арргол. |
| current | | | | | | current | | | | | | | | | | | |
| I_{e} | | | | | | $I_{ m e}$ | | | | | | | | | | | |
| | 230 V | | 500 V | 690 V | | | 200 V | | | 575 V | | Order No. | Price per PU | | | | |
| A | kW | kW | kW | kW | kW | A | hp | hp | hp | hp | | | perio | | | | kg |
| | | | | ionai v | | 400 6 | | | | | | | | | | | |
| 29 | | 15 | 18.5 | | | 26 | | | 15 | 20 | Α | 3RW44 22-□BC□5 | | 1 | 1 unit | 131 | 6.500 |
| 36 | | 18.5 | 22 | | | 32 | | | 20 | 25 | Α | 3RW44 24-□BC□5 | | 1 | 1 unit | 131 | 6.500 |
| 47 | | 22 | 30 | | | 42 | | | 25 | 30 | Α | 3RW44 25-□BC□5 | | 1 | 1 unit | 131 | 6.500 |
| 57 | | 30 | 37 | | | 51 | | | 30 | 40 | Α | 3RW44 25-□BC□5 | | 1 | 1 unit | 131 | 6.500 |
| Order N | | | for con | nection | ı types | | | | | | | | | | | | |
| With sWith s | | | inals | | | | | | | | | 1 3 | | | | | |
| 77 | | 37 | 45 | | | 68 | | | 50 | 50 | В | 3RW44 34-□BC□5 | | 1 | 1 unit | 131 | 7.900 |
| 93 | | 45 | 55 | | | 82 | | | 60 | 75 | В | 3RW44 35-□BC□5 | | 1 | 1 unit | 131 | 7.900 |
| 113 | | 55 | 75 | | | 100 | | | 75 | 75 | В | 3RW44 43-□BC□5 | | 1 | 1 unit | 131 | 11.500 |
| 134 | | 75 | 90 | | | 117 | | | 75 | 100 | В | 3RW44 43-□BC□5 | | 1 | 1 unit | 131 | 11.500 |
| 162 | | 90 | 110 | | | 145 | | | 100 | 125 | В | 3RW44 43-□BC□5 | | 1 | 1 unit | 131 | 11.500 |
| 203 | | 110 | 132 | | | 180 | | | 125 | 150 | В | 3RW44 46-□BC□5 | | 1 | 1 unit | 131 | 11.500 |
| 250 | | 132 | 160 | | | 215 | | | 150 | 200 | В | 3RW44 47-□BC□5 | | 1 | 1 unit | 131 | 11.500 |
| 313 | | 160 | 200 | | | 280 | | | 200 | 250 | С | 3RW44 53-□BC□5 | | 1 | 1 unit | 131 | 50.000 |
| 356 | | 200 | 250 | | | 315 | | | 250 | 300 | С | 3RW44 53-□BC□5 | | 1 | 1 unit | 131 | 50.000 |
| 432 | | 250 | 315 | | | 385 | | | 300 | 400 | С | 3RW44 53-□BC□5 | | 1 | 1 unit | 131 | 50.000 |
| 551 | | 315 | 355 | | | 494 | | | 400 | 500 | С | 3RW44 55-□BC□5 | | 1 | 1 unit | 131 | 50.000 |
| 615 | | 355 | 400 | | | 551 | | | 450 | 600 | С | 3RW44 58-□BC□5 | | 1 | 1 unit | 131 | 50.000 |
| 693 | | 400 | 500 | | | 615 | | | 500 | 700 | С | 3RW44 65-□BC□5 | | 1 | 1 unit | 131 | 78.000 |
| 780 | | 450 | 560 | | | 693 | | | 600 | 750 | С | 3RW44 65-□BC□5 | | 1 | 1 unit | 131 | 78.000 |
| 880 | | 500 | 630 | | | 780 | | | 700 | 850 | С | 3RW44 65-□BC□5 | | 1 | 1 unit | 131 | 78.000 |
| | | | | | | 850 | | | 750 | 900 | С | 3RW44 66-□BC□5 | | 1 | 1 unit | 131 | 78.000 |
| | | | _ | | | • | | | | | | | | | | | |

Order No. supplement for connection types

- With spring-type terminals
- With screw terminals

Order No. supplement for the rated control supply voltage $U_s^{(2)}$

- 115 V AC
- 115 V AC • 230 V AC

Note:

Soft starter selection depends on the rated motor current.

Please observe the notes for the selection of soft starters on Page 4/7.

The 3RW44 solid-state soft starters are designed for normal starting (Class 10). (Inertia load of the overall operating mechanism $J_{\rm Load} <$ 10 x $J_{\rm Motor}$; starting current 350 % x $I_{\rm e}$ for 20 s or similar load). For any other conditions of use, the devices should be selected using the Win-Soft Starter selection and simulation program. For information about rated currents for ambient temperatures > 40 °C and switching frequency, see "Technical specifications".

Soft starter with screw terminals: 3RW44 2. ... 3RW44 4. Delivery time class A, 3RW44 5. ... 3RW44 6. Delivery time class B.

²⁾ Control by way of the internal 24 V DC supply and direct control by means of PLC possible.

3RW44 Soft Starters for High-Feature Applications

3RW44

| Ambient t | temper | ature 40 |) °C | | | Ambient | temper | ature 5 | 0 °C | | DT | Very heavy starting | | PU | PS* | PG | Weight |
|---------------------------------|----------|--------------------|-----------------------|----------------------------|----------|---------------------------------------|--------|-----------|------------------|-------|----|---------------------------------|--------|----------------------|--------|-----|-------------------|
| Rated operational current I_e | | | of induc onal volt | ction mo age <i>U</i> e | tors for | Rated operational current $I_{\rm e}$ | | s for rat | of inducted oper | | | (CLASS 30) in inline circuit | | (UNIT, SET, M) | | | per PU approx. |
| | 230 V | 400 V | 500 V | 690 V | 1000 V | | 200 V | 230 V | 460 V | 575 V | | Order No. | Price | | | | |
| Α | kW | kW | kW | kW | kW | А | hp | hp | hp | hp | | | per PU | | | | kg |
| Inline c | ircuit, | | • | | voltage | | 90 V | | | | | | | | | | |
| 29 | | 15 | 18.5 | 30 | | 26 | | | 15 | 20 | В | 3RW44 22-□BC□6 | | 1 | 1 unit | 131 | 6.500 |
| 36 | | 18.5 | 22 | 37 | | 32 | | | 20 | 25 | В | 3RW44 24-□BC□6 | | 1 | 1 unit | 131 | 6.500 |
| 47 | | 22 | 30 | 45 | | 42 | | | 25 | 30 | В | 3RW44 25-□BC□6 | | 1 | 1 unit | 131 | 6.500 |
| 57 | | 30 | 37 | 55 | | 51 | | | 30 | 40 | В | 3RW44 25-□BC□6 | | 1 | 1 unit | 131 | 6.500 |
| • With sci • With sp | rew teri | minals oe termi | nals | | 1 types | | | | | | | 1 3 | | | | | |
| 77 | | 37 | 45 | 75 | | 68 | | | 50 | 50 | В | 3RW44 34-□BC□6 | | 1 | 1 unit | 131 | 7.900 |
| 93 | | 45 | 55 | 90 | | 82 | | | 60 | 75 | В | 3RW44 35-□BC□6 | | 1 | 1 unit | 131 | 7.900 |
| 113 | | 55 | 75 | 110 | | 100 | | | 75 | 75 | В | 3RW44 43-□BC□6 | | 1 | 1 unit | 131 | 11.500 |
| 134 | | 75 | 90 | 132 | | 117 | | | 75 | 100 | В | 3RW44 43-□BC□6 | | 1 | 1 unit | 131 | 11.500 |
| 162 | | 90 | 110 | 160 | | 145 | | | 100 | 125 | В | 3RW44 43-□BC□6 | | 1 | 1 unit | 131 | 11.500 |
| 203 | | 110 | 132 | 200 | | 180 | | | 125 | 150 | В | 3RW44 46-□BC□6 | | 1 | 1 unit | 131 | 11.500 |
| 250 | | 132 | 160 | 250 | | 215 | | | 150 | 200 | В | 3RW44 47-□BC□6 | | 1 | 1 unit | 131 | 11.500 |
| 313 | | 160 | 200 | 315 | | 280 | | | 200 | 250 | С | 3RW44 53-□BC□6 | | 1 | 1 unit | 131 | 50.000 |
| 356 | | 200 | 250 | 355 | | 315 | | | 250 | 300 | С | 3RW44 53-□BC□6 | | 1 | 1 unit | 131 | 50.000 |
| 432 | | 250 | 315 | 400 | | 385 | | | 300 | 400 | С | 3RW44 53-□BC□6 | | 1 | 1 unit | 131 | 50.000 |
| 551 | | 315 | 355 | 560 | | 494 | | | 400 | 500 | С | 3RW44 55-□BC□6 | | 1 | 1 unit | 131 | 50.000 |
| 615 | | 355 | 400 | 630 | | 551 | | | 450 | 600 | С | 3RW44 58-□BC□6 | | 1 | 1 unit | 131 | 50.000 |
| 693 | | 400 | 500 | 710 | | 615 | | | 500 | 700 | С | 3RW44 65-□BC□6 | | 1 | 1 unit | 131 | 78.000 |
| 780 | | 450 | 560 | 800 | | 693 | | | 600 | 750 | С | 3RW44 65-□BC□6 | | 1 | 1 unit | 131 | 78.000 |
| 880 | | 500 | 630 | 900 | | 780 | | | 700 | 850 | С | 3RW44 65-□BC□6 | | 1 | 1 unit | 131 | 78.000 |
| | | | | | | 850 | | | 750 | 900 | С | 3RW44 66-□BC□6 | | 1 | 1 unit | 131 | 78.000 |

Order No. supplement for connection types

- With spring-type terminals
- With spring-type term
 With screw terminals

Order No. supplement for the rated control supply voltage $U_{\rm s}^{\ 1)}$

- 115 V AC
- 230 V AC
- 1) Control by way of the internal 24 V DC supply and direct control by means of PLC possible.

Note:

Soft starter selection depends on the rated motor current.

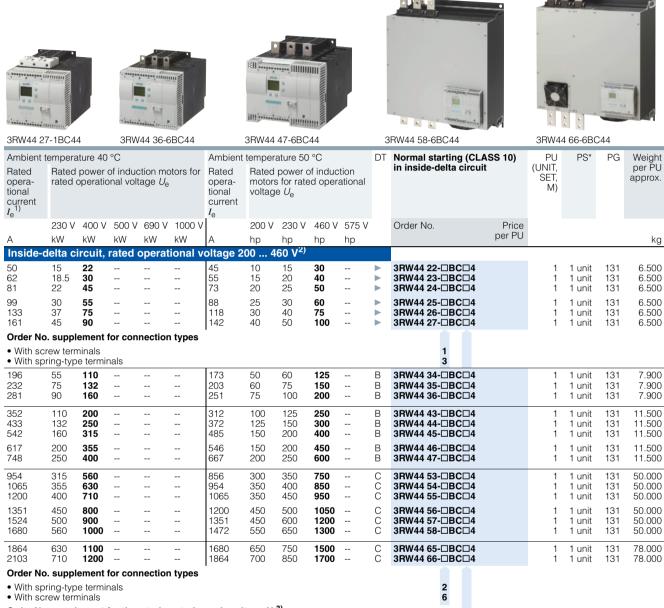
Please observe the notes for the selection of soft starters on Page 4/7.

The 3RW44 solid-state soft starters are designed for normal starting (Class 10). (Inertia load of the overall operating mechanism $J_{\rm Load}$ <10 x $J_{\rm Motor}$; starting current 350 % x $I_{\rm e}$ for 20 s or similar load). For any other conditions of use, the devices should be selected using the Win-Soft Starter selection and simulation program. For information about rated currents for ambient temperatures > 40 °C and switching frequency, see "Technical specifications".

3RW44 Soft Starters for High-Feature Applications

3RW44

SIRIUS 3RW44 for normal starting (CLASS 10) in inside-delta circuit



Order No. supplement for the rated control supply voltage $U_s^{(3)}$

- 115 V AC
- 230 V AC

Note:

Soft starter selection depends on the rated motor current.

Please observe the notes for the selection of soft starters on Page 4/7.

The 3RW44 solid-state soft starters are designed for normal starting (Class 10). (Inertia load of the overall operating mechanism $J_{\rm Load} <$ 10 x $J_{\rm Motor}$; starting current 350 % x $I_{\rm e}$ for 20 s or similar load). For any other conditions of use, the devices should be selected using the Win-Soft Starter selection and simulation program. For information about rated currents for ambient temperatures > 40 °C and switching frequency, see "Technical specifications".

- 2) 3RW44 2 soft starters. ... 3RW44 4. with screw terminals: delivery time class ► (preferred type).
- 3) Control by way of the internal 24 V DC supply and direct control by means of PLC possible.

¹⁾ In the selection table, the unit rated current I_e refers to the induction motor's rated operational current in the inside-delta circuit. The actual current of the device is approx. 58 % of this value.

3RW44 Soft Starters for High-Feature Applications

3RW44

| Ambient temperature 40 °C | | | | | | Ambient temperature 50 °C | | | | | DT | Normal starting (CLASS 10) | PU | PS* | PG | Weigh |
|--------------------------------------|--|--------------------|---------------------|----------|---------------------------------|---|------------------|--------------------|----------------------|----------------------|-------------------------|--|-------------|----------------------------|-------------------|-------------------------|
| Rated operational current $I_e^{1)}$ | Rated power of induction motors rated operational voltage U_{e} | | | | Rated operational current I_e | Rated power of induction motors for rated operational voltage $U_{\rm e}$ | | | | | in inside-delta circuit | (UNIT, SET, M) | | | per Pl approx | |
| | 230 V | 400 V | 500 V | 690 V | | | 200 V | 230 V | 460 V | 575 V | | Order No. Price | | | | |
| A | kW | kW | kW | kW | kW | Α | hp | hp | hp | hp | | per PU | | | | k |
| Inside-d | delta c | ircuit, | rated | operat | ional v | oltage 4 | 100 (| 600 V ² |) | | | | | | | |
| 50 62 81 | | 22 30 45 | 30 37 45 | | | 45 55 73 | | | 30 40 50 | 40 50 60 | A A A | 3RW44 22-□BC□5 3RW44 23-□BC□5 3RW44 24-□BC□5 | 1 1 1 | 1 unit 1 unit 1 unit | 131 131 131 | 6.50 6.50 6.50 |
| 99 133 161 | | 55 75 90 | 55 90 110 | | | 88 118 142 | | | 60 75 100 | 75 100 125 | A A A | 3RW44 25-□BC□5 3RW44 26-□BC□5 3RW44 27-□BC□5 | 1 1 1 | 1 unit 1 unit 1 unit | 131 131 131 | 6.50 6.50 6.50 |
| Order No With so With sp | rew terr | ninals | | nection | ı types | | | | | | | 1 3 | | | | |
| 196 232 281 | | 110 132 160 | 132 160 200 | | | 173 203 251 | | | 125 150 200 | 150 200 250 | B B B | 3RW44 34-□BC□5 3RW44 35-□BC□5 3RW44 36-□BC□5 | 1 1 1 | 1 unit 1 unit 1 unit | 131 131 131 | 7.90 7.90 7.90 |
| 352 433 542 | | 200 250 315 | 250 315 355 | | | 312 372 485 | | | 250 300 400 | 300 350 500 | B B B | 3RW44 43-□BC□5 3RW44 44-□BC□5 3RW44 45-□BC□5 | 1 1 1 | 1 unit 1 unit 1 unit | 131 131 131 | 11.50 11.50 11.50 |
| 617 748 | | 355 400 | 450 500 | | | 546 667 | | | 450 600 | 600 750 | B B | 3RW44 46-□BC□5 3RW44 47-□BC□5 | 1 1 | 1 unit 1 unit | 131 131 | 11.50 11.50 |
| 954 1065 1200 | | 560 630 710 | 630 710 800 | | | 856 954 1065 | | | 750 850 950 | 950 1050 1200 | C C C | 3RW44 53-□BC□5 3RW44 54-□BC□5 3RW44 55-□BC□5 | 1 1 1 | 1 unit 1 unit 1 unit | 131 131 131 | 50.00 50.00 50.00 |
| 1351 1524 1680 | | 800 900 1000 | 900 1000 1200 | | | 1200 1351 1472 | | | 1050 1200 1300 | 1350 1500 1650 | CCC | 3RW44 56-□BC□5 3RW44 57-□BC□5 3RW44 58-□BC□5 | 1 1 1 | 1 unit 1 unit 1 unit | 131 131 131 | 50.00 50.00 50.00 |
| 1864 2103 | | 1100 1200 | 1350 1500 | | | 1680 1864 | | | 1500 1700 | 1900 2100 | C | 3RW44 65-□BC□5 3RW44 66-□BC□5 | 1 1 | 1 unit 1 unit | 131 131 | 78.00 78.00 |

- With screw terminals

Order No. supplement for the rated control supply voltage $U_s^{(3)}$

- 115 V AC
- 230 V AC
- $^{1)}$ In the selection table, the unit rated current $I_{\rm e}$ refers to the induction motor's rated operational current in the inside-delta circuit. The actual current of the device is approx. 58 % of this value.
- 2) Soft starter with screw terminals: 3RW44 2. ... 3RW44 4. Delivery time class A 3RW44 5. ... 3RW44 6. Delivery time class B.
- Control by way of the internal $24\ V$ DC supply and direct control by means of PLC possible.

Note:

Soft starter selection depends on the rated motor current.

Please observe the notes for the selection of soft starters on Page 4/7.

The 3RW44 solid-state soft starters are designed for normal starting (Class 10). (Inertia load of the overall operating mechanism $J_{\rm Load}$ <10 × $J_{\rm Motor}$; starting current 350 % × $I_{\rm e}$ for 20 s or similar load). For any other conditions of use, the devices should be selected using the Win-Soft Starter selection and simulation program. For information about rated currents for ambient temperatures > 40 °C and switching frequency, see "Technical specifications".

3RW44 Soft Starters for High-Feature Applications

3RW44

SIRIUS 3RW44 for heavy starting (CLASS 20) in inside-delta circuit

SIRIUS 3RW Soft Starters











50.000

78.000

78.000

78.000

78.000

1 unit

1 unit

1 unit

1 unit

131

131

| Transport of the state of the s | | | The state of the s | | | MATTERS SEED | | | | | | | | | | | | |
|--|-------|-------|--|-------|---------------------------------|---|-------|-------|-------|-------|---|----------------|--------------|----------------|--------|------------------|--------|--|
| 3RW44 27-1BC44 | | | 3RW44 36-6BC44 | | | 3RW44 47-6BC44 | | | | | 3 | RW44 58-6BC44 | | 3RW44 66-6BC44 | | | | |
| Ambient temperature 40 °C | | | | | Ambient temperature 50 °C | | | | | DT | Heavy starting (CLASS 20) in inside-delta circuit | | PU (UNIT, | PS* | PG | Weight per PU | | |
| Rated operational voltage $U_{\rm e}$ current $I_{\rm e}^{-1}$ | | | | | Rated operational current I_e | Rated power of induction motors for rated operational voltage $U_{\rm e}$ | | | | | | | SET, M) | | | approx. | | |
| | 230 V | 400 V | 500 V | 690 V | 1000 V | | 200 V | 230 V | 460 V | 575 V | | | rice PU | | | | | |
| Α | kW | kW | kW | kW | kW | А | hp | hp | hp | hp | | pei | FU | | | | kg | |
| Inside-delta circuit, rated operational voltage 200 460 V ²⁾ | | | | | | | | | | | | | | | | | | |
| 50 | 15 | 22 | | | | 45 | 10 | 15 | 30 | | > | 3RW44 23-□BC□4 | | 1 | 1 unit | 131 | 6.500 | |
| 62 | 18.5 | 30 | | | | 55 | 15 | 20 | 40 | | | 3RW44 24-□BC□4 | | 1 | 1 unit | 131 | 6.500 | |
| 81 | 22 | 45 | | | | 73 | 20 | 25 | 50 | | | 3RW44 25-□BC□4 | | 1 | 1 unit | 131 | 6.500 | |
| 99 | 30 | 55 | | | | 88 | 25 | 30 | 60 | | > | 3RW44 25-□BC□4 | | 1 | 1 unit | 131 | 6.500 | |
| 133 | 37 | 75 | | | | 118 | 30 | 40 | 75 | | | 3RW44 27-□BC□4 | | 1 | 1 unit | 131 | 6.500 | |
| Order No. supplement for connection types | | | | | | | | | | | | | | | | | | |
| With screw terminals With spring-type terminals 3 | | | | | | | | | | | | | | | | | | |
| 161 | 45 | 90 | | | | 142 | 40 | 50 | 100 | | В | 3RW44 34-□BC□4 | | 1 | 1 unit | 131 | 7.900 | |
| 196 | 55 | 110 | | | | 173 | 50 | 60 | 125 | | В | 3RW44 35-□BC□4 | | 1 | 1 unit | 131 | 7.900 | |
| 232 | 75 | 132 | | | | 203 | 60 | 75 | 150 | | В | 3RW44 36-□BC□4 | | 1 | 1 unit | 131 | 7.900 | |
| 281 | 90 | 160 | | | | 251 | 75 | 100 | 200 | | В | 3RW44 43-□BC□4 | | 1 | 1 unit | 131 | 11.500 | |
| 352 | 110 | 200 | | | | 312 | 100 | 125 | 250 | | В | 3RW44 44-□BC□4 | | 1 | 1 unit | 131 | 11.500 | |
| 433 | 132 | 250 | | | | 372 | 125 | 150 | 300 | | В | 3RW44 45-□BC□4 | | 1 | 1 unit | 131 | 11.500 | |
| 542 | 160 | 315 | | | | 485 | 150 | 200 | 400 | | В | 3RW44 47-□BC□4 | | 1 | 1 unit | 131 | 11.500 | |
| 617 | 200 | 355 | | | | 546 | 150 | 200 | 450 | | В | 3RW44 47-□BC□4 | | 1 | 1 unit | 131 | 11.500 | |
| 748 | 250 | 400 | | | | 667 | 200 | 250 | 600 | | С | 3RW44 53-□BC□4 | | 1 | 1 unit | 131 | 50.000 | |
| 954 | 315 | 560 | | | | 856 | 300 | 350 | 750 | | С | 3RW44 53-□BC□4 | | 1 | 1 unit | 131 | 50.000 | |
| 1065 | 355 | 630 | | | | 954 | 350 | 400 | 850 | | С | 3RW44 55-□BC□4 | | 1 | 1 unit | 131 | 50.000 | |
| | | | | | | | | | | | | | | | | | | |

Order No. supplement for connection types

710

900

1000

· With spring-type terminals

500

560

Order No. supplement for the rated control supply voltage $U_s^{(3)}$

1065

1200

1351

1472

1680

450

500

600

650

750

450

550

650

950

1050

1200

1300

1500

С

C

С

• 115 V AC

1200

1351

1524

1680

• 230 V AC

Note:

Soft starter selection depends on the rated motor current.

Please observe the notes for the selection of soft starters on Page 4/7.

The 3RW44 solid-state soft starters are designed for normal starting (Class 10). (Inertia load of the overall operating mechanism J_{Load} <10 x J_{Motor} ; starting current 350 % x I_e for 20 s or similar load). For any other conditions of use, the devices should be selected using the Win-Soft Starter selection and simulation program. For information about rated currents for ambient tem3RW44 57-□BC□4

3RW44 65-□BC□4

3RW44 65-□BC□4

3RW44 65-□BC□4

3RW44 66-□BC□4

6

peratures > 40 °C and switching frequency, see "Technical specifications".

¹⁾ In the selection table, the unit rated current I_{e} refers to the induction motor's rated operational current in the inside-delta circuit. The actual current of the device is approx. 58 % of this value

²⁾ 3RW44 2 soft starters. ... 3RW44 4. with screw terminals: delivery time class ► (preferred type).

³⁾ Control by way of the internal 24 V DC supply and direct control by means of PLC possible.

3RW44 Soft Starters for High-Feature Applications

3RW44

| Ambient | Ambient temperature 40 °C Rated Rated power of induction motors for | | | | Ambient | temper | ature 5 | 0 °C | | DT | Heavy starting (CLASS 2 | 0) | PU | PS* | PG | Weight | |
|--------------------------------------|---|----------------------|---------|---------|---------|---------------------------------|---------|--------------------|------------------|-------|-------------------------|-------------------------|-------|----------------------|--------|--------|-------------------|
| Rated operational current $I_e^{1)}$ | | l power operation | | | | Rated operational current I_e | | s for rat | of inducted oper | | | in inside-delta circuit | | (UNIT, SET, M) | | | per PU approx. |
| | 230 V | 400 V | 500 V | 690 V | 1000 V | | 200 V | 230 V | 460 V | 575 V | | | Price | | | | |
| Α | kW | kW | kW | kW | kW | Α | hp | hp | hp | hp | | pe | er PU | | | | kg |
| Inside | -delta c | ircuit, | rated | operat | ional v | oltage 4 | 00 6 | 600 V ² |) | | | | | | | | |
| 50 | | 22 | 30 | | | 45 | | | 30 | 40 | Α | 3RW44 23-□BC□5 | | 1 | 1 unit | 131 | 6.500 |
| 62 | | 30 | 37 | | | 55 | | | 40 | 50 | Α | 3RW44 24-□BC□5 | | 1 | 1 unit | 131 | 6.500 |
| 81 | | 45 | 45 | | | 73 | | | 50 | 60 | Α | 3RW44 25-□BC□5 | | 1 | 1 unit | 131 | 6.500 |
| 99 | | 55 | 55 | | | 88 | | | 60 | 75 | Α | 3RW44 25-□BC□5 | | 1 | 1 unit | 131 | 6.500 |
| 133 | | 75 | 90 | | | 118 | | | 75 | 100 | Α | 3RW44 27-□BC□5 | | 1 | 1 unit | 131 | 6.500 |
| Order N | • • • | | for con | nection | 1 types | | | | | | | | | | | | |
| • With s | crew teri pring-typ | | nals | | | | | | | | | 1 3 | | | | | |
| 161 | | 90 | 110 | | | 142 | | | 100 | 125 | В | 3RW44 34-□BC□5 | | 1 | 1 unit | 131 | 7.900 |
| 196 | | 110 | 132 | | | 173 | | | 125 | 150 | В | 3RW44 35-□BC□5 | | 1 | 1 unit | 131 | 7.900 |
| 232 | | 132 | 160 | | | 203 | | | 150 | 200 | В | 3RW44 36-□BC□5 | | 1 | 1 unit | 131 | 7.900 |
| 281 | | 160 | 200 | | | 251 | | | 200 | 250 | В | 3RW44 43-□BC□5 | | 1 | 1 unit | 131 | 11.500 |
| 352 | | 200 | 250 | | | 312 | | | 250 | 300 | В | 3RW44 44-□BC□5 | | 1 | 1 unit | 131 | 11.500 |
| 433 | | 250 | 315 | | | 372 | | | 300 | 350 | В | 3RW44 45-□BC□5 | | 1 | 1 unit | 131 | 11.500 |
| 542 | | 315 | 355 | | | 485 | | | 400 | 500 | В | 3RW44 47-□BC□5 | | 1 | 1 unit | 131 | 11.500 |
| 617 | | 355 | 450 | | | 546 | | | 450 | 600 | В | 3RW44 47-□BC□5 | | 1 | 1 unit | 131 | 11.500 |
| 748 | | 400 | 500 | | | 667 | | | 600 | 750 | С | 3RW44 53-□BC□5 | | 1 | 1 unit | 131 | 50.000 |
| 954 | | 560 | 630 | | | 856 | | | 750 | 950 | С | 3RW44 53-□BC□5 | | 1 | 1 unit | 131 | 50.000 |
| 1065 | | 630 | 710 | | | 954 | | | 850 | 1050 | С | 3RW44 55-□BC□5 | | 1 | 1 unit | 131 | 50.000 |
| 1200 | | 710 | 800 | | | 1065 | | | 950 | 1200 | С | 3RW44 57-□BC□5 | | 1 | 1 unit | 131 | 50.000 |
| 1351 | | 800 | 900 | | | 1200 | | | 1050 | 1350 | С | 3RW44 65-□BC□5 | | 1 | 1 unit | 131 | 78.000 |
| 1524 | | 900 | 1000 | | | 1351 | | | 1200 | 1500 | С | 3RW44 65-□BC□5 | | 1 | 1 unit | 131 | 78.000 |
| 1680 | | 1000 | 1200 | | | 1472 | | | 1300 | 1650 | С | 3RW44 65-□BC□5 | | 1 | 1 unit | 131 | 78.000 |
| | | | | | | 1680 | | | 1500 | 1900 | С | 3RW44 66-□BC□5 | | 1 | 1 unit | 131 | 78.000 |

Order No. supplement for connection types

- With spring-type terminalsWith screw terminals

Order No. supplement for the rated control supply voltage $U_s^{(3)}$

- 115 V AC
- $^{\rm 1)}$ In the selection table, the unit rated current $I_{\rm e}$ refers to the induction motor's rated operational current in the inside-delta circuit. The actual current of the device is approx. 58 % of this value.
- ²⁾ Soft starter with screw terminals: 3RW44 2. ... 3RW44 4. Delivery time class A 3RW44 5. ... 3RW44 6. Delivery time class B.
- 3) Control by way of the internal 24 V DC supply and direct control by means of PLC possible.

Soft starter selection depends on the rated motor current.

Please observe the notes for the selection of soft starters on Page 4/7.

The 3RW44 solid-state soft starters are designed for normal starting (Class 10). (Inertia load of the overall operating mechanism $J_{\rm Load}$ <10 x $J_{\rm Motor}$; starting current 350 % x $I_{\rm e}$ for 20 s or similar load). For any other conditions of use, the devices should be selected using the Win-Soft Starter selection and simulation program. For information about rated currents for ambient temperatures > 40 °C and switching frequency, see "Technical specifications".

3RW44 Soft Starters for High-Feature Applications

3RW44

SIRIUS 3RW44 for very heavy starting (CLASS 30) in inside-delta circuit











50.000

78.000

78.000

78.000

78.000

1 unit

1 unit

1 unit

131

131

| | The second second | | | | and a | | | | - | | | | , | | | | |
|---|-------------------|-----------|----------|----------------|---------|---------------------------------------|-------------------|--------------------|----------|---------|-------------|---------------------------------------|-----------------|----------------------|--------|-----|-------------------|
| 3RW44 27 | 7-1BC4 | 4 | 3RW | 44 36-6 | BC44 | | 3RW44 | 47-6BC | 44 | | 3 | RW44 58-6BC44 | | 3RW44 | 66-6BC | 44 | |
| Ambient t | empera | ature 40 | °C | | | Ambient | tempera | ature 50 | °C | | DT | Very heavy starting | | PU | PS* | PG | Weight |
| Rated operational current $I_e^{1)}$ | rated | power o | nal volt | age <i>U</i> e | | Rated operational current $I_{\rm e}$ | motors voltage | Ü | ed opera | ational | | (CLASS 30) in inside-delta circuit | | (UNIT, SET, M) | | | per PU approx. |
| | 230 V | 400 V | 500 V | 690 V | 1000 V | | 200 V | 230 V | 460 V | 575 V | | Order No. | Price per PU | | | | |
| Α | kW | kW | kW | kW | kW | А | hp | hp | hp | hp | | | per Pu | | | | kg |
| Inside-c | lelta ci | ircuit, I | rated | operat | ional v | oltage 2 | 00 4 | 60 V ²⁾ | | | | | | | | | |
| 50 | 15 | 22 | | | | 45 | 10 | 15 | 30 | | > | 3RW44 23-□BC□4 | | 1 | 1 unit | 131 | 6.500 |
| 62 | 18.5 | 30 | | | | 55 | 15 | 20 | 40 | | | 3RW44 24-□BC□4 | | 1 | 1 unit | 131 | 6.500 |
| 81 | 22 | 45 | | | | 73 | 20 | 25 | 50 | | | 3RW44 25-□BC□4 | | 1 | 1 unit | 131 | 6.500 |
| 99 | 30 | 55 | | | | 88 | 25 | 30 | 60 | | > | 3RW44 25-□BC□4 | | 1 | 1 unit | 131 | 6.500 |
| 133 | 37 | 75 | | | | 118 | 30 | 40 | 75 | | | 3RW44 27-□BC□4 | | 1 | 1 unit | 131 | 6.500 |
| Order No | . suppl | ement f | or con | nectior | 1 types | • | | | | | | | | | | | |
| With scrWith spr | | | nals | | | | | | | | | 1 3 | | | | | |
| 161 | 45 | 90 | | | | 142 | 40 | 50 | 100 | | В | 3RW44 35-□BC□4 | | 1 | 1 unit | 131 | 7.900 |
| 196 | 55 | 110 | | | | 173 | 50 | 60 | 125 | | В | 3RW44 36-□BC□4 | | 1 | 1 unit | 131 | 7.900 |
| 232 | 75 | 132 | | | | 203 | 60 | 75 | 150 | | В | 3RW44 43-□BC□4 | | 1 | 1 unit | 131 | 11.500 |
| 281 | 90 | 160 | | | | 251 | 75 | 100 | 200 | | В | 3RW44 43-□BC□4 | | 1 | 1 unit | 131 | 11.500 |
| 352 | 110 | 200 | | | | 312 | 100 | 125 | 250 | | В | 3RW44 45-□BC□4 | | 1 | 1 unit | 131 | 11.500 |
| 433 | 132 | 250 | | | | 372 | 125 | 150 | 300 | | В | 3RW44 47-□BC□4 | | 1 | 1 unit | 131 | 11.500 |
| 542 | 160 | 315 | | | | 485 | 150 | 200 | 400 | | С | 3RW44 53-□BC□4 | | 1 | 1 unit | 131 | 50.000 |
| 617 | 200 | 355 | | | | 546 | 150 | 200 | 450 | | С | 3RW44 53-□BC□4 | | 1 | 1 unit | 131 | 50.000 |
| 748 | 250 | 400 | | | | 667 | 200 | 250 | 600 | | С | 3RW44 53-□BC□4 | | 1 | 1 unit | 131 | 50.000 |
| 954 | 315 | 560 | | | | 856 | 300 | 350 | 750 | | С | 3RW44 55-□BC□4 | | 1 | 1 unit | 131 | 50.000 |
| | | | | | | 1 | | | | | | | | | | | |

Order No. supplement for connection types

630

800

900

• With spring-type terminals

450

500

With screw terminals

Order No. supplement for the rated control supply voltage $U_s^{(3)}$

954

1065

1200

1351

1472

350

350

450

450

550

400

450

500

600

650

850

950

1050

1200

1300 --

С

С

• 115 V AC

1065

1200

1351

1524

• 230 V AC

Note:

Soft starter selection depends on the rated motor current.

Please observe the notes for the selection of soft starters on Page 4/7.

The 3RW44 solid-state soft starters are designed for normal starting (Class 10). (Inertia load of the overall operating mechanism $J_{l,oad}$ <10 x J_{Motor} ; starting current 350 % x I_e for 20 s or similar load). For any other conditions of use, the devices should be selected using the Win-Soft Starter selection and simulation program. For information about rated currents for ambient tem-



3RW44 58-□BC□4

3RW44 65-□BC□4

3RW44 65-□BC□4

3RW44 65-□BC□4

3RW44 66-□BC□4

6

peratures > 40 °C and switching frequency, see "Technical specifications".

 $^{^{\}rm 1)}$ In the selection table, the unit rated current $I_{\rm e}$ refers to the induction motor's rated operational current in the inside-delta circuit. The actual current of the device is approx. 58 % of this value.

³⁾ Control by way of the internal 24 V DC supply and direct control by means of PLC possible.

3RW44 Soft Starters for High-Feature Applications

3RW44

| Ambient t | tempera | ature 40 | °C | | | Ambient | tempe | rature 5 | 0 °C | | DT | Very heavy starting | | PU | PS* | PG | Weight |
|--------------------------------------|-------------|-------------|-------------|-----------------|--------------|--|-----------------|----------------------------|--------------|----------|----|---------------------------------------|-----------------|----------------------|--------|------------|-------------------|
| Rated operational current $I_e^{1)}$ | | operation | onal voli | tage <i>U</i> e | | opera- tional current $I_{\rm e}$ | motor voltag | s for rat ge <i>U</i> e | of induction | rational | | (CLASS 30) in inside-delta circuit | | (UNIT, SET, M) | | | per PU approx. |
| ^ | 230 V kW | 400 V kW | 500 V kW | 690 V kW | 1000 V kW | | 200 V | : | | 575 V | | Order No. | Price per PU | | | | Les |
| A | | | | | | A oltage 4 | hp | hp | hp | hp | | | p | | | | kg |
| | | | 30 | | lonai v | 45 | | OUU V | | 40 | ^ | 3RW44 23-□BC□5 | | 1 | 4 | 101 | 0.500 |
| 50 | | 22 | | | | _ | | | 30 | 40 | A | | | | 1 unit | 131 | 6.500 |
| 62 | | 30 | 37 | | | 55 73 | | | 40 | 50 | A | 3RW44 24-□BC□5 | | 1 | 1 unit | 131 | 6.500 |
| 81 99 | | 45 55 | 45 55 | | | 73 88 | | | 50 60 | 60 75 | A | 3RW44 25-□BC□5 3RW44 25-□BC□5 | | | 1 unit | 131 131 | 6.500 6.500 |
| | | 55 75 | | | | | | | | | A | | | | 1 unit | | |
| 133 | | | 90 | | | 118 | | | 75 | 100 | Α | 3RW44 27-□BC□5 | | 1 | 1 unit | 131 | 6.500 |
| • With sc • With sp | rew terr | ninals | | nection | ı types | | | | | | | 1 3 | | | | | |
| 161 | | 90 | 110 | | | 142 | | | 100 | 125 | В | 3RW44 35-□BC□5 | | 1 | 1 unit | 131 | 7.900 |
| 196 | | 110 | 132 | | | 173 | | | 125 | 150 | В | 3RW44 36-□BC□5 | | 1 | 1 unit | 131 | 7.900 |
| 232 | | 132 | 160 | | | 203 | | | 150 | 200 | В | 3RW44 43-□BC□5 | | 1 | 1 unit | 131 | 11.500 |
| 281 | | 160 | 200 | | | 251 | | | 200 | 250 | В | 3RW44 43-□BC□5 | | 1 | 1 unit | 131 | 11.500 |
| 352 | | 200 | 250 | | | 312 | | | 250 | 300 | В | 3RW44 45-□BC□5 | | 1 | 1 unit | 131 | 11.500 |
| 433 | | 250 | 315 | | | 372 | | | 300 | 350 | В | 3RW44 47-□BC□5 | | 1 | 1 unit | 131 | 11.500 |
| 542 | | 315 | 355 | | | 485 | | | 400 | 500 | С | 3RW44 53-□BC□5 | | 1 | 1 unit | 131 | 50.000 |
| 617 | | 355 | 450 | | | 546 | | | 450 | 600 | С | 3RW44 53-□BC□5 | | 1 | 1 unit | 131 | 50.000 |
| 748 | | 400 | 500 | | | 667 | | | 600 | 750 | С | 3RW44 53-□BC□5 | | 1 | 1 unit | 131 | 50.000 |
| 954 | | 560 | 630 | | | 856 | | | 750 | 950 | С | 3RW44 55-□BC□5 | | 1 | 1 unit | 131 | 50.000 |
| 1065 | | 630 | 710 | | | 954 | | | 850 | 1050 | С | 3RW44 58-□BC□5 | | 1 | 1 unit | 131 | 50.000 |
| 1200 | | 710 | 800 | | | 1065 | | | 950 | 1200 | С | 3RW44 65-□BC□5 | | 1 | 1 unit | 131 | 78.000 |
| 1351 | | 800 | 900 | | | 1200 | | | 1050 | 1350 | С | 3RW44 65-□BC□5 | | 1 | 1 unit | 131 | 78.000 |
| 1524 | | 900 | 1000 | | | 1351 | | | 1200 | 1500 | С | 3RW44 65-□BC□5 | | 1 | 1 unit | 131 | 78.000 |
| | | | | | | 1472 | | | 1300 | 1650 | С | 3RW44 66-□BC□5 | | 1 | 1 unit | 131 | 78.000 |

Order No. supplement for connection types

- With spring-type terminals
- With screw terminals

Order No. supplement for the rated control supply voltage $U_s^{(3)}$

- 115 V AC
- 230 V AC
- $^{1)}\,$ In the selection table, the unit rated current $I_{\rm e}$ refers to the induction motor's rated operational current in the inside-delta circuit. The actual current of the device is approx. 58 % of this value.
- 2) Soft starter with screw terminals: 3RW44 2. ... 3RW44 4. Delivery time class A 3RW44 5. ... 3RW44 6. Delivery time class B.
- 3) Control by way of the internal 24 V DC supply and direct control by means

Soft starter selection depends on the rated motor current.

Please observe the notes for the selection of soft starters on

The 3RW44 solid-state soft starters are designed for normal starting (Class 10). (Inertia load of the overall operating mechanism $J_{\rm Load}$ <10 x $J_{\rm Motor}$; starting current 350 % x $I_{\rm e}$ for 20 s or similar load). For any other conditions of use, the devices should be selected using the Win-Soft Starter selection and simulation program. For information about rated currents for ambient temperatures > 40 °C and switching frequency, see "Technical specifications".

SIRIUS 3RW Soft Starters 3RW44 Soft Starters for High-Feature Applications

3RW44

| - | | | | | | | | | |
|---|---|---|---|---|---|---|----|---|---|
| л | 0 | ~ | 0 | 0 | 0 | 0 | ri | 0 | c |
| | | | | | | | | | |

| Accessories | | | | | | | | | |
|--|--|--|----------|--------------------------------------|--------|----------------|------------------|------------|-------------------|
| | For | Version | DT | Order No. | Price | PU | PS* | PG | Weight |
| | soft starters | | | | per PU | (UNIT, SET, | | | per PU approx. |
| | | | | | | M) | | | αρρίολ. |
| | Туре | | | | | | | | kg |
| Soft Starter ES 2007 | PC communi | cation program ²⁾ | | | | | | | |
| No. | | S 2007 Basic | | | | | | | |
| ter to the land between 8 to the land | • | se for one user | | | | | | | |
| Septimental and the control of the c | | e and documentation on CD, German/English/French), | | | | | | | |
| | | n through system interface | | | | | | | |
| | License key | on USB stick, Class A, including CD | В | 3ZS1 313-4CC10-0YA5 | | 1 | 1 unit | 131 | 0.230 |
| | Soft Starter E | S 2007 Standard | | | | | | | |
| | | se for one user | | | | | | | |
| | • | e and documentation on CD, | | | | | | | |
| | 3 languages (| German/English/French), | | | | | | | |
| | | n through system interface on USB stick, Class A, including CD | В | 3ZS1 313-5CC10-0YA5 | | 1 | 1 unit | 131 | 0.230 |
| | | S 2007 Premium | D | 3231 313-300 10-01A3 | | 1 | 1 UIIII | 131 | 0.230 |
| | | se for one user | | | | | | | |
| | • | e and documentation on CD, | | | | | | | |
| | | German/English/French), in through system interface or PROFIBUS | | | | | | | |
| | | on USB stick, Class A, including CD | В | 3ZS1 313-6CC10-0YA5 | | 1 | 1 unit | 131 | 0.230 |
| PC cables | LIGOTIOC REY | c ccb didit, clade A, moldanig ob | <u> </u> | 5_51 010 00010 01A0 | | ' | i dilit | .01 | 0.200 |
| | For PC/PG co | ommunication with SIRIUS 3RW44 soft | Α | 3UF7 940-0AA00-0 | | 1 | 1 unit | 131 | 0.150 |
| | starters | | | | | | | | |
| | through the sy | stem interface, for connecting to face of the PC/PG | | | | | | | |
| | | 1400 01 110 1 071 4 | | | | | | | |
| | | | | | | | | | |
| 3UF7 940-0AA00-0 | | | | | | | | | |
| USB/serial adapters | | | | | | | | | |
| | | ng the PC cable to the USB interface of a | В | 3UF7 946-0AA00-0 | | 1 | 1 unit | 131 | 0.150 |
| | PC | 1 | | | | | | | |
| | | nd, in conjunction with 3RW44 soft starter, DDE pro 3UF7, 3RK3 modular safety sys- | | | | | | | |
| | | ECOFAST/ET 200pro motor starters, AS-i ; AS-i analyzer | | | | | | | |
| PROFIBUS communi | | | | | | | | | |
| 6 | | pe plugged into the soft starters for inte- | Α | 3RW49 00-0KC00 | | 1 | 1 unit | 131 | 0.320 |
| | grating the sta | arters in the PROFIBUS network with DPV1 | | | | | | | |
| | | soft starter has only DPV0 slave functional- | | | | | | | |
| | ity. | | | | | | | | |
| | | | | | | | | | |
| | | | | | | | | | |
| 0DW40 00 01/000 | | | | | | | | | |
| 3RW49 00-0KC00 External display and | operator med | dule | | | | | | | |
| External display allu | • | and operating the functions provided by | ▶ | 3RW49 00-0AC00 | | 1 | 1 unit | 131 | 0.320 |
| BROW SAW SAW | the soft starter | r using an externally mounted display and | | | | <u>'</u> | . uillt | 101 | 3.020 |
| | | ule in degree of protection IP54 ontrol cabinet door) | | | | | | | |
| 100 No. 100 No | Connection c | <u>'</u> | | | | | | | |
| | | ce interface (serial) of the 3RW44 soft | | | | | | | |
| 3RW49 00-0AC00 | starter to the e Length 0.5 n | external display and operator module n. flat | Α | 3UF7 932-0AA00-0 | | 1 | 1 unit | 131 | 0.020 |
| | Length 0.5 n | n, round | Α | 3UF7 932-0BA00-0 | | 1 | 1 unit | 131 | 0.050 |
| | Length 1.0 n Length 2.5 n | | A A | 3UF7 937-0BA00-0 3UF7 933-0BA00-0 | | 1 1 | 1 unit 1 unit | 131 131 | 0.100 0.150 |
| Box terminal blocks | | | | | | | - | | |
| | Box terminal | blocks | | | | | | | |
| | 3RW44 2. | Included in the scope of supply | | | | | | | |
| P-2 P-2 1 | 3RW44 3. | Up to 70 mm² Up to 120 mm² | | 3RT19 55-4G 3RT19 56-4G | | 1 | 1 unit 1 unit | 101 101 | 0.230 0.260 |
| | 3RW44 4. | • Up to 240 mm ² | | 3RT19 66-4G | | 1 | 1 unit | 101 | 0.260 |
| | J. 17777 7. | OP 10 11 11 11 | | J.11 10 00 TG | | ' | , uillt | 101 | 5.070 |
| 3RT19 | | | | | | | | | |
| | | | | | | | | | |

SIRIUS 3RW Soft Starters 3RW44 Soft Starters for High-Feature Applications

3RW44

| | For soft starters | Version | DT | Order No. Pric | e PU J (UNIT, SET, M) | PS* | PG | Weight per PU approx. |
|------------------------------|-----------------------------------|---|-------------|---|--------------------------------|-----------|--------|-----------------------------|
| | Туре | | | | | | | kg |
| Covers for soft starte | ers | | | | | | | |
| | Terminal cove | ers for box terminals | | | | | | |
| | | ch protection to be fitted at the box termi- equired per device) | | | | | | |
| | 3RW44 2. and 3RW44 3. | | • | 3RT19 56-4EA2 | 1 | 1 unit | 101 | 0.030 |
| | 3RW44 4. | | > | 3RT19 66-4EA2 | 1 | 1 unit | 101 | 0.040 |
| - | tions 3RW44 2. and 3RW44 3. | ers for cable lugs and busbar connec- | • | 3RT19 56-4EA1 | 1 | 1 unit | 101 | 0.070 |
| 3RT19.6-4EA1 | 3RW44 4. | | • | 3RT19 66-4EA1 | 1 | 1 unit | 101 | 0.130 |
| Operating instruction | าร ^{า)} | | | | | | | |
| | for 3RW44 sof | t starters | | 3ZX10 12-0RW44-1AA1 | | | | |
| 1) The operating instruction | ns are included | in the scope of supply. | | nore information on the Soft Starte Configuration with SIRIUS" | ES softwa | are see C | hapter | "Planning |
| Spare parts | | | | | | | | |
| | For soft starters | Version | DT | | e PU J (UNIT, SET, M) | PS* | PG | Weight per PU approx. |

| | For soft starters | Version | DT | Order No. | Price per PU | PU (UNIT, SET, M) | PS* | PG | Weight per PU approx. |
|-------|-------------------------|----------------------|-------------|----------------------------------|-----------------|----------------------------|------------------|------------|-----------------------|
| | Туре | | | | | | | | kg |
| Fans | | | | | | | | | |
| | Fans | | | | | | | | |
| | 3RW442. and 3RW443. | 115 V AC 230 V AC | > | 3RW49 36-8VX30 3RW49 36-8VX40 | | 1 1 | 1 unit 1 unit | 131 131 | 0.300 0.300 |
| | 3RW44 4. | 115 V AC 230 V AC | > | 3RW49 47-8VX30 3RW49 47-8VX40 | | 1 1 | 1 unit 1 unit | 131 131 | 0.500 0.500 |
| 3RW49 | 3RW445. and 3RW4461) | 115 V AC 230 V AC | > | 3RW49 57-8VX30 3RW49 57-8VX40 | | 1 1 | 1 unit 1 unit | 131 131 | 0.800 0.800 |
| | 3RW44 6. ²⁾ | 115 V AC 230 V AC | > | 3RW49 66-8VX30 3RW49 66-8VX40 | | 1 1 | 1 unit 1 unit | 131 131 | 0.300 0.300 |

^{1) 3}RW44 6. mounting on output side.

²⁾ For mounting on front side.

3RW44 Soft Starters for High-Feature Applications

3RW44

More information

Application examples for normal starting (Class 10)

Normal starting Class 10 (up to 20 s with 350 % $I_{\rm n\ motor}$). The soft starter rating can be selected to be as high as the rating of the motor used

| Application | | Conveyor belt | Roller conveyor | Compressor | Small fans ¹⁾ | Pump | Hydraulic pump |
|---|--------|-------------------------|-------------------------|---------------------------------------|--------------------------------|-------------------------|-------------------------|
| Starting parameters | | | | | | | |
| Voltage ramp and current limiting Starting voltage Starting time Current limit value | % S | 70 10 Deactivated | 60 10 Deactivated | 50 10 4 × <i>I</i> _M | 30 10 4 × I _M | 30 10 Deactivated | 30 10 Deactivated |
| Torque rampStarting torqueEnd torqueStarting time | | 60 150 10 | 50 150 10 | 40 150 10 | 20 150 10 | 10 150 10 | 10 150 10 |
| Breakaway pulse | | Deactivated (0 ms) | Deactivated (0 ms) | Deactivated (0 ms) | Deactivated (0 ms) | Deactivated (0 ms) | Deactivated (0 ms) |
| Ramp-down mode | | Smooth ramp- down | Smooth ramp- down | Free ramp-down | Free ramp-down | Pump ramp-down | Free ramp-down |

Application examples for heavy starting (Class 20)

Heavy starting Class 20 (up to 40 s with 350 % $I_{\rm n\ motor}$), The soft starter has to be selected one performance class higher than the motor used

| Application | | Stirrer | Centrifuge | Milling machine |
|---|--------|---------------------------------------|---------------------------------------|---------------------------------------|
| Starting parameters | | | | |
| Voltage ramp and current limiting Starting voltage Starting time Current limit value | % S | 30 30 4 × <i>I</i> _M | 30 30 4 × <i>I</i> _M | 30 30 4 × <i>I</i> _M |
| Torque rampStarting torqueEnd torqueStarting time | | 30 150 30 | 30 150 30 | 30 150 30 |
| Breakaway pulse | | Deactivated (0 ms) | Deactivated (0 ms) | Deactivated (0 ms) |
| Ramp-down mode | | Free ramp-down | Free ramp-down | Free ramp-down or DC braking |

Application examples for very heavy starting (Class 30)

Very heavy starting Class 30 (up to 60 s with 350 % $I_{\rm n\ motor}$). The soft starter has to be selected two performance classes higher than the motor used

| Application | | Large fans ²⁾ | Mill | Breakers | Circular saw/bandsaw |
|---|--------|--------------------------------|--------------------------------|---------------------------------------|--------------------------------|
| Starting parameters | | | | | |
| Voltage ramp and current limiting Starting voltage Starting time Current limit value | % S | 30 60 4 × I _M | 50 60 4 × I _M | 50 60 4 × <i>I</i> _M | 30 60 4 × I _M |
| Torque rampStarting torqueEnd torqueStarting time | | 20 150 60 | 50 150 60 | 50 150 60 | 20 150 60 |
| Breakaway pulse | | Deactivated (0 ms) | 80 %; 300 ms | 80 %; 300 ms | Deactivated (0 ms) |
| Ramp-down mode | | Free ramp-down | Free ramp-down | Free ramp-down | Free ramp-down |

¹⁾ The mass inertia of the fan is <10 times the mass inertia of the motor

These tables present sample set values and device sizes. They are intended only for the purposes of information and are not binding. The set values depend on the application in question and must be optimized during commissioning.

The soft starter dimensions should be checked where necessary with the Win-Soft Starter software or with the help of Technical Assistance.

The mass inertia of the fan is \geq 10 times the mass inertia of the motor

3RW44 Soft Starters for High-Feature Applications

3RW44

Circuit concept

The SIRIUS 3RW44 soft starters can be operated in two different types of circuit.

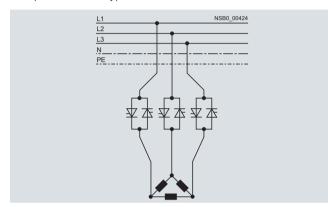
• Inline circuit

The controls for isolating and protecting the motor are simply connected in series with the soft starter. The motor is connected to the soft starter with three cables.

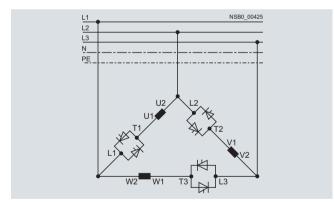
Inside-delta circuit

The wiring is similar to that of wye-delta starters. The phases of the soft starter are connected in series with the individual motor windings. The soft starter then only has to carry the phase current, amounting to about 58 % of the rated motor current (conductor current).

Comparison of the types of circuit



Inline circuit: Rated current $I_{\rm e}$ corresponds to the rated motor current $I_{\rm n}$, 3 cables to the motor



Inside-delta circuit:

Rated current $I_{\rm e}$ corresponds to approx. 58 % of the rated motor current $I_{\rm n}$, 6 cables to the motor (as with wye-delta starters)

Which circuit?

Using the inline circuit involves the lowest wiring outlay. If the soft starter to motor connections are long, this circuit is preferable. With the inside-delta circuit there is double the wiring complexity but a smaller size of device can be used at the same rating.

Thanks to the choice of operating mode between the inline circuit and inside-delta circuit, it is always possible to select the most favorable solution.

The braking function is possible only in the inline circuit.

Configuration

The 3RW44 solid-state soft starters are designed for normal starting. In case of heavy starting or increased starting frequency, a larger device must be selected.

For long starting times it is recommended to have a PTC sensor in the motor. This also applies for the ramp-down modes smooth ramp-down, pump ramp-down and DC braking, because during the ramp-down time in these modes, an additional current loading applies in contrast to free ramp-down.

No capacitive elements are permitted in the motor feeder between the SIRIUS 3RW soft starter and the motor (e. g. no reactive-power compensation equipment). In addition, neither static systems for reactive-power compensation nor dynamic PFC (Power Factor Correction) must be operated in parallel during starting and ramp-down of the soft starter. This is important to prevent faults arising on the compensation equipment and/or the soft starter.

All elements of the main circuit (such as fuses and controls) should be dimensioned for direct starting, following the local short-circuit conditions. Fuses, controls and overload relays must be ordered separately.

A bypass contact system and solid-state overload relay are already integrated in the 3RW44 soft starter and therefore do not have to be ordered separately.

The harmonic component load for starting currents must be taken into consideration for the selection of motor starter protectors (selection of release).

Note:

When induction motors are switched on, voltage drops occur as a rule on starters of all types (direct starters, wye-delta starters, soft starters). The infeed transformer must always be dimensioned such that the voltage dip when starting the motor remains within the permissible tolerance. If the infeed transformer is dimensioned with only a small margin, it is best for the control voltage to be supplied from a separate circuit (independently of the main voltage) in order to avoid the potential switching off of the soft starter.

Device interface, PROFIBUS DP communication module, Soft Starter ES parameterizing and operating software

The 3RW44 electronic soft starters have a PC interface for communicating with the Soft Starter ES software or for connecting the external display and operator module. If the optional PROFIBUS communication module is used, the 3RW44 soft starter can be integrated in the PROFIBUS network and communicate using the GSD file or Soft Starter ES Premium software.

3RW44 Soft Starters for High-Feature Applications

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Manual for SIRIUS 3RW44

Besides containing all important information on configuring, commissioning and servicing, the manual also contains example circuits and the technical specifications for all devices.

Win-Soft Starter selection and simulation program

With this software, you can simulate and select all Siemens soft starters, taking into account various parameters such as mains properties, motor and load data, and special application requirements.

The software is a valuable tool, which makes complicated, lengthy manual calculations for determining the required soft starters superfluous.

The Win-Soft Starter selection and simulation program can be downloaded from:

www.siemens.com/softstarter > Software

You can find more information about soft starters on the Internet likewise at:

www.siemens.com/softstarter

Training course for SIRIUS soft starters (SD-SIRIUSO)

Siemens offers a 2-day training course on the SIRIUS solid-state soft starters to keep customers and own personnel up-to-date on configuring, commissioning and maintenance issues.

Please direct enquiries and applications to:

Training Center for Automation and Industrial Solution Gleiwitzer Strasse 555 D-90475 Nürnberg

Telephone: +49 911 895 3202 Telefax: +49 911 895 3275

E-mail: ingeborg.hoier@siemens.com www.siemens.com/sitrain-cd

General data

Overview

| Туре | Solid-Stat | e Relays | | Solid-State | Contactors | Function m | nodules | | | | |
|--|------------|----------|-----------------|------------------|-----------------|------------|------------|----------|-----------------|-------------------|-----------------|
| | Single-pha | ase | Three- phase | Single- phase | Three- phase | Converters | Load monit | toring | Heating current | Power controllers | Power regulator |
| | 22.5 mm | 45 mm | 45 mm | | | | Basic | Extended | monitoring | | |
| Usage | | | | | | | | | | | |
| Simple use of exist- ing solid-state relays | | 1 | | | | | | | | | |
| Complete unit "Ready to use" | | | | ✓ | ✓ | | | | | | |
| Space-saving | ✓ | | ✓ | ✓ | ✓ | ✓ | ✓ | | | | |
| Can be extended with modular function modules | ✓ | | 1) | / | 1) | | | | | | |
| Frequent switching and monitoring of loads and solid-state relays/solid-state contactors | | | | | | | 1 | ✓ | ✓ | √ | 1 |
| Monitoring of up to 6 partial loads | | | | | | | 1 | | 1 | ✓ | |
| Monitoring of more than 6 partial loads | | | | | | | | ✓ | | | |
| Control of the heat- ing power through an analog input | | | | | | 1 | | | | ✓ | ✓ |
| Power control | | | | | | | | | | | / |
| Startup | | | | | | | | | | | |
| Easy setting of set- point values with "Teach" button | | | | | | | ✓ | 1 | | ✓ | ✓ |
| "Remote Teach" input for setting set-points | | | | | - | | | | ✓ | | |
| Mounting | | | | | | | | | | | |
| Mounting onto mounting rails or mounting plates | | | | 1 | 1 | | | | | | |
| Can be snapped directly onto a solid- state relay or con- tactor | | | | | | ✓ | / | ✓ | ✓ | / | √ |
| For use with "Cool- plate" heat sink | ✓ | ✓ | 1 | | | | | | | | |
| Wiring | | | | | | | | | | | |
| Connection of load circuit as for con-trolgear | 1 | | 1 | 1 | 1 | | ✓ | ✓ | ✓ | ✓ | 1 |
| Connection of load circuit from above | | 1 | | | | | | | | | |

- ✓ Function is available
- ☐ Function is possible
- -- Function not available.

Benefits

Characteristics

- Considerable space savings thanks to a width of only 22.5 mm
- Variety of connection methods: Screw terminal, spring-type connection or ring terminal lug, there is no problem – they are all finger-safe
- Flexible for all applications with function modules for retrofitting
- · Possibility of fuseless short-circuit proof design

Advantages

- Saves time and costs with fast mounting and commissioning, short start-up times and easy wiring
- Extremely long life, low maintenance, rugged and reliable
- Space-saving and safe thanks to side-by-side mounting up to an ambient temperature of +60 °C
- Modular design: Standardized function modules and heat sinks can be used in conjunction with solid-state relays to satisfy individual requirements
- Safety due to lifelong, vibration-resistant and shock-resistant spring-type terminal connection method even under tough conditions

¹⁾ The converter can also be used with three-phase devices.

General data

Application

Applications

Example: Plastics processing industry

Thanks to their high switching endurance, SIRIUS solid-state switching devices are ideally suited for use in the control of electrical heat. This is because the more precise the temperature regulation process has to be, the higher the switching frequency. The accurate regulation of electrical heat is used for example in many processes in the plastics processing industry:

- Band heaters heat the extrudate to the correct temperature in plastic extruders
- Heat emitters heat plastic blanks to the correct temperature
- Heat drums dry plastic granules
- Heating channels keep molds at the correct temperature in order to manufacture different plastic parts without defects

The powerful SIRIUS solid-state relays and contactors can be used to control several heating loads at the same time. By using a load monitoring module the individual partial loads can easily be monitored, and in the event of a failure a signal is generated to be sent to the controller.

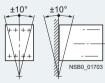
Use in fuseless load feeders

Short-circuit protection and line protection with miniature circuit breakers is easy to achieve with SIRIUS solid-state relays and solid-state contactors in comparison with designing load feeders with fuses. A special version of the solid-state contactors can be protected against damage in the case of a short-circuit with a miniature circuit breaker with type B tripping characteristic. This allows the low-cost and simple design of fuseless load feeders with full protection of the switchgear.

More information

Specification

| Туре | | 3RF20, 3RF21, 3RF23A,B,D | 3RF23C | 3RF22, 3RF24 |
|---|----------|---|--|---|
| General data | | | | |
| Ambient temperature • During operation, derating from 40 °C • During storage | °C °C | -25 + 60 -55 + 80 | | |
| Installation altitude | m | 0 1000; derating from 1000 ¹⁾ | | |
| Shock resistance acc. to IEC 60068-2-27 | g/ms | 15/11 | | |
| Vibration resistance acc. to IEC 60068-2-6 | g | 2 | | |
| Degree of protection | | IP20 | | |
| Insulation strength at 50/60 Hz (main/control circuit to floor) | V rms | 4000 | | |
| Electromagnetic compatibility (EMC) | | | | |
| Emitted interference | | | | |
| - Conducted interference voltage acc. to IEC 60947-4-3 | | Class A for industrial applications | Class A for industrial applications Class B for residential applications ²⁾ | Class A for industrial applications ³⁾ |
| Emitted, high-frequency interference voltage acc. to IEC 60947-4-3 | | Class A for industrial applications | Class A for industrial applications | Class A for industrial applications |
| Interference immunity | | | | |
| Electrostatic discharge acc. to IEC 61000-4-2 (corresponds to degree of severity 3) | kV | Contact discharge: 4; Air discharge: 8; Behavior criterion 2 | | |
| induced RF fields acc. to IEC 61000-4-6 | MHz | 0.15 80; 140 dBµV; behavior criterion 1 | | |
| - Burst acc. to IEC 61000-4-4 | kV | 2/5.0 kHz; behavior criterion 1 | | |
| - Surge acc. to IEC 61000-4-5 | kV | Conductor - Ground: 2; Conductor - Conductor: 1; Behavior criterion 2 | | |
| Permissible mounting positions | | +10° +10° | | |



- 1) Please contact Technical Assistance.
- 2) "Low Noise" version for residential, business and commercial applications up to 16 A, AC-51.
- 3) These products were built as Class A devices. The use of these devices in residential areas could result in lead in radio interference. In this case these may be required to introduce additional interference suppression measures.

Notes on integration in the load feeders

The SIRIUS solid-state switching devices are very easy to integrate into the load feeders thanks to their industrial connection method and design.

Particular attention must however be paid to the circumstances of the installation and ambient conditions, as the performance of the solid-state switching devices is largely dependent on these. Depending on the version, certain restrictions must be observed. Detailed information, for example in relation to solid-state contactors about the minimum spacing and to solid-state relays about the choice of heat sink, is given in the technical specifications (see manual) and the product data sheets.

For applications with a very large power requirement it is possible to use SIVOLT AC power controller. More information on the product range can be found in the Catalog DA 68 or in our Mall.

support.automation.siemens.com/WW/view/de/10862346

See ID: 10752358

Short-circuit and overload protection

Despite the rugged power semiconductors that are used, solidstate switching devices respond more sensitively to short-circuits in the load feeder. Consequently, special precautions have to be taken against destruction, depending on the type of design.

Siemens generally recommends using SITOR semiconductor protection fuses. These fuses also provide protection against destruction in the event of a short-circuit even when the solid-state contactors and solid-state relays are fully utilized.

General data

Alternatively, if there is lower loading, protection can also be provided by standard fuses or miniature circuit breakers. This protection is achieved by overdimensioning the solid-state switching devices accordingly. The technical specifications and the product data sheets contain details both about the solid-state fuse protection itself and about use of the devices with conventional protection equipment.

Electromagnetic compatibility (EMC)

The solid-state switching devices are suitable for interferencefree operation in industrial networks without further measures. If they are used in public networks, it may be necessary for conducted interference to be reduced by means of filters.

This does not include the solid-state contactors for resistive loads of the special type 3RF23..-.CA.. "Low Noise". These comply with the class B limit values up to a rated current of 16 A. If other versions are used, and at currents of over 16 A, standard filters can be used in order to comply with the limit values. The decisive factors when it comes to selecting the filters are essentially the current loading and the other parameters (operational voltage, design type, etc.) in the load feeder.

Suitable filters can be ordered from EPCOS AG. You can find more information on the Internet at:

www.epcos.com

Solid-State Relays

General data

Overview

Solid-State Relays

SIRIUS solid-state relays are suitable for surface mounting on existing cooling surfaces. Mounting is quick and easy, involving just two screws. The special technology of the power semiconductor ensures there is excellent thermal contact with the heat sink. Depending on the nature of the heat sink, the capacity reaches up to 88 A on resistive loads.

The solid-state relays are available in three different versions:

- 3RF21 single-phase solid-state relay with a width of 22.5 mm
- 3RF20 single-phase solid-state relay with a width of 45 mm
- 3RF22 three-phase solid-state relay with a width of 45 mm

The 3RF21 and 3RF22 solid-state relays can be expanded with various function modules to adapt them to individual applications

Version for resistive loads, "zero-point switching"

This standard version is often used for switching space heaters on and off.

Version for inductive loads, "instantaneous switching"

In this version the solid-state relay is specifically matched to inductive loads. Whether it is a matter of frequent actuation of the valves in a filling plant or starting and stopping small operating mechanisms in packet distribution systems, operation is carried out safely and noiselessly.

Special "Low noise" version

Thanks to a special control circuit, this special version can be used in public networks up to 16 A without any additional measures, such as interference suppressor filters. As a result, in terms of emitted interference, it conforms to limit value curve class B according to EN 60947-4-3.

Single-phase solid-state relays with a width of 22.5 mm

With its compact design and a width of just 22.5 mm, which stays the same even at currents of up to 88 A, the 3RF21 solid-state relay offers an ultra small footprint. The logical connection method, with the power infeed from above and load connection from below, ensures tidy installation in the control cabinet.

Single-phase solid-state relays with a width of 45 mm

The solid-state relays with a width of 45 mm provide for connection of the power supply lead and the load from above. This makes it easy to replace existing solid-state relays in existing arrangements. The connection of the control cable also saves space in much the same way as the 22.5 mm design, as it is simply plugged on.

Three-phase solid-state relays with a width of 45 mm

With its compact design and a width of just 45 m, which stays the same even at currents of up to 55 A, the 3RF22 solid-state relay offers an ultra small footprint. The logical connection method, with the power infeed from above and load connection from below, ensures tidy installation in the control cabinet.

The three-phase solid-state relays are available with

- two-phase control (suitable in particular for circuits without connection to the neutral conductor) and
- three-phase control (suitable for star circuits with connection to the neutral conductor or for applications in which the system requires all phases to be switched).

Selection notes

When selecting solid-state relays, in addition to information about the network, the load and the ambient conditions it is also necessary to know details of the planned design. The solid-state relays can only conform to their specific technical specifications if they are mounted with appropriate care on an adequately dimensioned heat sink.

The following procedure is recommended:

- Determine the rated current of the load and the mains voltage
- Select the relay design and choose a solid-state relay with higher rated current than the load
- Determine the thermal resistance of the proposed heat sink
- Check the correct relay size with the aid of the diagrams

You can find more information on the Internet at:

www.siemens.com/solid-state-switching-devices

Solid-State Relays

SIRIUS 3RF21 solid-state relays, single-phase, 22.5 mm

| | Type current ¹⁾ | Rated control supply voltage $U_{\rm S}$ | DT | Screw terminals ²⁾ | + | PU (UNIT, | PS* | PG | Weight per PU |
|--|--|--|--------|---|----------|--------------|------------------|------------|------------------|
| | | | | Order No. | Price | SET, M) | | | approx. |
| and the second section is | Α | V | | | per PU | | | | kg |
| ro-point switch ited operationa | าเทg เI voltage <i>U_e</i> 24 230 | V | | | | | | | |
| 1 | 20 30 | 24 DC acc. to EN 61131-2 | A A | 3RF21 20-1AA02 3RF21 30-1AA02 | | 1 1 | 1 unit 1 unit | 101 101 | 0.075 0.075 |
| (O) | 50 | acc. to LIN 01131-2 | Α | 3RF21 50-1AA02 | | 1 | 1 unit | 101 | 0.07 |
| The state of the s | 70 90 | | A A | 3RF21 70-1AA02 3RF21 90-1AA02 | | 1 | 1 unit 1 unit | 101 101 | 0.075 0.075 |
| | 20 30 | 110 230 AC | A A | 3RF21 20-1AA22 3RF21 30-1AA22 | | 1 1 | 1 unit 1 unit | 101 101 | 0.07 |
| Service . | 50 70 | | A A | 3RF21 50-1AA22 3RF21 70-1AA22 | | 1 | 1 unit 1 unit | 101 101 | 0.07 0.07 |
| 0 | 90 | | В | 3RF21 90-1AA22 | | 1 | 1 unit | 101 | 0.075 |
| F21 20-1AA02 | 20 30 | 4 30 DC | B B | 3RF21 20-1AA42 3RF21 30-1AA42 | | 1 1 | 1 unit 1 unit | 101 101 | 0.07 0.07 |
| ro-point switch | ning al voltage <i>U_e 48 460</i> | V | | | | | | | |
| ileu operationa | 20 | 24 DC | А | 3RF21 20-1AA04 | | 1 | 1 unit | 101 | 0.075 |
| | 30 50 | acc. to EN 61131-2 | A A | 3RF21 30-1AA04 3RF21 50-1AA04 | | 1 1 | 1 unit 1 unit | 101 101 | 0.07 |
| | 70 90 | | A A | 3RF21 70-1AA04 3RF21 90-1AA04 | | i 1 | 1 unit 1 unit | 101 101 | 0.075 |
| | 20 | 110 230 AC | A | 3RF21 20-1AA24 | | 1 | 1 unit | 101 | 0.07 |
| | 30 50 | | A A | 3RF21 30-1AA24 3RF21 50-1AA24 | | 1 | 1 unit 1 unit | 101 101 | 0.07 |
| | 70 90 | | A A | 3RF21 70-1AA24 3RF21 90-1AA24 | | 1 | 1 unit 1 unit | 101 101 | 0.075 0.075 |
| ro-point switch | ning | NV. | | | | | | | |
| ileu operationa | ol voltage U _e 48 600 70 | 24 DC Low Power | В | 3RF21 70-1AA05-0KN | 0 | 1 | 1 unit | 101 | 0.075 |
| | 20 | 4 30 DC | В | 3RF21 20-1AA45 | | 1 | 1 unit | 101 | 0.075 |
| | 30 50 | | B B | 3RF21 30-1AA45 3RF21 50-1AA45 | | 1 | 1 unit 1 unit | 101 101 | 0.07 |
| | 70 90 | | B B | 3RF21 70-1AA45 3RF21 90-1AA45 | | 1 1 | 1 unit 1 unit | 101 101 | 0.075 0.075 |
| | ning · Blocking voltag I voltage <i>U_e 4</i> 8 600 | | | | | | | | |
| | 30 | 24 DC | A | 3RF21 30-1AA06 | | 1 | 1 unit | 101 | 0.075 |
| | 50 70 | acc. to EN 61131-2 | A B | 3RF21 50-1AA06 3RF21 70-1AA06 | | 1 1 | 1 unit 1 unit | 101 101 | 0.07 0.07 |
| | 90 30 | 110 230 AC | B B | 3RF21 90-1AA06 3RF21 30-1AA26 | | 1 | 1 unit 1 unit | 101 | 0.07 |
| | 50 | 110 200 710 | В | 3RF21 50-1AA26 | | 1 | 1 unit | 101 | 0.07 |
| | 70 90 | | B B | 3RF21 70-1AA26 3RF21 90-1AA26 | | 1 1 | 1 unit 1 unit | 101 101 | 0.075 0.075 |
| stantaneous swated operationa | vitching Il voltage <i>U_e 24 23</i> 0 | v | | | | | | | |
| | 50 | 110 230 AC | Α | 3RF21 50-1BA22 | | 1 | 1 unit | 101 | 0.075 |
| stantaneous sv | vitching Il voltage <i>U_e 48 46</i> 0 | V | | | | | | | |
| nea operationa | 20 | 24 DC | В | 3RF21 20-1BA04 | | 1 | 1 unit | 101 | 0.075 |
| | 30 50 | acc. to EN 61131-2 | B B | 3RF21 30-1BA04 3RF21 50-1BA04 | | 1 1 | 1 unit 1 unit | 101 101 | 0.075 0.075 |
| | 70 90 | | A B | 3RF21 70-1BA04 3RF21 90-1BA04 | | 1 | 1 unit 1 unit | 101 101 | 0.075 |
| stantaneous sv | vitching · Blocking vo | oltage 1600 V | | - I - I - I - I - I - I - I - I - I - I | | <u> </u> | | 101 | 3.07 |
| ited operationa | ul voltage <i>U</i> _e 48 600 50 | 24 DC | В | 3RF21 50-1BA06 | | 1 | 1 unit | 101 | 0.075 |
| noise3) - 7 | | acc. to EN 61131-2 | | | | · · | | | |
| w noise ^{s)} · Zer ited operatio <u>na</u> | o-point switching Il voltage <i>U_e 48 46</i> 0 | V | | | | | | | |
| | 70 | 24 DC acc. to EN 61131-2 | В | 3RF21 70-1CA04 | | 1 | 1 unit | 101 | 0.075 |

Other rated control supply voltages on request.

¹⁾ The type current provides information about the performance capacity of

the solid-state relay. The actual permitted rated operational current $I_{\rm e}$ can be smaller depending on the connection method and cooling conditions.

 $^{^{2)}}$ Please note that this version can only be used for a rated current of up to approx. 50 A and a conductor cross-section of 10 $\rm mm^2.$

³⁾ See page 4/48.

SIRIUS 3RF21 solid-state relays, single-phase, 22.5 mm

| | Type current ¹⁾ | Rated control supply voltage $U_{\rm S}$ | DT | Spring-type terminals ²⁾ | | PU (UNIT, SET, M) | PS* | PG | Weight per PU approx. |
|--|--|--|-------------|--|-----------------|-------------------------|----------------------------|-------------------|-------------------------|
| | А | V | | Order No. | Price per PU | | | | kg |
| Zero-point switchi | ng voltage <i>U</i> _e 24 230 | ı V | | | | | | | |
| 100 M | 20 50 | 24 DC acc. to EN 61131-2 | A B | 3RF21 20-2AA02 3RF21 50-2AA02 | | 1 | 1 unit 1 unit | 101 101 | 0.075 0.075 |
| .0. | 90 | 110 230 AC | B B | 3RF21 90-2AA02 3RF21 20-2AA22 | | 1 1 | 1 unit | 101 | 0.075 |
| ■ 310 L □ 3100 t 0 3100 t 0 1000 to | 50 90 | | B B | 3RF21 50-2AA22 3RF21 90-2AA22 | | 1 | 1 unit 1 unit | 101 101 | 0.075 0.075 |
| | 20 | 4 30 DC | В | 3RF21 20-2AA42 | | 1 | 1 unit | 101 | 0.075 |
| Zero-point switchi Rated operational | ng voltage <i>U_e</i> 48 460 20 | 24 DC | В | 3RF21 20-2AA04 | | 1 | 1 unit | 101 | 0.075 |
| | 50 90 | acc. to EN 61131-2 | B B | 3RF21 50-2AA04 3RF21 90-2AA04 | | 1 1 | 1 unit 1 unit | 101 101 | 0.075 0.075 |
| | 50 | 24 AC/DC | В | 3RF21 50-2AA14 | | 1 | 1 unit | 101 | 0.075 |
| | 20 50 90 | 110 230 AC | B B B | 3RF21 20-2AA24 3RF21 50-2AA24 3RF21 90-2AA24 | | 1 1 1 | 1 unit 1 unit 1 unit | 101 101 101 | 0.075 0.075 0.075 |
| Zero-point switchi Rated operational | ng voltage <i>U_e 48 600</i> |) V | | | | | | | |
| | 20 | 4 30 DC | В | 3RF21 20-2AA45 | | 1 | 1 unit | 101 | 0.075 |
| Zero-point switchi rated operational v | ng · Blocking voltac voltage <i>U</i> _e 48 600 | ge 1600 V, V | | | | | | | |
| | 50 90 | 24 DC acc. to EN 61131-2 | B B | 3RF21 50-2AA06 3RF21 90-2AA06 | | 1 1 | 1 unit 1 unit | 101 101 | 0.075 0.075 |
| | 50 90 | 110 230 AC | B B | 3RF21 50-2AA26 3RF21 90-2AA26 | | 1 1 | 1 unit 1 unit | 101 101 | 0.075 0.075 |

¹⁾ The type current provides information about the performance capacity of the solid-state relay.

The actual permitted rated operational current $I_{\rm g}$ can be smaller depending on the connection method and cooling conditions.

²⁾ Please note that the version with spring-type terminals can only be used for a rated current of up to approx. 20 A and a conductor cross-section of 2.5 mm². Higher currents are possible by connecting two conductors per terminal.

SIRIUS 3RF21 solid-state relays, single-phase, 22.5 mm

| | Type current ¹⁾ | Rated control supply voltage $U_{\rm S}$ | DT | Ring terminal lug con- nection | (1) | PU (UNIT, SET, M) | PS* | PG | Weight per PU approx. |
|---|--|--|-------------|--|-----------------|-------------------------|----------------------------|-------------------|-------------------------|
| | А | V | | Order No. | Price per PU | | | | kg |
| Zero-point switching Rated operational values | |) V | | | | | | | |
| | 20 50 90 | 24 DC acc. to EN 61131-2 | A B B | 3RF21 20-3AA02 3RF21 50-3AA02 3RF21 90-3AA02 | | 1 1 1 | 1 unit 1 unit 1 unit | 101 101 101 | 0.075 0.075 0.075 |
| | 20 50 90 | 110 230 AC | В В В | 3RF21 20-3AA22 3RF21 50-3AA22 3RF21 90-3AA22 | | 1 1 1 | 1 unit 1 unit 1 unit | 101 101 101 | 0.075 0.075 0.075 |
| 3RF21 20-3AA02 Zero-point switchir Rated operational v | ng voltage <i>U_e 48 460</i> |) V | | | | | | | |
| | 20 50 90 | 24 DC acc. to EN 61131-2 | B B B | 3RF21 20-3AA04 3RF21 50-3AA04 3RF21 90-3AA04 | | 1 1 1 | 1 unit 1 unit 1 unit | 101 101 101 | 0.075 0.075 0.075 |
| | 20 50 90 | 110 230 AC | B B B | 3RF21 20-3AA24 3RF21 50-3AA24 3RF21 90-3AA24 | | 1 1 1 | 1 unit 1 unit 1 unit | 101 101 101 | 0.075 0.075 0.075 |
| | 90 | 4 30 DC | В | 3RF21 90-3AA44 | | 1 | 1 unit | 101 | 0.075 |
| Zero-point switchir rated operational v | ng · Blocking voltag oltage <i>U_e 48 600</i> | ge 1600 V, V | | | | | | | |
| | 50 90 | 24 DC acc. to EN 61131-2 | B B | 3RF21 50-3AA06 3RF21 90-3AA06 | | 1 1 | 1 unit 1 unit | 101 101 | 0.075 0.075 |
| | 50 90 | 110 230 AC | B B | 3RF21 50-3AA26 3RF21 90-3AA26 | | 1 1 | 1 unit 1 unit | 101 101 | 0.075 0.075 |

| | Version | DT | Order No. | Price per PU | PU (UNIT, SET, M) | PS* | PG | Weight per PU approx. |
|----------------------|--|----|----------------|-----------------|-------------------------|----------|-----|-----------------------|
| | | | | | | | | kg |
| Optional accessories | | | | | | | | |
| | Screwdrivers for opening spring-type terminals | С | 8WA2 880 | | 1 | 1 unit | 041 | 0.034 |
| | Terminal covers for 3RF21 solid-state relays and 3RF23 solid-state contactors in ring terminal lug connection | Α | 3RF29 00-3PA88 | | 1 | 10 units | 101 | 0.004 |
| 3RF29 00-3PA88 | (After simple adaptation, this terminal cover can also be used for screw connection). | | | | | | | |

¹⁾ The type current provides information about the performance capacity of the solid-state relay. The actual permitted rated operational current I_e can be smaller depend-ing on the connection method and cooling conditions.

SIRIUS 3RF20 solid-state relays, single-phase. 45 mm

| single-phase, 4 | 5 mm | | | | | | | | |
|--|--|--|-------------|--|-----------------|-------------------------|------------------|------------|-----------------------|
| Selection and orde | ering data | | | | | | | | |
| | Type current ¹⁾ | Rated control supply voltage $U_{\rm S}$ | DT | Screw terminals ²⁾ | + | PU (UNIT, SET, M) | PS* | PG | Weight per PU approx. |
| | Α | V | | Order No. | Price per PU | | | | kg |
| Zero-point switching Rated operational values | ng | | | | 17-2-2 | | | | |
| At the state of th | 20 | 24 DC | A | 3RF20 20-1AA02 | | 1 | 1 unit | 101 | 0.085 |
| 5 C 2 | 30 50 | acc. to EN 61131-2 | A | 3RF20 30-1AA02 3RF20 50-1AA02 | | 1 | 1 unit 1 unit | 101 101 | 0.085 0.085 |
| 3000 | 70 90 | | A A | 3RF20 70-1AA02 3RF20 90-1AA02 | | 1 | 1 unit 1 unit | 101 101 | 0.085 0.085 |
| AC 6 | 20 30 | 110 230 AC | A A | 3RF20 20-1AA22 3RF20 30-1AA22 | | 1 1 | 1 unit 1 unit | 101 101 | 0.085 0.085 |
| 11 12 (0 (0) | 50 70 | | A A | 3RF20 50-1AA22 3RF20 70-1AA22 | | 1 1 | 1 unit 1 unit | 101 101 | 0.085 0.085 |
| 3PE20 20 14 402 | 90 | 4 30 DC | A B | 3RF20 90-1AA22 3RF20 20-1AA42 | | 1 | 1 unit 1 unit | 101 101 | 0.085 |
| 3RF20 20-1AA02 | 30 | 4 50 DC | В | 3RF20 30-1AA42 | | 1 | 1 unit | 101 | 0.085 |
| Zero-point switchin Rated operational | ng voltage <i>U_e 48 46</i> 0 | V | | | | | | | |
| | 20 30 | 24 DC acc. to EN 61131-2 | A A | 3RF20 20-1AA04 3RF20 30-1AA04 | | 1 | 1 unit 1 unit | 101 101 | 0.085 0.085 |
| | 50 70 | | A A | 3RF20 50-1AA04 3RF20 70-1AA04 | | 1 | 1 unit 1 unit | 101 101 | 0.085 0.085 |
| | 90 20 | 110 230 AC | A | 3RF20 90-1AA04 3RF20 20-1AA24 | | 1 | 1 unit 1 unit | 101 | 0.085 |
| | 30 50 | 110 230 AC | Α | 3RF20 30-1AA24 | | 1 | 1 unit 1 unit | 101 | 0.085 |
| | 70 90 | | A A A | 3RF20 50-1AA24 3RF20 70-1AA24 3RF20 90-1AA24 | | 1 1 1 | 1 unit | 101 101 | 0.085 |
| | 50 | 4 30 DC | A | 3RF20 50-1AA44 | | 1 | 1 unit 1 unit | 101 | 0.085 |
| Zero-point switchin Rated operational | ng voltage <i>U</i> . 48 600 | V | | | | | | | |
| | 20 | 4 30 DC | В | 3RF20 20-1AA45 | | 1 | 1 unit | 101 | 0.085 |
| | 50 70 | | B B | 3RF20 50-1AA45 3RF20 70-1AA45 | | 1 | 1 unit 1 unit | 101 101 | 0.085 |
| Zero-point switching | 90 ng · Blocking voltag | e 1600 V, | В | 3RF20 90-1AA45 | | 1 | 1 unit | 101 | 0.085 |
| rated operational v | 30 30 | 24 DC | В | 3RF20 30-1AA06 | | 1 | 1 unit | 101 | 0.085 |
| | 50 70 | acc. to EN 61131-2 | B B | 3RF20 50-1AA06 3RF20 70-1AA06 | | 1 | 1 unit 1 unit | 101 101 | 0.085 0.085 |
| | 90 | 110 230 AC | B B | 3RF20 90-1AA06 3RF20 30-1AA26 | | 1 | 1 unit | 101 | 0.085 |
| | 50 | 110 230 AC | B B | 3RF20 50-1AA26 | | 1 | 1 unit | 101 101 | 0.085 |
| | 70 90 | | В | 3RF20 70-1AA26 3RF20 90-1AA26 | | 1 | 1 unit 1 unit | 101 101 | 0.085 0.085 |
| Instantaneous swit Rated operational | | v | | | | | | | |
| | 30 | 24 DC acc. to EN 61131-2 | В | 3RF20 30-1BA04 | | 1 | 1 unit | 101 | 0.085 |
| | | dec. to EN 011012 | | | | | | | |
| | Type current ¹⁾ | Rated control supply | DT | Screw terminals + | 00 | PU | PS* | PG | Weight |
| | , , , , , , , , , , , , , , , , , , , | voltage U _s | | spring-type terminals (control current side) | | (UNIT, SET, M) | | | per PU approx. |
| | Α | V | | Order No. | Price per PU | , | | | |
| Zero-point switching | ng | | | | perio | | | | kg |
| Rated operational | voltage <i>U</i> _e 24 230 50 | 24 DC | А | 3RF20 50-4AA02 | | 1 | 1 unit | 101 | 0.085 |
| | | acc. to EN 61131-2 | | | | | | | |
| 3RF20 50-4AA02 | | | | | | | | | |

 $^{^{1)}}$ The type current provides information about the performance capacity of the solid-state relay. The actual permitted rated operational current $I_{\rm e}$ can be smaller depending on the connection method and cooling conditions.

 $^{^{2)}}$ Please note that this version can only be used for a rated current of up to approx. 50 A and a conductor cross-section of 10 $\rm mm^2.$

Solid-State Relays

SIRIUS 3RF22 solid-state relays, three-phase, 45 mm

| Selection | and | order | ing | data |
|-----------|-----|-------|-----|------|
| | | | | |
| | | | | |

| | J | | | | | | | | |
|--|--|--|----|-------------------------------------|-----------------|-------------------------|--------|-----|-----------------------|
| | Type current ¹⁾ | Rated control supply voltage $U_{\rm S}$ | DT | Screw terminals ²⁾ | + | PU (UNIT, SET, M) | PS* | PG | Weight per PU approx. |
| | A | V | | Order No. | Price per PU | | | | kg |
| Zero-point switchin | ng | | | | p 2 | | | | 9 |
| Hateu operational | voltage <i>U</i> _e 48 600 | | | | | | | | |
| | Two-phase con | 110 AC | В | 3RF22 30-1AB35 | | 1 | 1 unit | 101 | 0.150 |
| 000 | 55 | TIUAC | В | 3RF22 55-1AB35 | | 1 | 1 unit | 101 | 0.150 |
| SIEMENS | 30 | 4 30 DC | В | 3RF22 30-1AB45 | | 1 | 1 unit | 101 | 0.150 |
| | 55 | 55 2 5 | В | 3RF22 55-1AB45 | | 1 | 1 unit | 101 | 0.150 |
| 66 | Three-phase co | ntrolled | | | | | | | |
| eeel | 30 | 110 AC | В | 3RF22 30-1AC35 | | 1 | 1 unit | 101 | 0.150 |
| 3RF22 30-1AB45 | 55 | | В | 3RF22 55-1AC35 | | 1 | 1 unit | 101 | 0.150 |
| 2 22 00 2.10 | 30 | 4 30 DC | Α | 3RF22 30-1AC45 | | 1 | 1 unit | 101 | 0.150 |
| | 55 | | В | 3RF22 55-1AC45 | | 1 | 1 unit | 101 | 0.150 |
| | | | | | | | | | |
| | Type current ¹⁾ | Rated control supply voltage $U_{\rm S}$ | DT | Spring-type terminals ³⁾ | ∞ | PU (UNIT, SET, M) | PS* | PG | Weight per PU approx. |
| | А | V | | Order No. | Price per PU | | | | kg |
| Zero-point switchin Rated operational | ng voltage <i>U_e 48 6</i> 00 |) V | | | | | | | <u> </u> |
| 0000 | Two-phase con | trolled | | | | | | | |
| 00 00 00 Hm Hm Hm | 30 | 4 30 DC | В | 3RF22 30-2AB45 | | 1 | 1 unit | 101 | 0.150 |
| (i) (ii) | 55 | | В | 3RF22 55-2AB45 | | 1 | 1 unit | 101 | 0.150 |
| SILMENS COLUMN | Three-phase co | | | | | | | | |
| 0 | 30 | 4 30 DC | В | 3RF22 30-2AC45 | | 1 | 1 unit | 101 | 0.150 |
| EE EE EE | 55 | | В | 3RF22 55-2AC45 | | 1 | 1 unit | 101 | 0.150 |
| ee ee ee | | | | | | | | | |
| 3RF22 30-2AB45 | | | | | | | | | |
| | | | | | | | | | |
| | Type current ¹⁾ | Rated control supply voltage $U_{\rm S}$ | DT | Ring terminal lug con- nection | + | PU (UNIT, SET, M) | PS* | PG | Weight per PU approx. |
| | А | V | | Order No. | Price per PU | | | | kg |
| Zero-point switchir Rated operational | ng voltage <i>U_e 48 600</i> | v | | | | | | | |
| 4441 | Two-phase con | | | | | | | | |
| | 30 | 4 30 DC | В | 3RF22 30-3AB45 | | 1 | 1 unit | 101 | 0.150 |
| MA C M | 55 | | В | 3RF22 55-3AB45 | | 1 | 1 unit | 101 | 0.150 |
| SIEMEDES COLO | Three-phase co | | | | | | | | |
| 66 9 | 30 | 4 30 DC | В | 3RF22 30-3AC45 | | 1 | 1 unit | 101 | 0.150 |
| 555 | 55 | | В | 3RF22 55-3AC45 | | 1 | 1 unit | 101 | 0.150 |
| 3RF22 30-3AB45 | | | _ | | | | | | |



- 1) The type current provides information about the performance capacity of the solid-state relay.
 - The actual permitted rated operational current $I_{\rm e}$ can be smaller depending on the connection method and cooling conditions.
- $^{2)}\,$ Please note that the version with an M4 screw connection can only be used for a rated current of up to approx. 50 A and a conductor cross-section of $10\ mm^2$.
- ³⁾ Please note that the version with spring-type terminals can only be used for a rated current of up to approx. 20 A and a conductor cross-section of 2.5 mm². Higher currents are possible by connecting two conductors per

Solid-State Contactors

General data

Overview

Solid-State Contactors

The complete units consist of a solid-state relay plus optimized heat sink, and are therefore ready to use. They offer defined rated currents to make selection as easy as possible. Depending on the version, current strengths of up to 88 A are achieved. Like all of our solid-state switching devices, one of their particular advantages is their compact and space-saving design.

With their insulated mounting foot they can easily be snapped onto a standard mounting rail, or they can be mounted on support plates with fixing screws. This insulation enables them to be used in circuits with protective extra-low voltage (PELV) or safety extra-low voltage (SELV) in building management systems. For other applications, such as for extended personal safety, the heat sink can be grounded through a screw terminal.

The solid-state contactors are available in 2 different versions:

- 3RF23 single-phase solid-state contactors,
- 3RF24 three-phase solid-state contactors

Single-phase versions

The 3RF23 solid-state contactors can be expanded with various function modules to adapt them to individual applications.

Version for resistive loads, "zero-point switching"

This standard version is often used for switching space heaters on and off

Version for inductive loads, "instantaneous switching"

In this version the solid-state contactor is specifically matched to inductive loads. Whether it is a matter of frequent actuation of the valves in a filling plant or starting and stopping small operating mechanisms in packet distribution systems, operation is carried out safely and noiselessly.

Special "Low noise" version

Thanks to a special control circuit, this special version can be used in public networks up to 16 A without any additional measures, such as interference suppressor filters. As a result, in terms of emitted interference, it conforms to limit value curve class B according to EN 60947-4-3.

Special "Short-circuit proof" version

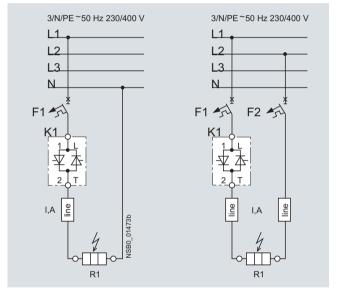
Skillful matching of the power semiconductor with the performance capacity of the solid-state contactor means that "short-circuit strength" can be achieved with a standard miniature circuit breaker. In combination with a B-type MCB or a conventional line protection fuse, the result is a short-circuit proof feeder.

In order to achieve problem-free short-circuit protection by means of miniature circuit breakers, however, certain boundary conditions must be observed. As the magnitude and duration of the short-circuit current are determined not only by the short-circuit breaking response of the miniature circuit breaker but also the properties of the wiring system, such as the internal resistance of the input to the network and damping by controls and cables, particular attention must also be paid to these parameters. The necessary cable lengths are therefore shown for the main factor, the line resistance, in the table below.

The following miniature circuit breakers with a B characteristic and 10 kA or 6 kA breaking capacity protect the 3RF23..-.DA.. solid-state contactors in the event of short-circuits on the load and the specified conductor cross-sections and lengths:

| Rated current of the miniature circuit breaker | Example of type 1) | Max. conductor cross-section | Minimum cable length from contactor to load |
|--|---------------------------|------------------------------|--|
| 6 A | 5SY4 106-6, 5SX2 106-6 | 1 mm ² | 5 m |
| 10 A | 5SY4 110-6, 5SX2 110-6 | 1.5 mm ² | 8 m |
| 16 A | 5SY4 116-6, 5SX2 116-6 | 1.5 mm ² | 12 m |
| 16 A | 5SY4 116-6, 5SX2 116-6 | 2.5 mm ² | 20 m |
| 20 A | 5SY4 120-6, 5SX2 120-6 | 2.5 mm ² | 20 m |
| 25 A | 5SY4 125-6, 5SX2 125-6 | 2.5 mm ² | 26 m |

¹⁾ The miniature circuit breakers can be used up to a maximum rated voltage of 480 V!



The setup and installation above can also be used for the solidstate relays with a I^2t value of at least 6600 A²s.

Three-phase versions

The three-phase solid-state contactors for resistive loads up to 50 A are available with

- two-phase control (suitable in particular for circuits without connection to the neutral conductor) and
- three-phase control (suitable for star circuits with connection to the neutral conductor or for applications in which the system requires all phases to be switched).

The converter function module can be snapped onto both versions for the simple power control of AC loads by means of analog signals.

Check the correct contactor size with the aid of the rated current diagram, taking account of the installation conditions

Solid-State Contactors

SIRIUS 3RF23 solid-state contactors, single-phase

Selection and ordering data

Selection notes

The solid-state contactors are selected on the basis of details of the network, the load and the ambient conditions. As the solidstate contactors are already equipped with an optimally matched heat sink, the selection process is considerably simpler than that for solid-state relays. The following procedure is recommended:

- Determine the rated current of the load and the mains voltage
- Select a solid-state contactor with the same or higher rated current than the load

| pler than that for soli | ia-state relays. | | | | | | | | |
|--|---|--|--------|----------------------------------|-----------------|-------------------------|------------------|------------|-----------------------|
| | Type current ¹⁾ I_{max} | Rated control supply voltage $U_{\rm S}$ | DT | Screw terminals | 1 | PU (UNIT, SET, M) | PS* | PG | Weight per PU approx. |
| | A | V | | Order No. | Price per PU | | | | kg |
| Zero-point switchin Rated operational v | | V | | | | | | | |
| 15. | 10.5 20 | 24 DC acc. to EN 61131-2 | A A | 3RF23 10-1AA02 3RF23 20-1AA02 | | 1 | 1 unit 1 unit | 101 101 | 0.165 0.240 |
| | 30 | acc. to EIV 01101 2 | Α | 3RF23 30-1AA02 | | 1 | 1 unit | 101 | 0.400 |
| . © . | 40 50 | | A A | 3RF23 40-1AA02 3RF23 50-1AA02 | | 1 1 | 1 unit 1 unit | 101 101 | 0.550 0.550 |
| O positi | 20 | 24 DC Low Power | Α | 3RF23 20-1AA02-0KN0 | | 1 | 1 unit | 101 | 0.240 |
| | 10.5 | 24 AC/DC | Α | 3RF23 10-1AA12 | | 1 | 1 unit | 101 | 0.165 |
| 0 14 | 10.5 20 | 110 230 AC | A A | 3RF23 10-1AA22 3RF23 20-1AA22 | | 1 1 | 1 unit 1 unit | 101 101 | 0.165 0.240 |
| 3RF23 10-1 | 30 40 | | A A | 3RF23 30-1AA22 3RF23 40-1AA22 | | 1 1 | 1 unit 1 unit | 101 101 | 0.400 0.550 |
| 3NF23 10-1 | 50 | | A | 3RF23 50-1AA22 | | 1 | 1 unit | 101 | 0.550 |
| Zero-point switchin Rated operational v | g oltage <i>U_e 48 460</i> | v | | | | | | | |
| | 10.5 20 | 24 DC acc. to EN 61131-2 | A A | 3RF23 10-1AA04 3RF23 20-1AA04 | | 1 1 | 1 unit 1 unit | 101 101 | 0.165 0.240 |
| | 30 | acc. to LIN 01131-2 | A | 3RF23 30-1AA04 | | 1 | 1 unit | 101 | 0.400 |
| C | 40 50 | | A A | 3RF23 40-1AA04 3RF23 50-1AA04 | | 1 1 | 1 unit 1 unit | 101 101 | 0.550 0.550 |
| .0. | 10.5 | 24 DC Low Power | A | 3RF23 10-1AA04-0KN0 | | 1 | 1 unit | 101 | 0.165 |
| O TOTAL | 10.5 | 24 AC/DC | Α | 3RF23 10-1AA14 | | 1 | 1 unit | 101 | 0.165 |
| 88 | 20 30 | | B A | 3RF23 20-1AA14 3RF23 30-1AA14 | | 1 1 | 1 unit 1 unit | 101 101 | 0.240 0.400 |
| 0 | 40 | | В | 3RF23 40-1AA14 | | 1 | 1 unit | 101 | 0.550 |
| 3RF23 20-1 | 50 10.5 | 110 230 AC | B A | 3RF23 50-1AA14 3RF23 10-1AA24 | | 1 | 1 unit 1 unit | 101 | 0.550 |
| | 20 | | Α | 3RF23 20-1AA24 | | 1 | 1 unit | 101 | 0.240 |
| | 30 40 | | A A | 3RF23 30-1AA24 3RF23 40-1AA24 | | 1 1 | 1 unit 1 unit | 101 101 | 0.400 0.550 |
| | 50 | | A | 3RF23 50-1AA24 | | 1 | 1 unit | 101 | 0.550 |
| | 10.5 20 | 4 30 DC | B A | 3RF23 10-1AA44 3RF23 20-1AA44 | | 1 1 | 1 unit 1 unit | 101 101 | 0.165 0.240 |
| | 30 | | Α | 3RF23 30-1AA44 | | 1 | 1 unit | 101 | 0.400 |
| Zero-point switchin Rated operational v | g oltage <i>U_e 48 600</i> | V | | | | | | | |
| | 30 | 110 230 AC | В | 3RF23 30-1AA25 | | 1 | 1 unit | 101 | 0.400 |
| | 10.5 20 | 4 30 DC | B A | 3RF23 10-1AA45 3RF23 20-1AA45 | | 1 1 | 1 unit 1 unit | 101 101 | 0.165 0.240 |
| | 30 | | Α | 3RF23 30-1AA45 | | 1 | 1 unit | 101 | 0.400 |
| | 40 50 | | A A | 3RF23 40-1AA45 3RF23 50-1AA45 | | 1 1 | 1 unit 1 unit | 101 101 | 0.550 0.550 |
| Zero-point switchin rated operational vo | g · Blocking voltag oltage <i>U_e 48 600</i> | e 1600 V, V | | | | | | | |
| • | 10.5 | 24 DC | В | 3RF23 10-1AA06 | | 1 | 1 unit | 101 | 0.165 |
| | 20 30 | acc. to EN 61131-2 | A A | 3RF23 20-1AA06 3RF23 30-1AA06 | | 1 1 | 1 unit 1 unit | 101 101 | 0.240 0.400 |
| e | 40 50 | | B B | 3RF23 40-1AA06 | | i 1 | 1 unit | 101 | 0.550 |
| . <u>.</u> | 10.5 | 110 230 AC | В | 3RF23 50-1AA06 3RF23 10-1AA26 | | 1 | 1 unit 1 unit | 101 | 0.550 |
| | 20 | | В | 3RF23 20-1AA26 | | 1 | 1 unit | 101 | 0.240 |
| 60 | 30 40 | | B B | 3RF23 30-1AA26 3RF23 40-1AA26 | | 1 1 | 1 unit 1 unit | 101 101 | 0.400 0.550 |
| 6 | 50 | | В | 3RF23 50-1AA26 | | 1 | 1 unit | 101 | 0.550 |
| 3RF23 40-1 | | | | | | | | | |

¹⁾ The type current provides information about the performance of the solid-state contactor. The actual permitted rated operational current I_e can be smaller depending on the connection method and start-up conditions. For derating see the manual, "Characteristic curves".

SIRIUS 3RF23 solid-state contactors, single-phase

| | Type current ¹⁾ I_{max} | Opera- tional current I_e /AC-15 ²⁾ | Rated control supply voltage $U_{\rm S}$ | DT | Screw terminals | + | PU (UNIT, SET, M) | PS* | PG | Weight per PU approx. |
|--|---|---|--|----------------------------|--|-----------------|----------------------------|--|---|---|
| | А | Α | V | | Order No. | Price per PU | | | | kg |
| Instantaneous switch Rated operational vo | ning Itage <i>U</i> _e 2 | 4 230 V | | | | | | | | |
| | 10.5 20 30 40 50 50 | 6 12 15 20 25 27.5 30 | 24 DC acc. to EN 61131-2 | A A B B B B B | 3RF23 10-1BA02 3RF23 20-1BA02 3RF23 30-1BA02 3RF23 40-1BA02 3RF23 50-1BA02 3RF23 70-1BA02 3RF23 90-1BA02 | | 1 1 1 1 1 1 | 1 unit 1 unit 1 unit 1 unit 1 unit 1 unit 1 unit | 101 101 101 101 101 101 101 | 0.165 0.240 0.400 0.550 0.550 1.200 2.900 |
| 3RF23 10-1 | 10.5 20 30 40 50 50 | 6 12 15 20 25 27.5 30 | 110 230 AC | B B B B B B | 3RF23 10-1BA22 3RF23 20-1BA22 3RF23 30-1BA22 3RF23 40-1BA22 3RF23 50-1BA22 3RF23 70-1BA22 3RF23 90-1BA22 | | 1 1 1 1 1 1 | 1 unit 1 unit 1 unit 1 unit 1 unit 1 unit 1 unit | 101 101 101 101 101 101 101 | 0.165 0.240 0.400 0.550 0.550 1.200 2.900 |
| Instantaneous switch Rated operational vo | | 8 460 V | | | | | | | | |
| | 10.5 20 30 40 50 50 | 6 12 15 20 25 27.5 30 | 24 DC acc. to EN 61131-2 | A A B B B B | 3RF23 10-1BA04 3RF23 20-1BA04 3RF23 30-1BA04 3RF23 40-1BA04 3RF23 50-1BA04 3RF23 70-1BA04 3RF23 90-1BA04 | | 1 1 1 1 1 1 | 1 unit | 101 101 101 101 101 101 101 | 0.165 0.240 0.400 0.550 0.550 1.200 2.900 |
| 3RF23 20-1 | 10.5 20 30 40 50 50 | 6 12 15 20 25 27.5 30 | 110 230 AC | B B B B B B | 3RF23 10-1BA24 3RF23 20-1BA24 3RF23 30-1BA24 3RF23 40-1BA24 3RF23 50-1BA24 3RF23 70-1BA24 3RF23 90-1BA24 | | 1 1 1 1 1 1 | 1 unit | 101 101 101 101 101 101 101 | 0.165 0.240 0.400 0.550 0.550 1.200 2.900 |
| | 20 30 50 | 12 15 25 | 4 30 DC | B B B | 3RF23 20-1BA44 3RF23 30-1BA44 3RF23 50-1BA44 | | 1 1 1 | 1 unit 1 unit 1 unit | 101 101 101 | 0.240 0.400 0.550 |
| Instantaneous switch Rated operational vo | ning ⋅ Bloc Itage <i>U</i> e 4 | king volta 8 600 V | ge 1600 V | | | | | | | |
| .6. | 10.5 20 30 40 50 50 | 6 12 15 20 25 27.5 30 | 24 DC acc. to EN 61131-2 | B A B B B B | 3RF23 10-1BA06 3RF23 20-1BA06 3RF23 30-1BA06 3RF23 40-1BA06 3RF23 50-1BA06 3RF23 70-1BA06 3RF23 90-1BA06 | | 1 1 1 1 1 1 | 1 unit 1 unit 1 unit 1 unit 1 unit 1 unit 1 unit | 101 101 101 101 101 101 101 | 0.165 0.240 0.400 0.550 0.550 1.200 2.900 |
| 3RF23 40-1 | 10.5 20 30 40 50 50 | 6 12 15 20 25 27.5 30 | 110 230 AC | B B B B B B | 3RF23 10-1BA26 3RF23 20-1BA26 3RF23 30-1BA26 3RF23 40-1BA26 3RF23 50-1BA26 3RF23 70-1BA26 3RF23 90-1BA26 | | 1 1 1 1 1 1 | 1 unit 1 unit 1 unit 1 unit 1 unit 1 unit 1 unit | 101 101 101 101 101 101 101 | 0.165 0.240 0.400 0.550 0.550 1.200 2.900 |

¹⁾ The type current provides information about the performance of the solid-state contactor. The actual permitted rated operational current I_e can be smaller depending on the connection method and start-up conditions. For derating see the manual, "Characteristic curves".

²⁾ Utilization category AC-15: Electromagnetic loads, e. g. valves according to EN 60947-5. Parameters: max. 1200 1/h, 50 % ON Period, 10-times inrush current for

SIRIUS 3RF23 solid-state contactors, single-phase

| | Type current ¹⁾ I_{max} | Rated control supply voltage $U_{\rm S}$ | DT | Screw terminals | 1 | PU (UNIT, SET, M) | PS* | PG | Weight per PU approx. |
|---------------------------------------|---|--|--------|----------------------------------|-----------------|-------------------------|------------------|------------|-----------------------|
| | А | V | | Order No. | Price per PU | | | | kg |
| Low noise ²⁾ · Zero | p-point switching voltage <i>U_e</i> 24 230 | n V | | | | | | | |
| nateu operational | | 24 DC | D | 3RF23 20-1CA02 | | 4 | 1 unit | 101 | 0.240 |
| | 20 30 | acc. to EN 61131-2 | B B | 3RF23 20-1CA02 3RF23 30-1CA02 | | 1 1 | 1 unit | 101 | 0.400 |
| .0. | 20 | 110 230 AC | В | 3RF23 20-1CA22 | | 1 | 1 unit | 101 | 0.240 |
| 3RF23 20-1 | | | | | | | | | |
| Low noise ²⁾ · Zero | -point switching voltage <i>U_e</i> 48 46 | n V | | | | | | | |
| | 20 | 24 DC acc. to EN 61131-2 | В | 3RF23 20-1CA04 | | 1 | 1 unit | 101 | 0.240 |
| | 20 | 110 230 AC | В | 3RF23 20-1CA24 | | 1 | 1 unit | 101 | 0.240 |
| | 20 | 4 30 DC | Α | 3RF23 20-1CA44 | | 1 | 1 unit | 101 | 0.240 |
| Short-circuit proof rated operational | f with B-type MCB · voltage <i>U</i> _e 24 230 | Zero-point switching, V | | | | | | | |
| | 20 | 24 DC acc. to EN 61131-2 | А | 3RF23 20-1DA02 | | 1 | 1 unit | 101 | 0.240 |
| | 20 | 110 230 AC | В | 3RF23 20-1DA22 | | 1 | 1 unit | 101 | 0.240 |
| | f with B-type MCB · voltage <i>U</i> e 48 460 | Zero-point switching, | | | | | | | |
| | 20 | 24 DC acc. to EN 61131-2 | Α | 3RF23 20-1DA04 | | 1 | 1 unit | 101 | 0.240 |
| | 20 | 110 230 AC | В | 3RF23 20-1DA24 | | 1 | 1 unit | 101 | 0.240 |
| | 20 30 | 4 30 DC | A A | 3RF23 20-1DA44 3RF23 30-1DA44 | | 1 1 | 1 unit 1 unit | 101 101 | 0.240 0.240 |

¹⁾ The type current provides information about the performance of the solid-state contactor. The actual permitted rated operational current I_e can be smaller depending on the connection method and start-up conditions. For derating see the manual, "Characteristic curves".

²⁾ See page 4/54.

SIRIUS 3RF23 solid-state contactors, single-phase

| | Type current ¹⁾ I _{max} | Rated control supply voltage $U_{\rm S}$ | DT | Spring-type terminals | 8 | PU (UNIT, SET, M) | PS* | PG | Weight per PU approx. |
|---|---|--|--------|----------------------------------|-----------------|-------------------------|------------------|------------|-----------------------|
| | Α | V | | Order No. | Price per PU | | | | kg |
| Zero-point switching Rated operational vo | | | | | 1 | | | | |
| to-co | 10.5 20 | 24 DC acc. to EN 61131-2 | B A | 3RF23 10-2AA02 3RF23 20-2AA02 | | 1 1 | 1 unit 1 unit | 101 101 | 0.166 0.240 |
| | 10.5 | 110 230 AC | B B | 3RF23 10-2AA22 3RF23 20-2AA22 | | 1 | 1 unit 1 unit | 101 101 | 0.166 0.240 |
| 3RF23 20-2 Zero-point switching | | | | | | | | | |
| Rated operational vo | | V | | | | | | | |
| | 10.5 20 | 24 DC acc. to EN 61131-2 | A A | 3RF23 10-2AA04 3RF23 20-2AA04 | | 1 1 | 1 unit 1 unit | 101 101 | 0.166 0.240 |
| | 10.5 20 | 110 230 AC | B B | 3RF23 10-2AA24 3RF23 20-2AA24 | | 1 1 | 1 unit 1 unit | 101 101 | 0.166 0.240 |
| Zero-point switching rated operational vol | ı · Blocking voltag Itage <i>U</i> _e 48 600 | e 1600 V, V | | | | | | | |
| | 10.5 20 | 24 DC acc. to EN 61131-2 | B A | 3RF23 10-2AA06 3RF23 20-2AA06 | | 1 1 | 1 unit 1 unit | 101 101 | 0.166 0.240 |
| | 10.5 20 | 110 230 AC | B B | 3RF23 10-2AA26 3RF23 20-2AA26 | | 1 1 | 1 unit 1 unit | 101 101 | 0.166 0.240 |
| Low noise ²⁾ · Zero-pe Rated operational vo | | v | | | | | | | |
| | 20 | 24 DC acc. to EN 61131-2 | В | 3RF23 20-2CA02 | | 1 | 1 unit | 101 | 0.240 |
| | 20 | 110 230 AC | В | 3RF23 20-2CA22 | | 1 | 1 unit | 101 | 0.240 |
| Low noise ²⁾ · Zero-pe Rated operational vo | oint switching oltage <i>U_e 48 4</i> 60 | v | | | | | | | |
| | 20 | 24 DC acc. to EN 61131-2 | В | 3RF23 20-2CA04 | | 1 | 1 unit | 101 | 0.240 |
| | 20 | 110 230 AC | В | 3RF23 20-2CA24 | | 1 | 1 unit | 101 | 0.240 |
| Short-circuit proof w rated operational vol | vith B-type MCB · 2 Itage <i>U</i> e 24 230 | Zero-point switching, V | | | | | | | |
| | 20 | 110 230 AC | В | 3RF23 20-2DA22 | | 1 | 1 unit | 101 | 0.240 |
| Short-circuit proof w rated operational vol | | Zero-point switching, V | | | | | | | |
| | 20 | 110 230 AC | В | 3RF23 20-2DA24 | | 1 | 1 unit | 101 | 0.240 |

¹⁾ The type current provides information about the performance of the solidstate contactor. The actual permitted rated operational current $I_{\rm e}$ can be smaller depending on the connection method and start-up conditions. For derating see the manual, "Characteristic curves".

²⁾ See page 4/54.

SIRIUS 3RF23 solid-state contactors, single-phase

| | Type current ¹⁾ I_{max} | Rated control supply voltage $U_{\rm S}$ | DT | Ring terminal lug connection | (| PU (UNIT, SET, M) | PS* | PG | Weight per PU approx. |
|--|---|--|-------------|----------------------------------|-----------------|-------------------------|------------------|------------|-----------------------|
| | A | V | | Order No. | Price per PU | | | | kg |
| Zero-point switching Rated operational vo | g | | | | P 0 | | | | |
| A CONTRACTOR OF THE PARTY OF TH | 10.5 20 | 24 DC acc. to EN 61131-2 | B B | 3RF23 10-3AA02 3RF23 20-3AA02 | | 1 1 | 1 unit 1 unit | 101 101 | 0.166 0.200 |
| | 30 40 | | B B | 3RF23 30-3AA02 3RF23 40-3AA02 | | 1 1 | 1 unit 1 unit | 101 101 | 0.435 0.550 |
| .0. | 50 70 | | B A | 3RF23 50-3AA02 3RF23 70-3AA02 | | 1 | 1 unit 1 unit | 101 101 | 0.550 1.200 |
| 9 | 10.5 | 110 230 AC | B B | 3RF23 90-3AA02 3RF23 10-3AA22 | | 1 | 1 unit 1 unit | 101 | 2.900 0.166 |
| 66 | 20 30 | | B B | 3RF23 20-3AA22 3RF23 30-3AA22 | | 1 1 | 1 unit 1 unit | 101 101 | 0.200 0.435 |
| ODE00 00 0 | 40 50 | | B B | 3RF23 40-3AA22 3RF23 50-3AA22 | | 1 | 1 unit 1 unit | 101 101 | 0.550 0.550 |
| 3RF23 30-3 | 70 88 | | B B | 3RF23 70-3AA22 3RF23 90-3AA22 | | 1 1 | 1 unit 1 unit | 101 101 | 1.200 2.900 |
| Zero-point switching Rated operational vo | | V | | | | | | | |
| | 10.5 20 | 24 DC acc. to EN 61131-2 | B B | 3RF23 10-3AA04 3RF23 20-3AA04 | | 1 1 | 1 unit 1 unit | 101 101 | 0.166 0.200 |
| | 30 40 | | A B | 3RF23 30-3AA04 3RF23 40-3AA04 | | 1 1 | 1 unit 1 unit | 101 101 | 0.435 0.550 |
| | 50 70 | | B A | 3RF23 50-3AA04 3RF23 70-3AA04 | | 1 1 | 1 unit 1 unit | 101 101 | 0.550 1.200 |
| | 10.5 | 110 230 AC | A B | 3RF23 90-3AA04 3RF23 10-3AA24 | | 1 | 1 unit 1 unit | 101 | 2.900 0.166 |
| | 20 30 | | B B | 3RF23 20-3AA24 3RF23 30-3AA24 | | 1 | 1 unit 1 unit | 101 101 | 0.200 0.435 |
| | 40 50 | | B B | 3RF23 40-3AA24 3RF23 50-3AA24 | | 1 1 | 1 unit 1 unit | 101 101 | 0.550 0.550 |
| | 70 88 | | B B | 3RF23 70-3AA24 3RF23 90-3AA24 | | 1 1 | 1 unit 1 unit | 101 101 | 1.200 2.900 |
| | 20 30 | 4 30 DC | B B | 3RF23 20-3AA44 3RF23 30-3AA44 | | 1 | 1 unit 1 unit | 101 101 | 0.200 0.435 |
| Zava naint avvitahin | 50 | | B | 3RF23 50-3AA44 | | 1 | 1 unit | 101 | 0.550 |
| Zero-point switching Rated operational vo | | V | | | | | | | |
| | 40 70 | 4 30 DC | B A | 3RF23 40-3AA45 3RF23 70-3AA45 | | 1 1 | 1 unit 1 unit | 101 101 | 0.550 1.200 |
| Zero-point switching | 88 n . Blocking voltage | 1600 V | В | 3RF23 90-3AA45 | | 1 | 1 unit | 101 | 2.900 |
| rated operational vo | ltage <i>U_e 48 600 V</i> | | | | | | | | |
| | 10.5 20 | 24 DC acc. to EN 61131-2 | B B | 3RF23 10-3AA06 3RF23 20-3AA06 | | 1 1 | 1 unit 1 unit | 101 101 | 0.166 0.200 |
| | 30 40 | | B B | 3RF23 30-3AA06 3RF23 40-3AA06 | | 1 | 1 unit 1 unit | 101 | 0.435 0.550 |
| | 50 70 | | B B B | 3RF23 50-3AA06 3RF23 70-3AA06 | | 1 1 | 1 unit 1 unit | 101 101 | 0.550 1.200 |
| | 10.5 | 110 230 AC | В | 3RF23 90-3AA06 3RF23 10-3AA26 | | 1 1 | 1 unit | 101 | 2.900 0.166 |
| | 20 30 | | B B | 3RF23 20-3AA26 3RF23 30-3AA26 | | 1 | 1 unit 1 unit | 101 101 | 0.200 0.435 |
| | 40 50 | | B B | 3RF23 40-3AA26 3RF23 50-3AA26 | | 1 | 1 unit 1 unit | 101 101 | 0.550 0.550 |
| | 70 88 | | A B | 3RF23 70-3AA26 3RF23 90-3AA26 | | 1 1 | 1 unit 1 unit | 101 101 | 1.200 2.900 |

¹⁾ The type current provides information about the performance of the solid-state contactor. The actual permitted rated operational current I_e can be smaller depending on the connection method and start-up conditions. For derating see the manual, "Characteristic curves".

SIRIUS 3RF23 solid-state contactors, single-phase

| | Type current ¹⁾ I_{max} | Operational current I_e /AC-15 ²⁾ | Rated control supply voltage $U_{\rm S}$ | DT | Ring terminal lug connection | + | PU (UNIT, SET, M) | PS* | PG | Weight per PU approx. |
|---|---|--|--|--------|----------------------------------|-----------------|-------------------------|------------------|------------|-----------------------------|
| | А | Α | ٧ | | Order No. | Price per PU | | | | kg |
| Instantaneous switch Rated operational vo | | 4 230 V | | | | | | | | |
| | 70 88 | 27.5 30 | 24 DC acc. to EN 61131-2 | B B | 3RF23 70-3BA02 3RF23 90-3BA02 | | 1 1 | 1 unit 1 unit | 101 101 | 1.200 2.900 |
| | 70 88 | 27.5 30 | 110 230 AC | B B | 3RF23 70-3BA22 3RF23 90-3BA22 | | 1 1 | 1 unit 1 unit | 101 101 | 1.200 2.900 |
| Instantaneous switch Rated operational vo | | 8 460 V | | | | | | | | |
| | 70 88 | 27.5 30 | 24 DC acc. to EN 61131-2 | B B | 3RF23 70-3BA04 3RF23 90-3BA04 | | 1 1 | 1 unit 1 unit | 101 101 | 1.200 2.900 |
| | 70 88 | 27.5 30 | 110 230 AC | B B | 3RF23 70-3BA24 3RF23 90-3BA24 | | 1 1 | 1 unit 1 unit | 101 101 | 1.200 2.900 |
| Instantaneous switch Rated operational vo | | | ge 1600 V | | | | | | | |
| | 70 88 | 27.5 30 | 24 DC acc. to EN 61131-2 | B B | 3RF23 70-3BA06 3RF23 90-3BA06 | | 1 1 | 1 unit 1 unit | 101 101 | 1.200 2.900 |
| | 70 88 | 27.5 30 | 110 230 AC | B B | 3RF23 70-3BA26 3RF23 90-3BA26 | | 1 1 | 1 unit 1 unit | 101 101 | 1.200 2.900 |
| Short-circuit proof w rated operational vol | | | o-point switching, | | | | | | | |
| | 20 | | 24 DC acc. to EN 61131-2 | В | 3RF23 20-3DA02 | | 1 | 1 unit | 101 | 0.200 |
| | 20 | | 110 230 AC | В | 3RF23 20-3DA22 | | 1 | 1 unit | 101 | 0.200 |
| Short-circuit proof w rated operational vol | | | o-point switching, | | | | | | | |
| | 20 | | 24 DC acc. to EN 61131-2 | В | 3RF23 20-3DA04 | | 1 | 1 unit | 101 | 0.200 |
| | 20 | | 110 230 AC | В | 3RF23 20-3DA24 | | 1 | 1 unit | 101 | 0.200 |

²⁾ Utilization category AC-15: Electromagnetic loads, e. g. valves according to EN 60947-5. Parameters: max. 1200 1/h, 50 % ON Period, 10-times inrush current for

| | Version | DT | Order No. | Price per PU | PU (UNIT, SET, M) | PS* | PG | Weight per PU approx. kg |
|----------------------|--|----|----------------|-----------------|-------------------------|----------|-----|-----------------------------------|
| Optional accessories | | | | • | • | | | |
| | Screwdrivers for opening spring-type terminals | С | 8WA2 880 | | 1 | 1 unit | 041 | 0.034 |
| | Terminal covers for 3RF21 solid-state relays and 3RF23 solid-state contactors in ring terminal lug connection | Α | 3RF29 00-3PA88 | | 1 | 10 units | 101 | 0.004 |
| 3RF29 00-3PA88 | (after simple adaptation, this terminal cover can also be used for screw connection) | | | | | | | |

¹⁾ The type current provides information about the performance of the solid-state contactor. The actual permitted rated operational current $I_{\rm e}$ can be smaller depending on the connection method and start-up conditions. For derating see the manual, "Characteristic curves".

SIRIUS 3RF24 solid-state contactors, three-phase

Selection and ordering data

| Selection and orde | ering data | | | | | | | | |
|--|---|--|------------------|--|-----------------|-------------------------|--|---------------------------------|---|
| | Type current ¹⁾ I _{max} | Rated control supply voltage $U_{\rm S}$ | DT | Screw terminals | + | PU (UNIT, SET, M) | PS* | PG | Weight per PU approx. |
| | А | V | | Order No. | Price per PU | | | | kg |
| Zero-point switching Rated operational | ng voltage <i>U_e 48 600</i> | v | | | | | | | |
| | Two-phase cont | | | | | | | | |
| 0 0 0 | 10.5 20 30 40 50 | 4 30 DC | A A B A | 3RF24 10-1AB45 3RF24 20-1AB45 3RF24 30-1AB45 3RF24 40-1AB45 3RF24 50-1AB45 | | 1 1 1 1 | 1 unit 1 unit 1 unit 1 unit 1 unit | 101 101 101 101 101 | 0.320 0.400 0.540 0.800 1.100 |
| STATE OF THE PARTY | 10.5 20 30 40 50 | 110 AC | B B B B | 3RF24 10-1AB35 3RF24 20-1AB35 3RF24 30-1AB35 3RF24 40-1AB35 3RF24 50-1AB35 | | 1 1 1 1 | 1 unit 1 unit 1 unit 1 unit 1 unit | 101 101 101 101 101 | 0.320 0.400 0.540 0.800 1.100 |
| 3RF24 20-1AB45 | 10.5 20 30 40 50 | 230 AC | B B B B | 3RF24 10-1AB55 3RF24 20-1AB55 3RF24 30-1AB55 3RF24 40-1AB55 3RF24 50-1AB55 | | 1 1 1 1 1 | 1 unit 1 unit 1 unit 1 unit 1 unit | 101 101 101 101 101 | 0.320 0.400 0.540 0.800 1.100 |
| 0 0 | Three-phase col | ntrolled | | | | | | | |
| AAA G | 10.5 20 30 40 50 | 4 30 DC | A A A A | 3RF24 10-1AC45 3RF24 20-1AC45 3RF24 30-1AC45 3RF24 40-1AC45 3RF24 50-1AC45 | | 1 1 1 1 1 | 1 unit 1 unit 1 unit 1 unit 1 unit | 101 101 101 101 101 | 0.320 0.540 0.800 1.100 1.850 |
| THE STATE OF THE S | 10.5 20 30 40 50 | 110 AC | B B B B | 3RF24 10-1AC35 3RF24 20-1AC35 3RF24 30-1AC35 3RF24 40-1AC35 3RF24 50-1AC35 | | 1 1 1 1 1 | 1 unit 1 unit 1 unit 1 unit 1 unit | 101 101 101 101 101 | 0.320 0.540 0.800 1.100 1.850 |
| 3RF24 10-1AC45 | 10.5 20 30 40 50 | 230 AC | B B B B | 3RF24 10-1AC55 3RF24 20-1AC55 3RF24 30-1AC55 3RF24 40-1AC55 3RF24 50-1AC55 | | 1 1 1 1 | 1 unit 1 unit 1 unit 1 unit 1 unit | 101 101 101 101 101 | 0.320 0.540 0.800 1.100 1.850 |

 $^{^{1)}}$ The type current provides information about the performance of the solid-state contactor. The actual permitted rated operational current $I_{\rm e}$ can be smaller depending on the connection method and start-up conditions. For derating see the manual, "Characteristic curves".

SIRIUS 3RF24 solid-state contactors, three-phase

| | Type current ¹⁾ <i>I</i> _{max} | Rated control supply voltage $U_{\rm S}$ | DT | Spring-type terminals | <u> </u> | PU (UNIT, SET, M) | PS* | PG | Weight per PU approx. |
|--|--|--|--------|----------------------------------|-----------------|-------------------------|------------------|------------|-----------------------|
| | А | V | | Order No. | Price per PU | | | | kg |
| Zero-point switchin Rated operational v | ıg voltage <i>U_e 48 600</i> | v | | | | | | | |
| | Two-phase cont | | | | | | | | |
| 0 | 10 20 | 4 30 DC | B B | 3RF24 10-2AB45 3RF24 20-2AB45 | | 1 1 | 1 unit 1 unit | 101 101 | 0.320 0.400 |
| 6 - 1 | 10 20 | 230 AC | B B | 3RF24 10-2AB55 3RF24 20-2AB55 | | 1 1 | 1 unit 1 unit | 101 101 | 0.320 0.400 |
| SICHEDS COME | Three-phase cor | ntrolled | | | | | | | |
| | 10 20 | 4 30 DC | B B | 3RF24 10-2AC45 3RF24 20-2AC45 | | 1 1 | 1 unit 1 unit | 101 101 | 0.320 0.540 |
| 3RF24 10-2AB45 | 10 20 | 230 AC | B B | 3RF24 10-2AC55 3RF24 20-2AC55 | | 1 1 | 1 unit 1 unit | 101 101 | 0.320 0.540 |
| | | | | | | | | | |
| | Type current ¹⁾ I_{max} | Rated control supply voltage $U_{\rm S}$ | DT | Ring terminal lug connection | (| PU (UNIT, SET, M) | PS* | PG | Weight per PU approx. |
| | A | V | | Order No. | Price per PU | | | | kg |
| Zero-point switchin Rated operational v | ig voltage <i>U_e 48 600</i> | v | | | | | | | |
| • | Two-phase cont | | | | | | | | |
| | 50 | 4 30 DC | В | 3RF24 50-3AB45 | | 1 | 1 unit | 101 | 1.100 |
| | 50 | 230 AC | В | 3RF24 50-3AB55 | | 1 | 1 unit | 101 | 1.100 |
| | Three-phase cor | ntrolled | | | | | | | |
| | 50 | 4 30 DC | В | 3RF24 50-3AC45 | | 1 | 1 unit | 101 | 1.850 |
| | 50 | 230 AC | В | 3RF24 50-3AC55 | | 1 | 1 unit | 101 | 1.850 |

 $^{^{1)}}$ The type current provides information about the performance of the solid-state contactor. The actual permitted rated operational current $I_{\rm e}$ can be smaller depending on the connection method and start-up conditions. For derating see the manual, "Characteristic curves".

Solid-State Switching Devices for Resistive Loads 3RF29 Function Modules

General data

Overview

Function modules for SIRIUS 3RF2 solid-state switching devices

A great variety of applications demand an expanded range of functionality. With our function modules, these requirements can be met really easily. The modules are mounted simply by clicking them into place; straight away the necessary connections are made with the solid-state relay or contactor. The plug-in connection to control the solid-state switching devices can simply remain in use.

The following function modules are available:

- Converters
- Load monitoring
- Heating current monitoring
- Power controllers
- Power regulators

With the exception of the converter, the function modules can be used only with single-phase solid-state switching devices.

Recommended assignment of the function modules to the 3RF21 single-phase solid-state relays

| Order No. | Accessories | | | | | |
|---|--|--|--|--------------------------------------|--------------------------------------|--|
| | Converters | Load monitoring Basic | Extended | Heating current monitoring | Power controllers ¹⁾ | Power regulators ¹ |
| ype current = | 20 A | Basio | Extoriada | | | |
| RF21 20-1A.02 RF21 20-1A.04 | 3RF29 00-0EA18 3RF29 00-0EA18 | 3RF29 20-0FA08 3RF29 20-0FA08 | 3RF29 20-0GA13 3RF29 20-0GA16 | 3RF29 32-0JA16 | 3RF29 20-0KA13 3RF29 20-0KA16 | 3RF29 20-0HA13 3RF29 20-0HA16 |
| RF21 20-1A.22 RF21 20-1A.24 | | | 3RF29 20-0GA33 3RF29 20-0GA36 | | | |
| RF21 20-1A.42 RF21 20-1A.45 | 3RF29 00-0EA18 3RF29 00-0EA18 | 3RF29 20-0FA08 3RF29 20-0FA08 | 3RF29 20-0GA13 3RF29 20-0GA16 | 3RF29 32-0JA16 | 3RF29 20-0KA13 3RF29 20-0KA16 | 3RF29 20-0HA13 3RF29 20-0HA16 |
| RF21 20-1B.04 | 3RF29 00-0EA18 | 3RF29 20-0FA08 | 3RF29 20-0GA16 | 3RF29 32-0JA16 | 3RF29 20-0KA16 | 3RF29 20-0HA16 |
| RF21 20-2A.02 RF21 20-2A.04 | 3RF29 00-0EA18 3RF29 00-0EA18 | | | | | |
| RF21 20-2A.22 RF21 20-2A.24 | | | | | | |
| RF21 20-2A.42 RF21 20-2A.45 | 3RF29 00-0EA18 3RF29 00-0EA18 | | | | | |
| RF21 20-3A.02 RF21 20-3A.04 | 3RF29 00-0EA18 3RF29 00-0EA18 | | 3RF29 20-0GA13 3RF29 20-0GA16 | 3RF29 32-0JA16 | 3RF29 20-0KA16 | 3RF29 20-0HA13 3RF29 20-0HA16 |
| RF21 20-3A.22 RF21 20-3A.24 | | | 3RF29 20-0GA33 3RF29 20-0GA36 | | 3RF29 20-0KA13 3RF29 20-0KA16 | 3RF29 20-0HA13 3RF29 20-0HA16 |
| ype current = | 30 A | | | | | |
| RF21 30-1A.02 RF21 30-1A.04 RF21 30-1A.06 | 3RF29 00-0EA18 3RF29 00-0EA18 3RF29 00-0EA18 | 3RF29 20-0FA08 3RF29 20-0FA08 3RF29 20-0FA08 | 3RF29 50-0GA13 3RF29 50-0GA16 3RF29 50-0GA16 | 3RF29 32-0JA16 3RF29 32-0JA16 | 3RF29 50-0KA16 3RF29 50-0KA16 | 3RF29 50-0HA13 3RF29 50-0HA16 3RF29 50-0HA16 |
| RF21 30-1A.22 RF21 30-1A.24 RF21 30-1A.26 | | | 3RF29 50-0GA33 3RF29 50-0GA36 3RF29 50-0GA36 | | | 3RF29 50-0HA33 3RF29 50-0HA36 3RF29 50-0HA36 |
| RF21 30-1A.42 RF21 30-1A.45 | 3RF29 00-0EA18 3RF29 00-0EA18 | 3RF29 20-0FA08 3RF29 20-0FA08 | 3RF29 50-0GA13 3RF29 50-0GA16 | 3RF29 32-0JA16 | 3RF29 50-0KA16 | 3RF29 50-0HA13 3RF29 50-0HA16 |
| RF21 30-1B.04 | 3RF29 00-0EA18 | 3RF29 20-0FA08 | 3RF29 50-0GA16 | 3RF29 32-0JA16 | 3RF29 50-0KA16 | 3RF29 50-0HA16 |
| ype current = | 50 A | | | | | |
| RF21 50-1A.02 RF21 50-1A.04 RF21 50-1A.06 | 3RF29 00-0EA18 3RF29 00-0EA18 3RF29 00-0EA18 | 3RF29 20-0FA08 3RF29 20-0FA08 3RF29 20-0FA08 | 3RF29 50-0GA13 3RF29 50-0GA16 3RF29 50-0GA16 | 3RF29 32-0JA16 3RF29 32-0JA16 | 3RF29 50-0KA16 3RF29 50-0KA16 | 3RF29 50-0HA13 3RF29 50-0HA16 3RF29 50-0HA16 |
| RF21 50-1A.22 RF21 50-1A.24 RF21 50-1A.26 | | | 3RF29 50-0GA33 3RF29 50-0GA36 3RF29 50-0GA36 | | | 3RF29 50-0HA33 3RF29 50-0HA36 3RF29 50-0HA36 |
| RF21 50-1A.45 | 3RF29 00-0EA18 | 3RF29 20-0FA08 | 3RF29 50-0GA16 | 3RF29 32-0JA16 | 3RF29 50-0KA16 | 3RF29 50-0HA16 |
| RF21 50-1B.04 RF21 50-1B.06 | 3RF29 00-0EA18 3RF29 00-0EA18 | 3RF29 20-0FA08 3RF29 20-0FA08 | 3RF29 50-0GA16 3RF29 50-0GA16 | 3RF29 32-0JA16 3RF29 32-0JA16 | 3RF29 50-0KA16 3RF29 50-0KA16 | 3RF29 50-0HA16 3RF29 50-0HA16 |
| RF21 50-1B.22 | | | 3RF29 50-0GA33 | | | 3RF29 50-0HA33 |
| RF21 50-2A.02 RF21 50-2A.04 | 3RF29 00-0EA18 3RF29 00-0EA18 | | | | | |
| RF21 50-2A.06 RF21 50-2A.14 | 3RF29 00-0EA18 3RF29 00-0EA18 | | | | | |
| RF21 50-2A.14 | | | | | | |
| RF21 50-2A.22 RF21 50-2A.24 RF21 50-2A.26 | | | | | | |
| RF21 50-3A.02 RF21 50-3A.04 RF21 50-3A.06 | 3RF29 00-0EA18 3RF29 00-0EA18 3RF29 00-0EA18 | | 3RF29 50-0GA13 3RF29 50-0GA16 3RF29 50-0GA16 | 3RF29 32-0JA16 3RF29 32-0JA16 | 3RF29 50-0KA16 3RF29 50-0KA16 | 3RF29 50-0HA13 3RF29 50-0HA16 3RF29 50-0HA16 |
| RF21 50-3A.22 RF21 50-3A.24 RF21 50-3A.26 | | | 3RF29 50-0GA33 3RF29 50-0GA36 3RF29 50-0GA36 | | | 3RF29 50-0HA33 3RF29 50-0HA36 3RF29 50-0HA36 |

¹⁾ The use of power controllers/regulators is also possible on zero-point switching versions for full-wave control mode. The generalized phase control mode is recommended only for the combination with instantaneous switching versions.

Solid-State Switching Devices for Resistive Loads 3RF29 Function Modules

General data

| Order No. | Accessories | | | | | |
|--|--|--|--|--|--|--|
| | Converters | Load monitoring Basic | Extended | Heating current monitoring | Power controllers ¹⁾ | Power regulators ¹⁾ |
| Type current = | 70 A | Buolo | Exteriada | | | |
| 3RF21 70-1A.02 3RF21 70-1A.04 3RF21 70-1A.05 3RF21 70-1A.06 | 3RF29 00-0EA18 3RF29 00-0EA18 3RF29 00-0EA18 3RF29 00-0EA18 | 3RF29 20-0FA08 3RF29 20-0FA08 3RF29 20-0FA08 3RF29 20-0FA08 | 3RF29 50-0GA13 3RF29 50-0GA16 3RF29 50-0GA16 3RF29 50-0GA16 | 3RF29 32-0JA16 3RF29 32-0JA16 3RF29 32-0JA16 | 3RF29 50-0KA16 3RF29 50-0KA16 3RF29 50-0KA16 | 3RF29 50-0HA13 3RF29 50-0HA16 3RF29 50-0HA16 3RF29 50-0HA16 |
| 3RF21 70-1A.22 3RF21 70-1A.24 3RF21 70-1A.26 | | | 3RF29 50-0GA33 3RF29 50-0GA36 3RF29 50-0GA36 | | | 3RF29 50-0HA33 3RF29 50-0HA36 3RF29 50-0HA36 |
| 3RF21 70-1A.45 | 3RF29 00-0EA18 | 3RF29 20-0FA08 | 3RF29 50-0GA16 | 3RF29 32-0JA16 | 3RF29 50-0KA16 | 3RF29 50-0HA16 |
| 3RF21 70-1B.04 | 3RF29 00-0EA18 | 3RF29 20-0FA08 | 3RF29 50-0GA16 | 3RF29 32-0JA16 | 3RF29 50-0KA16 | 3RF29 50-0HA16 |
| 3RF21 70-1C.04 | 3RF29 00-0EA18 | 3RF29 20-0FA08 | 3RF29 50-0GA16 | 3RF29 32-0JA16 | 3RF29 50-0KA16 | 3RF29 50-0HA16 |
| Type current = | 90 A | | | | | |
| BRF21 90-1A.02 BRF21 90-1A.04 BRF21 90-1A.06 | 3RF29 00-0EA18 3RF29 00-0EA18 3RF29 00-0EA18 | 3RF29 20-0FA08 3RF29 20-0FA08 3RF29 20-0FA08 | 3RF29 50-0GA13 3RF29 50-0GA16 3RF29 50-0GA16 | 3RF29 32-0JA16 3RF29 32-0JA16 | 3RF29 50-0KA16 3RF29 50-0KA16 | 3RF29 50-0HA13 3RF29 50-0HA16 3RF29 50-0HA16 |
| 3RF21 90-1A.22 3RF21 90-1A.24 3RF21 90-1A.26 | | | 3RF29 50-0GA33 3RF29 50-0GA36 3RF29 50-0GA36 | | | 3RF29 50-0HA33 3RF29 50-0HA36 3RF29 50-0HA36 |
| RF21 90-1A.45 | 3RF29 00-0EA18 | 3RF29 20-0FA08 | 3RF29 50-0GA16 | 3RF29 32-0JA16 | 3RF29 50-0KA16 | 3RF29 50-0HA16 |
| RF21 90-1B.04 | 3RF29 00-0EA18 | 3RF29 20-0FA08 | 3RF29 50-0GA16 | 3RF29 32-0JA16 | 3RF29 50-0KA16 | 3RF29 50-0HA16 |
| BRF21 90-2A.02 BRF21 90-2A.04 BRF21 90-2A.06 | 3RF29 00-0EA18 3RF29 00-0EA18 3RF29 00-0EA18 | | | | | |
| BRF21 90-2A.22 BRF21 90-2A.24 BRF21 90-2A.26 | | | | | | |
| BRF21 90-3A.02 BRF21 90-3A.04 BRF21 90-3A.06 | 3RF29 00-0EA18 3RF29 00-0EA18 3RF29 00-0EA18 | | 3RF29 90-0GA13 3RF29 90-0GA16 3RF29 90-0GA16 | 3RF29 32-0JA16 3RF29 32-0JA16 | 3RF29 90-0KA16 3RF29 90-0KA16 | 3RF29 90-0HA13 3RF29 90-0HA16 3RF29 90-0HA16 |
| BRF21 90-3A.22 BRF21 90-3A.24 BRF21 90-3A.26 | | | 3RF29 90-0GA33 3RF29 90-0GA36 3RF29 90-0GA36 | | | 3RF29 90-0HA33 3RF29 90-0HA36 3RF29 90-0HA36 |
| 3RF21 90-3A.44 | 3RF29 00-0EA18 | | 3RF29 90-0GA16 | 3RF29 32-0JA16 | 3RF29 90-0KA16 | 3RF29 90-0HA16 |

¹⁾ The use of power controllers/regulators is also possible on zero-point switching versions for full-wave control mode. The generalized phase con-trol mode is recommended only for the combination with instantaneous

Recommended assignment of the function modules to the 3RF22 three-phase solid-state relays

| Order No. Accessories | | | | | | | | | |
|-----------------------|----------------|-----------------|----------|-----------------|-------------------|------------------|--|--|--|
| | Converters | Load monitoring | | Heating current | Power controllers | Power regulators | | | |
| | | Basic | Extended | monitoring | | | | | |
| Type current u | p to 55 A | | | | | | | | |
| 3RF221A | 3RF29 00-0EA18 | | | | | | | | |
| 3RF222A | 3RF29 00-0EA18 | | | | | | | | |
| 3RF223A | 3RF29 00-0EA18 | | | | | | | | |

Recommended assignment of the function modules to the 3RF23 single-phase solid-state contactors

| Order No. | Accessories | | | | | |
|--|--|--|--|--|--|--|
| | Converters | Load monitoring | | Heating current | Power controllers ¹⁾ | Power regulators ¹⁾ |
| | | Basic | Extended | monitoring | | |
| Type current I _e | _s = 10.5 A | | | | | |
| 3RF23 10-1A.02 3RF23 10-1A.04 3RF23 10-1A.06 | 3RF29 00-0EA18 3RF29 00-0EA18 3RF29 00-0EA18 | 3RF29 20-0FA08 3RF29 20-0FA08 3RF29 20-0FA08 | 3RF29 20-0GA13 3RF29 20-0GA16 3RF29 20-0GA16 | 3RF29 16-0JA13 3RF29 32-0JA16 3RF29 32-0JA16 | 3RF29 20-0KA13 3RF29 20-0KA16 3RF29 20-0KA16 | 3RF29 20-0HA13 3RF29 20-0HA16 3RF29 20-0HA16 |
| 3RF23 10-1A.12 3RF23 10-1A.14 | 3RF29 00-0EA18 3RF29 00-0EA18 | | 3RF29 20-0GA13 3RF29 20-0GA16 | 3RF29 16-0JA13 3RF29 32-0JA16 | 3RF29 20-0KA13 3RF29 20-0KA16 | 3RF29 20-0HA13 3RF29 20-0HA16 |
| 3RF23 10-1A.22 3RF23 10-1A.24 3RF23 10-1A.26 | | | 3RF29 20-0GA33 3RF29 20-0GA36 3RF29 20-0GA36 | | | 3RF29 20-0HA33 3RF29 20-0HA36 3RF29 20-0HA36 |
| 3RF23 10-1A.44 3RF23 10-1A.45 | 3RF29 00-0EA18 3RF29 00-0EA18 | 3RF29 20-0FA08 3RF29 20-0FA08 | 3RF29 20-0GA16 3RF29 20-0GA16 | 3RF29 32-0JA16 3RF29 32-0JA16 | 3RF29 20-0KA16 3RF29 20-0KA16 | 3RF29 20-0HA16 3RF29 20-0HA16 |

Solid-State Switching Devices for Resistive Loads 3RF29 Function Modules

General data

| Order No. | Accessories | | | | | |
|--|--|--|--|--|--|--|
| | Converters | Load monitoring | | Heating current monitoring | Power controllers ¹⁾ | Power regulators ¹⁾ |
| was surrent I | - 10 F A | Basic | Extended | | | |
| ype current I _e | _ | 00500 00 05400 | 00500 00 00 440 | 0DE00 10 0 IA10 | 00500 00 01/440 | 0DE00 00 011440 |
| RF23 10-1B.02 RF23 10-1B.04 RF23 10-1B.06 | 3RF29 00-0EA18 3RF29 00-0EA18 3RF29 00-0EA18 | 3RF29 20-0FA08 3RF29 20-0FA08 3RF29 20-0FA08 | 3RF29 20-0GA13 3RF29 20-0GA16 3RF29 20-0GA16 | 3RF29 16-0JA13 3RF29 32-0JA16 3RF29 32-0JA16 | 3RF29 20-0KA13 3RF29 20-0KA16 3RF29 20-0KA16 | 3RF29 20-0HA13 3RF29 20-0HA16 3RF29 20-0HA16 |
| RF23 10-1B.22 RF23 10-1B.24 RF23 10-1B.26 | | | 3RF29 20-0GA33 3RF29 20-0GA36 3RF29 20-0GA36 | | | 3RF29 20-0HA33 3RF29 20-0HA36 3RF29 20-0HA36 |
| RF23 10-2A.02 RF23 10-2A.04 RF23 10-2A.06 | 3RF29 00-0EA18 3RF29 00-0EA18 3RF29 00-0EA18 | | | | | |
| RF23 10-2A.22 RF23 10-2A.22 | | | | | | |
| RF23 10-2A.26 | | | | | | |
| RF23 10-3A.02 RF23 10-3A.04 RF23 10-3A.06 | 3RF29 00-0EA18 3RF29 00-0EA18 3RF29 00-0EA18 | | 3RF29 20-0GA13 3RF29 20-0GA16 3RF29 20-0GA16 | 3RF29 16-0JA13 3RF29 32-0JA16 3RF29 32-0JA16 | 3RF29 20-0KA13 3RF29 20-0KA16 3RF29 20-0KA16 | 3RF29 20-0HA13 3RF29 20-0HA16 3RF29 20-0HA16 |
| RF23 10-3A.22 RF23 10-3A.24 RF23 10-3A.26 | | | 3RF29 20-0GA33 3RF29 20-0GA36 3RF29 20-0GA36 | | | 3RF29 20-0HA33 3RF29 20-0HA36 3RF29 20-0HA36 |
| ype current I_e | = 20 A | | | | | 0 20 20 0 |
| RF23 20-1A.02 RF23 20-1A.04 RF23 20-1A.06 | 3RF29 00-0EA18 3RF29 00-0EA18 3RF29 00-0EA18 | 3RF29 20-0FA08 3RF29 20-0FA08 3RF29 20-0FA08 | 3RF29 20-0GA13 3RF29 20-0GA16 3RF29 20-0GA16 | 3RF29 32-0JA16 3RF29 32-0JA16 | 3RF29 20-0KA13 3RF29 20-0KA16 3RF29 20-0KA16 | 3RF29 20-0HA13 3RF29 20-0HA16 3RF29 20-0HA16 |
| RF23 20-1A.14 | 3RF29 00-0EA18 | | 3RF29 20-0GA16 | | 3RF29 20-0KA16 | 3RF29 20-0HA16 |
| RF23 20-1A.22 RF23 20-1A.24 RF23 20-1A.26 | | | 3RF29 20-0GA33 3RF29 20-0GA36 3RF29 20-0GA36 | | | 3RF29 20-0HA33 3RF29 20-0HA36 3RF29 20-0HA36 |
| RF23 20-1A.44 RF23 20-1A.45 | 3RF29 00-0EA18 3RF29 00-0EA18 | 3RF29 20-0FA08 3RF29 20-0FA08 | 3RF29 20-0GA16 3RF29 20-0GA16 | 3RF29 32-0JA16 3RF29 32-0JA16 | 3RF29 20-0KA16 3RF29 20-0KA16 | 3RF29 20-0HA16 3RF29 20-0HA16 |
| RF23 20-1B.02 RF23 20-1B.04 RF23 20-1B.06 | 3RF29 00-0EA18 3RF29 00-0EA18 3RF29 00-0EA18 | 3RF29 20-0FA08 3RF29 20-0FA08 3RF29 20-0FA08 | 3RF29 20-0GA13 3RF29 20-0GA16 3RF29 20-0GA16 | 3RF29 32-0JA16 3RF29 32-0JA16 | 3RF29 20-0KA13 3RF29 20-0KA16 3RF29 20-0KA16 | 3RF29 20-0HA13 3RF29 20-0HA16 3RF29 20-0HA16 |
| RF23 20-1B.22 RF23 20-1B.24 RF23 20-1B.26 | | | 3RF29 20-0GA33 3RF29 20-0GA36 3RF29 20-0GA36 | | | 3RF29 20-0HA33 3RF29 20-0HA36 3RF29 20-0HA36 |
| RF23 20-1B.44 | 3RF29 00-0EA18 | 3RF29 20-0FA08 | 3RF29 20-0GA16 | 3RF29 32-0JA16 | 3RF29 20-0KA16 | 3RF29 20-0HA16 |
| RF23 20-1C.02 RF23 20-1C.04 | 3RF29 00-0EA18 3RF29 00-0EA18 | 3RF29 20-0FA08 3RF29 20-0FA08 | 3RF29 20-0GA13 3RF29 20-0GA16 | 3RF29 32-0JA16 | 3RF29 20-0KA13 3RF29 20-0KA16 | 3RF29 20-0HA13 3RF29 20-0HA16 |
| RF23 20-1C.22 RF23 20-1C.24 | | | 3RF29 20-0GA33 3RF29 20-0GA36 | | | 3RF29 20-0HA33 3RF29 20-0HA36 |
| RF23 20-1C.44 | 3RF29 00-0EA18 | 3RF29 20-0FA08 | 3RF29 20-0GA16 | 3RF29 32-0JA16 | 3RF29 20-0KA16 | 3RF29 20-0HA16 |
| RF23 20-1D.02 RF23 20-1D.04 | 3RF29 00-0EA18 3RF29 00-0EA18 | 3RF29 20-0FA08 3RF29 20-0FA08 | 3RF29 20-0GA13 3RF29 20-0GA16 | 3RF29 32-0JA16 | 3RF29 20-0KA13 3RF29 20-0KA16 | 3RF29 20-0HA13 3RF29 20-0HA16 |
| RF23 20-1D.22 RF23 20-1D.24 | | | 3RF29 20-0GA33 3RF29 20-0GA36 | | | 3RF29 20-0HA33 3RF29 20-0HA36 |
| RF23 20-1D.44 | 3RF29 00-0EA18 | 3RF29 20-0FA08 | 3RF29 20-0GA16 | 3RF29 32-0JA16 | 3RF29 20-0KA16 | 3RF29 20-0HA16 |
| RF23 20-2A.02 RF23 20-2A.04 RF23 20-2A.06 | 3RF29 00-0EA18 3RF29 00-0EA18 3RF29 00-0EA18 | | | | | |
| RF23 20-2A.22 RF23 20-2A.24 | | | | | | |
| RF23 20-2A.26 RF23 20-2C.02 RF23 20-2C.04 | 3RF29 00-0EA18 3RF29 00-0EA18 | | | | | |
| RF23 20-2C.22 RF23 20-2C.24 | | | | | | |
| RF23 20-2D.22 RF23 20-2D.24 | | | | | | |
| RF23 20-3A.02 RF23 20-3A.04 RF23 20-3A.06 | 3RF29 00-0EA18 3RF29 00-0EA18 3RF29 00-0EA18 | | 3RF29 20-0GA13 3RF29 20-0GA16 3RF29 20-0GA16 | 3RF29 32-0JA16 3RF29 32-0JA16 | 3RF29 20-0KA13 3RF29 20-0KA16 3RF29 20-0KA16 | 3RF29 20-0HA13 3RF29 20-0HA16 3RF29 20-0HA16 |
| BRF23 20-3A.22 BRF23 20-3A.24 BRF23 20-3A.26 | | | 3RF29 20-0GA33 3RF29 20-0GA36 3RF29 20-0GA36 | | | 3RF29 20-0HA33 3RF29 20-0HA36 3RF29 20-0HA36 |
| RF23 20-3A.44 | 3RF29 00-0EA18 | | 3RF29 20-0GA16 | 3RF29 32-0JA16 | 3RF29 20-0KA16 | 3RF29 20-0HA16 |

¹⁾ The use of power controllers/regulators is also possible on zero-point switching versions for full-wave control mode. The generalized phase control mode is recommended only for the combination with instantaneous switching versions.

| Order No. | Accessories | | | | | |
|--|--|--|--|--------------------------------------|--------------------------------------|--|
| | Converters | Load monitoring | | Heating current monitoring | Power controllers ¹⁾ | Power regulators ¹ |
| | | Basic | Extended | monitoring | | |
| ype current $I_{\rm e}$ | | | | | | |
| RF23 20-3D.02 RF23 20-3D.04 | 3RF29 00-0EA18 3RF29 00-0EA18 | | 3RF29 20-0GA13 3RF29 20-0GA16 | 3RF29 32-0JA16 | 3RF29 20-0KA13 3RF29 20-0KA16 | 3RF29 20-0HA13 3RF29 20-0HA16 |
| RF23 20-3D.22 RF23 20-3D.24 | | | 3RF29 20-0GA33 3RF29 20-0GA36 | | | 3RF29 20-0HA33 3RF29 20-0HA36 |
| Гуре current $I_{ m e}$ | , = 30 A | | | | | |
| BRF23 30-1A.02 BRF23 30-1A.04 BRF23 30-1A.06 | 3RF29 00-0EA18 3RF29 00-0EA18 3RF29 00-0EA18 | 3RF29 20-0FA08 3RF29 20-0FA08 3RF29 20-0FA08 | 3RF29 50-0GA13 3RF29 50-0GA16 3RF29 50-0GA16 | 3RF29 32-0JA16 3RF29 32-0JA16 | 3RF29 50-0KA16 3RF29 50-0KA16 | 3RF29 50-0HA13 3RF29 50-0HA16 3RF29 50-0HA16 |
| RF23 30-1A.14 | 3RF29 00-0EA18 | | 3RF29 50-0GA16 | 3RF29 32-0JA16 | 3RF29 50-0KA16 | 3RF29 50-0HA16 |
| BRF23 30-1A.22 BRF23 30-1A.24 BRF23 30-1A.25 BRF23 30-1A.26 | | | 3RF29 50-0GA33 3RF29 50-0GA36 3RF29 50-0GA36 3RF29 50-0GA36 | | <u>-</u> | 3RF29 50-0HA33 3RF29 50-0HA36 3RF29 50-0HA36 3RF29 50-0HA36 |
| BRF23 30-1A.44 BRF23 30-1A.45 | 3RF29 00-0EA18 3RF29 00-0EA18 | | 3RF29 50-0GA16 3RF29 50-0GA16 | 3RF29 32-0JA16 3RF29 32-0JA16 | 3RF29 50-0KA16 3RF29 50-0KA16 | 3RF29 50-0HA16 3RF29 50-0HA16 |
| 3RF23 30-1B.02 3RF23 30-1B.04 3RF23 30-1B.06 | 3RF29 00-0EA18 3RF29 00-0EA18 3RF29 00-0EA18 | 3RF29 20-0FA08 3RF29 20-0FA08 3RF29 20-0FA08 | 3RF29 50-0GA13 3RF29 50-0GA16 3RF29 50-0GA16 | 3RF29 32-0JA16 3RF29 32-0JA16 | 3RF29 50-0KA16 3RF29 50-0KA16 | 3RF29 50-0HA13 3RF29 50-0HA16 3RF29 50-0HA16 |
| 3RF23 30-1B.22 3RF23 30-1B.24 3RF23 30-1B.26 | | | 3RF29 50-0GA33 3RF29 50-0GA36 3RF29 50-0GA36 | | | 3RF29 50-0HA33 3RF29 50-0HA36 3RF29 50-0HA36 |
| 3RF23 30-1B.44 | 3RF29 00-0EA18 | | 3RF29 50-0GA16 | 3RF29 32-0JA16 | 3RF29 50-0KA16 | 3RF29 50-0HA16 |
| 3RF23 30-1C.02 | 3RF29 00-0EA18 | 3RF29 20-0FA08 | 3RF29 50-0GA13 | | | 3RF29 50-0HA13 |
| BRF23 30-1D.44 | 3RF29 00-0EA18 | | 3RF29 50-0GA16 | 3RF29 32-0JA16 | 3RF29 50-0KA16 | 3RF29 50-0HA16 |
| 3RF23 30-3A.02 3RF23 30-3A.04 3RF23 30-3A.06 | 3RF29 00-0EA18 3RF29 00-0EA18 3RF29 00-0EA18 | | 3RF29 50-0GA13 3RF29 50-0GA16 3RF29 50-0GA16 | 3RF29 32-0JA16 3RF29 32-0JA16 | 3RF29 50-0KA16 3RF29 50-0KA16 | 3RF29 50-0HA13 3RF29 50-0HA16 3RF29 50-0HA16 |
| 3RF23 30-3A.22 3RF23 30-3A.24 3RF23 30-3A.26 | | | 3RF29 50-0GA33 3RF29 50-0GA36 3RF29 50-0GA36 | | | 3RF29 50-0HA33 3RF29 50-0HA36 3RF29 50-0HA36 |
| 3RF23 30-3A.44 | 3RF29 00-0EA18 | | 3RF29 50-0GA16 | 3RF29 32-0JA16 | 3RF29 50-0KA16 | 3RF29 50-0HA16 |
| Type current I_{e} | , = 40 A | | | | | |
| 3RF23 40-1A.02 3RF23 40-1A.04 3RF23 40-1A.06 | 3RF29 00-0EA18 3RF29 00-0EA18 3RF29 00-0EA18 | | 3RF29 50-0GA13 3RF29 50-0GA16 3RF29 50-0GA16 | | 3RF29 50-0KA16 3RF29 50-0KA16 | 3RF29 50-0HA13 3RF29 50-0HA16 3RF29 50-0HA16 |
| 3RF23 40-1A.14 | 3RF29 00-0EA18 | | 3RF29 50-0GA16 | | 3RF29 50-0KA16 | 3RF29 50-0HA16 |
| BRF23 40-1A.22 BRF23 40-1A.24 BRF23 40-1A.26 | | | 3RF29 50-0GA33 3RF29 50-0GA36 3RF29 50-0GA36 | | | 3RF29 50-0HA33 3RF29 50-0HA36 3RF29 50-0HA36 |
| 3RF23 40-1A.45 | 3RF29 00-0EA18 | | 3RF29 50-0GA16 | | 3RF29 50-0KA16 | 3RF29 50-0HA16 |
| 3RF23 40-1B.02 3RF23 40-1B.04 3RF23 40-1B.06 | 3RF29 00-0EA18 3RF29 00-0EA18 3RF29 00-0EA18 | | 3RF29 50-0GA13 3RF29 50-0GA13 3RF29 50-0GA13 | | 3RF29 50-0KA16 3RF29 50-0KA16 | 3RF29 50-0HA13 3RF29 50-0HA16 3RF29 50-0HA16 |
| 3RF23 40-1B.22 3RF23 40-1B.24 3RF23 40-1B.26 | | | 3RF29 50-0GA33 3RF29 50-0GA36 3RF29 50-0GA36 | | | 3RF29 50-0HA33 3RF29 50-0HA36 3RF29 50-0HA36 |
| 3RF23 40-3A.02 3RF23 40-3A.04 3RF23 40-3A.06 | 3RF29 00-0EA18 3RF29 00-0EA18 3RF29 00-0EA18 | | 3RF29 50-0GA13 3RF29 50-0GA16 3RF29 50-0GA16 | | 3RF29 50-0KA16 3RF29 50-0KA16 | 3RF29 50-0HA13 3RF29 50-0HA16 3RF29 50-0HA16 |
| 3RF23 40-3A.22 3RF23 40-3A.24 3RF23 40-3A.26 | | | 3RF29 50-0GA33 3RF29 50-0GA36 3RF29 50-0GA36 | | | 3RF29 50-0HA33 3RF29 50-0HA36 3RF29 50-0HA36 |
| 3RF23 40-3A.45 | 3RF29 00-0EA18 | | 3RF29 50-0GA16 | | 3RF29 50-0KA16 | 3RF29 50-0HA16 |
| Type current I _e | , = 50 A | | | | | |
| BRF23 50-1A.02 BRF23 50-1A.04 BRF23 50-1A.06 | 3RF29 00-0EA18 3RF29 00-0EA18 3RF29 00-0EA18 | | 3RF29 50-0GA13 3RF29 50-0GA16 3RF29 50-0GA16 | | 3RF29 50-0KA16 3RF29 50-0KA16 | 3RF29 50-0HA13 3RF29 50-0HA16 3RF29 50-0HA16 |
| 3RF23 50-1A.14 | 3RF29 00-0EA18 | | 3RF29 50-0GA16 | | 3RF29 50-0KA16 | 3RF29 50-0HA16 |
| 3RF23 50-1A.22 3RF23 50-1A.24 3RF23 50-1A.26 | | | 3RF29 50-0GA33 3RF29 50-0GA36 3RF29 50-0GA36 | | | 3RF29 50-0HA33 3RF29 50-0HA36 3RF29 50-0HA36 |
| 3RF23 50-1A.45 | 3RF29 00-0EA18 | | 3RF29 50-0GA16 | | 3RF29 50-0KA16 | 3RF29 50-0HA16 |

¹⁾ The use of power controllers/regulators is also possible on zero-point switching versions for full-wave control mode. The generalized phase con-trol mode is recommended only for the combination with instantaneous switching versions.

Solid-State Switching Devices for Resistive Loads 3RF29 Function Modules

General data

| order No. | Accessories | | | | | |
|--------------------------------|----------------------------------|-----------------|----------------------------------|-----------------|----------------------------------|----------------------------------|
| | Converters | Load monitoring | | Heating current | Power controllers ¹⁾ | Power regulators ¹ |
| | | Basic | Extended | monitoring | | |
| ype current I | _e = 50 A | _ | | _ | | |
| RF23 50-1B.02 | 3RF29 00-0EA18 | | 3RF29 50-0GA13 | | | 3RF29 50-0HA13 |
| RF23 50-1B.04 | 3RF29 00-0EA18 | | 3RF29 50-0GA16 | | 3RF29 50-0KA16 | 3RF29 50-0HA16 |
| RF23 50-1B.06 | 3RF29 00-0EA18 | | 3RF29 50-0GA16 | | 3RF29 50-0KA16 | 3RF29 50-0HA16 |
| RF23 50-1B.22 RF23 50-1B.24 | | | 3RF29 50-0GA33 | | | 3RF29 50-0HA33 |
| RF23 50-1B.24 | | | 3RF29 50-0GA36 3RF29 50-0GA36 | | | 3RF29 50-0HA36 3RF29 50-0HA36 |
| RF23 50-1B.44 | 3RF29 00-0EA18 | | 3RF29 50-0GA16 | | 3RF29 50-0KA16 | 3RF29 50-0HA16 |
| RF23 50-3A.02 | 3RF29 00-0EA18 | | 3RF29 50-0GA13 | | | 3RF29 50-0HA13 |
| RF23 50-3A.04 | 3RF29 00-0EA18 | | 3RF29 50-0GA16 | | 3RF29 50-0KA16 | 3RF29 50-0HA16 |
| RF23 50-3A.06 | 3RF29 00-0EA18 | | 3RF29 50-0GA16 | | 3RF29 50-0KA16 | 3RF29 50-0HA16 |
| RF23 50-3A.22 | | | 3RF29 50-0GA33 | | | 3RF29 50-0HA33 |
| RF23 50-3A.24 RF23 50-3A.26 | | | 3RF29 50-0GA36 3RF29 50-0GA36 | | | 3RF29 50-0HA36 3RF29 50-0HA36 |
| RF23 50-3A.44 | 3RF29 00-0EA18 | | 3RF29 50-0GA16 | | 3RF29 50-0KA16 | 3RF29 50-0HA16 |
| pe current I | | | 5. ii 20 30 00/110 | | 3.1. 20 00 010 110 | 21.1. 20 30 01 1/(10 |
| RF23 70-1B.02 | 3RF29 00-0EA18 | | 3RF29 50-0GA13 | | | 3RF29 50-0HA13 |
| RF23 70-1B.02 | 3RF29 00-0EA18 | | 3RF29 50-0GA16 | | 3RF29 50-0KA16 | 3RF29 50-0HA16 |
| RF23 70-1B.06 | 3RF29 00-0EA18 | | 3RF29 50-0GA16 | | 3RF29 50-0KA16 | 3RF29 50-0HA16 |
| RF23 70-1B.22 | | | 3RF29 50-0GA33 | | | 3RF29 50-0HA33 |
| RF23 70-1B.24 | | | 3RF29 50-0GA36 3RF29 50-0GA36 | | | 3RF29 50-0HA36 |
| RF23 70-1B.26 | | | | | | 3RF29 50-0HA36 |
| RF23 70-3A.02 RF23 70-3A.04 | 3RF29 00-0EA18 3RF29 00-0EA18 | | 3RF29 90-0GA13 3RF29 90-0GA16 | | 3RF29 90-0KA16 | 3RF29 90-0HA13 3RF29 90-0HA16 |
| RF23 70-3A.06 | 3RF29 00-0EA18 | | 3RF29 90-0GA16 | | 3RF29 90-0KA16 | 3RF29 90-0HA16 |
| RF23 70-3A.22 | | | 3RF29 90-0GA33 | | | 3RF29 90-0HA33 |
| RF23 70-3A.24 | | | 3RF29 90-0GA36 | | | 3RF29 90-0HA36 |
| RF23 70-3A.26 | | | 3RF29 90-0GA36 | | | 3RF29 90-0HA36 |
| RF23 70-3A.45 | 3RF29 00-0EA18 | | 3RF29 90-0GA16 | | 3RF29 90-0KA16 | 3RF29 90-0HA16 |
| RF23 70-3B.02 RF23 70-3B.04 | 3RF29 00-0EA18 3RF29 00-0EA18 | | 3RF29 90-0GA13 3RF29 90-0GA16 | | 3RF29 90-0KA16 | 3RF29 90-0HA13 3RF29 90-0HA16 |
| RF23 70-3B.06 | 3RF29 00-0EA18 | | 3RF29 90-0GA16 | | 3RF29 90-0KA16 | 3RF29 90-0HA16 |
| RF23 70-3B.22 | | | 3RF29 90-0GA33 | | | 3RF29 90-0HA33 |
| RF23 70-3B.24 | | | 3RF29 90-0GA36 | | | 3RF29 90-0HA36 |
| RF23 70-3B.26 | | | 3RF29 90-0GA36 | | | 3RF29 90-0HA36 |
| ype current I_{ϵ} | <u> </u> | | | | | |
| RF23 90-1B.02 | 3RF29 00-0EA18 | | 3RF29 50-0GA13 | | 2DE00 E0 01/440 | 3RF29 50-0HA13 |
| RF23 90-1B.04 RF23 90-1B.06 | 3RF29 00-0EA18 3RF29 00-0EA18 | | 3RF29 50-0GA16 3RF29 50-0GA16 | | 3RF29 50-0KA16 3RF29 50-0KA16 | 3RF29 50-0HA16 3RF29 50-0HA16 |
| RF23 90-1B.22 | | | 3RF29 50-0GA33 | | | 3RF29 50-0HA33 |
| RF23 90-1B.24 | | | 3RF29 50-0GA36 | | | 3RF29 50-0HA36 |
| RF23 90-1B.26 | | | 3RF29 50-0GA36 | | | 3RF29 50-0HA36 |
| RF23 90-3A.02 | 3RF29 00-0EA18 | | 3RF29 90-0GA13 | | | 3RF29 90-0HA13 |
| RF23 90-3A.04 RF23 90-3A.06 | 3RF29 00-0EA18 3RF29 00-0EA18 | | 3RF29 90-0GA16 3RF29 90-0GA16 | | 3RF29 90-0KA16 3RF29 90-0KA16 | 3RF29 90-0HA16 3RF29 90-0HA16 |
| RF23 90-3A.22 | | | 3RF29 90-0GA33 | | | 3RF29 90-0HA33 |
| RF23 90-3A.24 | | | 3RF29 90-0GA36 | | | 3RF29 90-0HA36 |
| RF23 90-3A.26 | | | 3RF29 90-0GA36 | | | 3RF29 90-0HA36 |
| RF23 90-3A.45 | 3RF29 00-0EA18 | | 3RF29 90-0GA16 | | 3RF29 90-0KA16 | 3RF29 90-0HA16 |
| RF23 90-3B.02 | 3RF29 00-0EA18 | | 3RF29 90-0GA13 | | - | 3RF29 90-0HA13 |
| RF23 90-3B.04 | 3RF29 00-0EA18 | | 3RF29 90-0GA16 | | 3RF29 90-0KA16 | 3RF29 90-0HA16 |
| RF23 90-3B.06 | 3RF29 00-0EA18 | | 3RF29 90-0GA16 | | 3RF29 90-0KA16 | 3RF29 90-0HA16 |
| RF23 90-3B.22 RF23 90-3B.24 | | | 3RF29 90-0GA33 3RF29 90-0GA36 | | | 3RF29 90-0HA33 3RF29 90-0HA36 |
| | | | | | | |

¹⁾ The use of power controllers/regulators is also possible on zero-point switching versions for full-wave control mode. The generalized phase control mode is recommended only for the combination with instantaneous switching versions.

Recommended assignment of the function modules to the 3RF24 three-phase solid-state contactors

| Order No. | o. Accessories | | | | | | | | | | | | |
|-------------------|-------------------------|-----------------|----------|-----------------|-------------------|------------------|--|--|--|--|--|--|--|
| | Converters | Load monitoring | | Heating current | Power controllers | Power regulators | | | | | | | |
| | | Basic | Extended | monitoring | | | | | | | | | |
| Type current up t | Type current up to 50 A | | | | | | | | | | | | |
| 3RF2414. | 3RF29 00-0EA18 | | | | | | | | | | | | |
| 3RF2424. | | | | | | | | | | | | | |
| 3RF2434. | 3RF29 00-0EA18 | | | | | | | | | | | | |
| 3RF245. | | | | | | | | | | | | | |

3RF29 Function Modules

SIRIUS converters for 3RF

Overview

Converters for 3RF2 solid-state switching devices

These modules are used to convert analog control signals, such as those output from many temperature controllers for example, into a pulse-width-modulated digital signal. The connected solid-state contactors and relays can therefore regulate the output of a load as a percentage.

Application

This function module is used for conversion from an analog input signal to an on/off ratio. The module can only be used in conjunction with 3RF21 and 3RF23 single-phase solid-state switching devices or 3RF22 and 3RF24 three-phase devices. It can be used on versions with 24 V DC and 24 V AC/DC control supply voltage.

Selection and ordering data

| Rated operational current I_e | Rated operational voltage $U_{\rm e}$ | DT | Order No. | Price per PU | PU (UNIT, SET, M) | PS* | PG | Weight per PU approx. |
|---------------------------------|---------------------------------------|----|-----------|-----------------|-------------------------|-----|----|-----------------------|
| A | V | | | | | | | kg |

Converters

Rated control supply voltage 24 V AC/DC

-

3RF29 00-0EA18

1 unit

0.041

* You can order this quantity or a multiple thereof.

3RF29 Function Modules

SIRIUS load monitoring for 3RF

Overview

Load monitoring for 3RF2 single-phase solid-state switching devices

Many faults can be quickly detected by monitoring a load circuit connected to the solid-state switching device, as made possible with this module. Examples include the failure of load elements (up to 6 in the basic version or up to 12 in the extended version), alloyed power semiconductors, a lack of voltage or a break in a load circuit. A fault is indicated by one or more LEDs and reported to the controller by way of a PLC-compatible output.

The principle of operation is based on permanent monitoring of the current intensity. This figure is continuously compared with the reference value stored once during start-up by the simple press of a button. In order to detect the failure of one of several loads, the current difference must be 1/6 (in the basic version) or 1/12 (in the extended version) of the reference value. In the event of a fault, an output is actuated and one or more LEDs indicate the fault.

Application

The device is used for monitoring one or more loads (partial loads). The function module can only be used in conjunction with a 3RF21 solid-state relay or a 3RF23 solid-state contactor. The devices with spring-type connections in the load circuit are not suitable.

Selection and ordering data

| Selection and orde | ering data | | | | | | | | |
|--------------------|---------------------------------------|---------------------------------------|--------|----------------------------------|-----------------|-------------------------|------------------|------------|-----------------------|
| | Rated operational current $I_{\rm e}$ | Rated operational voltage $U_{\rm e}$ | DT | Order No. | Price per PU | PU (UNIT, SET, M) | PS* | PG | Weight per PU approx. |
| | Α | V | | | | | | | kg |
| Basic load monitor | ring | | | | | | | | |
| 46 19 | Rated control supply | voltage 24 V DC | | | | | | | |
| | 6 | | Α | 3RF29 06-0FA08 | | 1 | 1 unit | 101 | 0.068 |
| 0. | 20 | | Α | 3RF29 20-0FA08 | | 1 | 1 unit | 101 | 0.068 |
| Table 4 | With mounted 3RF2 | 9 00-0RA88 cover | | | | | | | |
| SIEMENS B | 6 | | A | 3RF29 06-0FA08-0KH0 | | 1 | 1 unit | 101 | 0.068 |
| | 20 | | А | 3RF29 20-0FA08-0KH0 | | 1 | 1 unit | 101 | 0.068 |
| Extended load mo | nitoring | | | | | | | | |
| G A | Rated control supply | voltage 24 V AC/DC | | | | | | | |
| 1 | 20 | 110 230 | Α | 3RF29 20-0GA13 | | 1 | 1 unit | 101 | 0.175 |
| 3. 2. | 20 | 400 600 | Α | 3RF29 20-0GA16 | | 1 | 1 unit | 101 | 0.175 |
| | 50 50 | 110 230 400 600 | A A | 3RF29 50-0GA13 3RF29 50-0GA16 | | 1 1 | 1 unit 1 unit | 101 101 | 0.175 0.175 |
| STEMENS 200000000 | 90 90 | 110 230 400 600 | A A | 3RF29 90-0GA13 3RF29 90-0GA16 | | 1 1 | 1 unit 1 unit | 101 101 | 0.175 0.175 |
| SE AC SE MODE SAN | Rated control supply | voltage 110 V AC | | | | | | | |
| ssesee. | 20 20 | 110 230 400 600 | A A | 3RF29 20-0GA33 3RF29 20-0GA36 | | 1 1 | 1 unit 1 unit | 101 101 | 0.175 0.175 |
| | 50 50 | 110 230 400 600 | A A | 3RF29 50-0GA33 3RF29 50-0GA36 | | 1 1 | 1 unit 1 unit | 101 101 | 0.175 0.175 |
| | 90 | 110 230 | Α | 3RF29 90-0GA33 | | 1 | 1 unit | 101 | 0.175 |
| | 90 | 400 600 | Α | 3RF29 90-0GA36 | | 1 | 1 unit | 101 | 0.175 |
| | Version | | DT | Order No. | Price | PU | PS* | PG | Weight |
| | | | | | per PU | (UNIT, SET, M) | | | per PU approx. |
| 0 " 1 | | | | | | | | | kg |
| Optional accessor | Sealable covers | | В | 3RF29 00-0RA88 | | 1 | 10 units | 101 | 0.001 |
| | for function modules | (not for converters) | | | | | | | |
| - | | | | | | | | | |
| 3RF29 00-0RA88 | | | | | | | | | |
| | | | | | | | | | |

3RF29 Function Modules

SIRIUS heating current monitoring for 3RF

Overview

Heating current monitoring for 3RF2 single-phase solidstate switching devices

Many faults can be quickly detected by monitoring a load circuit connected to the solid-state switching device, as made possible with this module. Examples include the failure of up to 6 load elements, alloyed power semiconductors, a lack of voltage or a break in a load circuit. A fault is indicated by LEDs and reported to the controller by way of a relay output (NC contact).

The principle of operation is based on permanent monitoring of the current intensity. This figure is continuously compared with the reference value stored once during start-up. In order to detect the failure of one of several loads, the current difference must be 1/6 of the reference value. In the event of a fault, an output is actuated and the LEDs indicate the fault.

The heating current monitoring has a teach input and therefore differs from the load monitoring. This remote teaching function enables simple adjustment to changing loads without manual intervention.

Special versions: deviations from the standard version

3RF29 ..-0JA1.-1KK0

If the current is below 50% of the lower teach current during the teach routine, the device will go into "Standby" mode; the LOAD LED will flicker. The device thus detects a non-connected load, e. g. channels not required for tool heaters, and does not signal a fault. This mode can be reset by re-teaching.

Application

The device is used for monitoring one or more loads (partial loads). The function module can only be used in conjunction with a 3RF21 solid-state relay or a 3RF23 solid-state contactor. The devices with spring-type connections in the load circuit are not suitable.

Selection and ordering data

| | Rated operational current $I_{\rm e}$ | Rated operational voltage $U_{\rm e}$ | DT | Order No. | Price per PU | PU (UNIT, SET, M) | PS* | PG | Weight per PU approx. |
|---------------------|---------------------------------------|---------------------------------------|-------------|--|-----------------|-------------------------|----------------------------|-------------------|-------------------------|
| | Α | V | | | | | | | kg |
| Heating current mon | itoring ¹⁾ | | | | | | | | |
| 16 M | Rated control supply vo | tage 24 V AC/DC | | - | | | | | |
| 30.36 | 16 16 16 | 110 230 110 230 400 600 | A A A | 3RF29 16-0JA13 3RF29 16-0JA13-1KK0 3RF29 16-0JA16-1KK0 | | 1 1 1 | 1 unit 1 unit 1 unit | 101 101 101 | 0.175 0.175 0.175 |
| Minus Property | 32 32 32 | 110 230 400 600 400 600 | A A A | 3RF29 32-0JA13-1KK0 3RF29 32-0JA16 3RF29 32-0JA16-1KK0 | | 1 1 1 | 1 unit 1 unit 1 unit | 101 101 101 | 0.175 0.175 0.175 |
| | | | | | | | | | |

Supplied without control connector. The control connector can be purchased from Phoenix Contact by quoting Order No. 1982 790 (2.5 HC/6-ST-5.08).

| | Version | DI | Order No. | Price per PU | (UNIT, SET, M) | PS* | PG | weight per PU approx. | |
|----------------------|---|----|----------------|-----------------|-------------------|----------|-----|-----------------------------|--|
| | | | | | | | | kg | |
| Optional accessories | | | | | | | | | |
| | Sealable covers for function modules (not for converters) | В | 3RF29 00-0RA88 | | 1 | 10 units | 101 | 0.001 | |

3RF29 00-0RA88

0

3RF29 Function Modules

SIRIUS power controllers for 3RF

Overview

Power controllers for 3RF2 single-phase solid-state switching devices

The power controller is a function module for the autonomous power control of complex heating systems and inductive loads.

The following functions have been integrated:

- Power controller for adjusting the power of the connected load. Here, the setpoint value is set with a rotary knob on the module as a percentage with reference to the 100 % power stored as a setpoint value.
- Inrush current limitation: With the aid of an adjustable voltage ramp, the inrush current is limited by means of phase control. This is useful above all with loads such as lamps or infrared lamps which have an inrush transient current.
- Load circuit monitoring for detecting load failure, partial load faults, alloyed power semiconductors, lack of voltage or a break in the load circuit.

Note:

With the phase control operating mode, a partial load fault is detected by cyclic "scanning" of the load; the exact mode of operation is described in the data sheets!

Special versions:

deviations from the standard version

3RF29 04-0KA13-0KC0

During the teaching process the connected solid-state relay or contactor is not activated; i. e. no current flow takes place. No current reference value is stored. No part-load monitoring!

3RF29 ..-0KA1.-0KT0

No part-load monitoring!

Application

The power controller can be used for:

- · Complex heating systems
- Inductive loads
- Loads with temperature-dependent resistor
- · Loads with ageing after long-time service
- Simple indirect control of temperature

The power controller can be used on the instantaneously switching 3RF21 and 3RF23 solid-state switching devices (single-phase). If only the full-wave operating mode is used, the power controller can also be used on the "zero-point switching" solid-state relays and contactors.

Power control

The power controller adjusts the power in the connected load by means of a solid-state switching device depending on the setpoint selection. It does not compensate for changes in the mains voltage or load resistance. The setpoint value can be predefined externally as a 0 to 10 V signal or internally by means of a potentiometer. Depending on the setting of the potentiometer ($t_{\rm R}$), the control is carried out according to the principle of full-wave control or generalized phase control.

Full-wave control

In this operating mode the output is adjusted to the required setpoint value changing the on-to-off period. The period duration is predefined at one second.

Generalized phase control

In this operating mode the output is adjusted to the required set-point value by changing the current flow angle. In order to observe the limit values of the conducted interference voltage for industrial networks, the load circuit must include a reactor with a rating of at least 200 $\mu H. \\$

Selection and ordering data

| Coloution and on | aog data | | | | | | | | |
|--|---------------------------------------|---------------------------------------|----|---------------------|-----------------|-------------------------|----------|-----|-----------------------|
| | Rated operational current $I_{\rm e}$ | Rated operational voltage $U_{\rm e}$ | DT | Order No. | Price per PU | PU (UNIT, SET, M) | PS* | PG | Weight per PU approx. |
| | A | V | | | | | | | kg |
| Power controllers | s | | | | | | | | |
| 16 11 | Rated control supply | voltage 24 V AC/DC | | - | | | | | |
| | 4 | 110 230 | Α | 3RF29 04-0KA13-0KC0 | | 1 | 1 unit | 101 | 0.175 |
| | 4 | | Α | 3RF29 04-0KA13-0KT0 | | 1 | 1 unit | 101 | 0.175 |
| @ Q @ | 20 | | Α | 3RF29 20-0KA13 | | 1 | 1 unit | 101 | 0.175 |
| Great Marie A | 50 | | Α | 3RF29 50-0KA13 | | 1 | 1 unit | 101 | 0.175 |
| Services Manager | 90 | | Α | 3RF29 90-0KA13 | | 1 | 1 unit | 101 | 0.175 |
| TO AN AND THE COME AND | 20 | 400 600 | Α | 3RF29 20-0KA16 | | 1 | 1 unit | 101 | 0.175 |
| 6060000 | 50 | | Α | 3RF29 50-0KA16 | | 1 | 1 unit | 101 | 0.175 |
| | 50 | | Α | 3RF29 50-0KA16-0KT0 | | 1 | 1 unit | 101 | 0.175 |
| | 90 | | Α | 3RF29 90-0KA16 | | 1 | 1 unit | 101 | 0.175 |
| | | | | | | | | | |
| | Version | | DT | Order No. | Price per PU | PU (UNIT, SET, M) | PS* | PG | Weight per PU approx. |
| | | | | | | | | | kg |
| Optional accesso | ories | | | | | | | | |
| | Sealable covers for function module | s (not for converters) | В | 3RF29 00-0RA88 | | 1 | 10 units | 101 | 0.001 |

3RF29 00-0RA88

3RF29 Function Modules

SIRIUS power regulators for 3RF

Overview

Power regulators for 3RF2 single-phase solid-state switching devices

The power regulator is a function module for the autonomous power control of complex heating systems.

The following functions have been integrated:

- Power controller with proportional-action control for adjusting the power of the connected load. Here, the setpoint value is set with a rotary knob on the module as a percentage with reference to the 100 % power stored as a setpoint value. Changes in the mains voltage or in the load resistance are compensated in this case.
- Inrush current limitation: With the aid of an adjustable voltage ramp, the inrush current is limited by means of phase control. This is useful above all with loads such as lamps which have an inrush transient current.
- Load circuit monitoring for detecting load failure, alloyed power semiconductors, lack of voltage or a break in the load circuit. Part-load monitoring is not possible. Load fluctuations are compensated.

Application

The power regulator can be used for:

- Complex heating systems
- Heating elements with temperature-dependent resistor
- Heating elements with ageing after long-time service
- Simple indirect control of temperature

The power regulator can be used on the instantaneously switching 3RF21 and 3RF23 solid-state switching devices (single-phase). If only the full-wave operating mode is used, the power regulator can also be used on the zero-point switching solid-state relays and contactors.

Power control

The power regulator adjusts the power in the connected load by means of a solid-state switching device depending on the taught power and the selected setpoint. Changes in the mains voltage or in the load resistance are thus compensated by the power regulator. The setpoint value can be predefined externally as a 0 to 10 V signal or internally by means of a potentiometer. Depending on the setting of the potentiometer ($t_{\rm R}$), the adjustment is carried out according to the principle of full-wave control or generalized phase control.

Full-wave control

In this operating mode the output is adjusted to the required setpoint value changing the on-to-off period. The period duration is predefined at one second.

Generalized phase control

In this operating mode the output is adjusted to the required set-point value by changing the current flow angle. In order to observe the limit values of the conducted interference voltage for industrial networks, the load circuit must include a reactor with a rating of at least 200 $\mu H. \\$

Selection and ordering data

| | Rated operational current I_e | Rated operational voltage $U_{\rm e}$ | DT | Order No. | Price per PU | PU (UNIT, SET, M) | PS* | PG | Weight per PU approx. | |
|---------------------------------------|---|---------------------------------------|--------|----------------------------------|-----------------|-------------------------|------------------|------------|-----------------------|--|
| | А | V | | | | | | | kg | |
| egulators | | | | | | | | | | |
| | Rated control supply | voltage 24 V AC/DC | | | | | | | | |
| | 20 20 | 110 230 400 600 | A A | 3RF29 20-0HA13 3RF29 20-0HA16 | | 1 1 | 1 unit 1 unit | 101 101 | 0.175 0.175 | |
| | 50 50 | 110 230 400 600 | A A | 3RF29 50-0HA13 3RF29 50-0HA16 | | 1 1 | 1 unit 1 unit | 101 101 | 0.175 0.175 | |
| 4 | 90 90 | 110 230 400 600 | A A | 3RF29 90-0HA13 3RF29 90-0HA16 | | 1 1 | 1 unit 1 unit | 101 101 | 0.175 0.175 | |
| Rated control supply voltage 110 V AC | | | | | | | | | | |
| | 20 20 | 110 230 400 600 | A A | 3RF29 20-0HA33 3RF29 20-0HA36 | | 1 1 | 1 unit 1 unit | 101 101 | 0.175 0.175 | |
| | 50 50 | 110 230 400 600 | A A | 3RF29 50-0HA33 3RF29 50-0HA36 | | 1 1 | 1 unit 1 unit | 101 101 | 0.175 0.175 | |
| | 90 90 | 110 230 400 600 | A A | 3RF29 90-0HA33 3RF29 90-0HA36 | | 1 1 | 1 unit 1 unit | 101 101 | 0.175 0.175 | |
| | | | | | | | | | | |
| | Version | | DT | Order No. | Price per PU | PU (UNIT, SET, M) | PS* | PG | Weight per PU approx. | |
| accesso | rico | | | | | | | | kg | |
| accesso | Sealable covers for function modules | (not for converters) | В | 3RF29 00-0RA88 | | 1 | 10 units | 101 | 0.001 | |

3RF29 00-0RA88

Solid-State Contactors

General data

Overview



Solid-state contactors for switching motors

The solid-state contactors for switching motors are intended for frequently switching on and off three-phase current operating mechanisms up to 7.5 kW and reversing up to 3.0 kW. The devices are constructed with complete insulation and can be mounted directly on circuit breakers and SIRIUS overload relays, resulting in a very simple integration into motor feeders.

These three-phase solid-state contactors are equipped with a two-phase control which is particularly suitable for typical motor current circuits without connecting to the neutral conductor.

Important features

- Insulated enclosure with integrated heat sink
- Degree of protection IP20
- Integrated mounting foot to snap on a standard mounting rail or for assembly onto a support plate
- Variety of connection methods
- Plug-in control connection
- Display via LEDs

Switching functions

The solid-state contactors to switch motors are "instantaneous switching" because this method is particularly suited for inductive loads. By distributing the ON point over the entire sine curve of the mains voltage, disturbances are reduced to a minimum.

Selecting solid-state contactors

The solid-state contactors are selected on the basis of details of the network, the load and the ambient conditions. As the solid-state contactors are already equipped with an optimally matched heat sink, the selection process is considerably simpler than that for solid-state relays.

The following procedure is recommended:

- Determine the rated current of the load and the mains voltage
- Select a solid-state contactor with the same or higher rated current than the load
- Testing the maximum permissible switching frequency based on the characteristic curves (see manual). To do this, the starting current, the starting time and the motor loaded in in the operating phase must be known.
- If the permissible switching frequency is under the desired frequency, it is possible to achieve an increase by overdimensioning the motor!

Alternatively the correct device size can be determined on the Internet by entering the network and motor data along with the application and ambient conditions in the tool for the selection of solid-state contactors for switching motors. You will find the tool at:

www.siemens.com/solid-state-switching-devices

Benefits

- Units with integrated heat sink, "ready to use"
- Compact and space-saving design
- Reversing contactors with integrated interlocking

Application

There is no typical design of a load feeder with solid-state relays or solid-state contactors; instead, the great variety of connection methods and control voltages offers universal application opportunities. SIRIUS solid-state relays and solid-state contactors can be installed in fuseless or fused feeders, as required. There are special versions with which it is even possible to achieve short-circuit strength in a fuseless design.

Standards and approvals

- IEC 60947-4-3
- UL 508, CSA for North America¹⁾
- CE marking for Europe
- · C-Tick approval for Australia
- Please note: Use overvoltage protection device; max. cut-off-voltage 6000 V; min. energy handling capability 100 J.

Solid-State Contactors

General data

More information

Connection methods

You can choose between the following connection methods for the solid-state contactors for switching motors:

Screw connection

The screw connection system is the standard among industrial controls. Open terminals and a plus-minus screw are just two features of this technology. Two conductors of up to 6 mm² can be connected in just one terminal. As a result, loads of up to 50 A can be connected.

Spring-type terminal connection system

This innovative technology manages without any screw connection. This means that very high vibration resistance is achieved. Two conductors of up to 2.5 mm² can be connected to each terminal. As a result, loads of up to 20 A can be dealt with.

Short-circuit protection

Despite the rugged power semiconductors that are used, solidstate switching devices respond more sensitively to short-circuits in the load feeder. Consequently, special precautions have to be taken against destruction, depending on the type of design.

Siemens generally recommends using SITOR semiconductor fuses. These fuses also provide protection against destruction in the event of a short-circuit even when the solid-state contactors and solid-state relays are fully utilized.

Alternatively, if there is lower loading, protection can also be provided by standard fuses or miniature circuit breakers. This protection is achieved by overdimensioning the solid-state switching devices accordingly.

Specification

| Order No. | | 3RF24BB, 3RF24BD |
|---|---------|---|
| General data | | |
| Ambient temperature | | |
| During operation, derating from 40 °C | °C | -25 +60 |
| During storage | °C | -55 +80 |
| Installation altitude | m | 0 1000; derating over 1000 m upon request |
| Shock resistance acc. to IEC 60068-2-27 | g/ms | 15/11 |
| Vibration resistance acc. to IEC 60068-2-6 | g | 2 |
| Degree of protection | | IP20 |
| Insulation strength at 50/60 Hz (main/control circuit to floor) | V rms | 4000 |
| Electromagnetic compatibility (EMC) | | |
| • Emitted interference acc. to IEC 60947-4-3 | | |
| - Conducted interference voltage | | Class A for industrial applications ¹⁾ |
| - Emitted, high-frequency interference voltage | | Class A for industrial applications |
| Interference immunity | | |
| - Electrostatic discharge | kV | Contact discharge: 4; |
| acc. to IEC 61000-4-2 (corresponds to degree of severity 3) | | Air discharge: 8; Behavior criterion 2 |
| - Induced RF fields | MHz | 0.15 80; 140 dBµV; |
| acc. to IEC 61000-4-6 | IVII IZ | Behavior criterion 1 |
| - Burst acc. to IEC 61000-4-4 | kV | 2/5 kHz; behavior criterion 1 |
| - Surge acc. to IEC 61000-4-5 | kV | Conductor - Ground: 2; Conductor - Conductor: 1; Behavior criterion 2 |
| Permissible mounting positions | | 1400 1400 |
| | | ±10° ±10° ++++ NSB0_01703 |

¹⁾ These products were built as Class A devices. The use of these devices in residential areas could result in lead in radio interference. In this case these may be required to introduce additional interference suppression measures.

Solid-State Contactors

General data

Notes on integration in the load feeders

The SIRIUS solid-state switching devices are very easy to integrate into the load feeders thanks to their industrial connection method and design.

Particular attention must however be paid to the circumstances of the installation and ambient conditions, as the performance of the solid-state switching devices is largely dependent on these. Depending on the version, certain restrictions must be observed. Detailed information, for example in relation to solid-state contactors about the minimum spacing and to solid-state relays about the choice of heat sink, is given in the technical specifications (see manual) and the product data sheets.

For applications with a very large power requirement it is possible to use SIVOLT AC power controller. More information on the product range can be found in the Catalog DA 68 or in our Mall.

support.automation.siemens.com/WW/view/de/10862346

See ID: 10752358

Short-circuit and overload protection

Despite the rugged power semiconductors that are used, solidstate switching devices respond more sensitively to short-circuits in the load feeder. Consequently, special precautions have to be taken against destruction, depending on the type of design.

Siemens generally recommends using SITOR semiconductor protection fuses. These fuses also provide protection against destruction in the event of a short-circuit even when the solid-state contactors and solid-state relays are fully utilized.

Alternatively, if there is lower loading, protection can also be provided by standard fuses or miniature circuit breakers. This protection is achieved by overdimensioning the solid-state switching devices accordingly. The technical specifications and the product data sheets contain details both about the solid-state fuse protection itself and about use of the devices with conventional protection equipment.

Semiconductor motor and reversing contactors can be easily combined with the 3RV motor starter protectors and 3RB2 overload relay from the SIRIUS modular system. Thus, fuseless and fuse motor feeders can be designed easily and in a space-saving manner.

Electromagnetic compatibility (EMC)

The solid-state switching devices are suitable for interferencefree operation in industrial networks without further measures. If they are used in public networks, it may be necessary for conducted interference to be reduced by means of filters.

Suitable filters can be ordered from EPCOS AG. You can find more information on the Internet at:

www.epcos.com

Solid-State Contactors

SIRIUS 3RF24 solid-state contactors, three-phase

Overview

These two-phase controlled, instantaneous switching solid-state contactors in the insulting enclosure are offered in 45 mm width to 5.2~A – and in 90 mm width to 16~A. This means that it is possible to operate motors up to 7.5~kW.

The devices with screw connection can use a link module 1) to directly connect to a circuit breaker. Direct mounting on a 3RB20 electronic overload relay 2) is possible. Rapid-switching fuseless and fuse motor feeders can thereby be implemented in a time-saving manner.

Selection and ordering data

Motor contactors · Instantaneous switching · Two-phase controlled

| Second Content Incompany | | | | | | | | | | | |
|---|-------------------------------|---|--|---|------------------|--|----------|---|--|--|--|
| Rated operational voltage U ₆ 48 460 V Section | | | | | DT | Screw terminals | + | (UNIT, | PS* | PG | Weight per PU approx. |
| Rated operational voltage U ₆ 48 460 V S | | A | | V | | Order No. | | | | | kg |
| Section Sect | Rated operational | | 3 460 V | | | | | | | | |
| 9.2 4.0 B 3RF24 10-18B24 1 1 unit 101 00 101 101 101 101 101 101 101 101 | 000 | 5.2 9.2 12.5 | 2.2 4.0 5.5 | | B B | 3RF24 10-1BB04 3RF24 12-1BB04 | | 1 1 | 1 unit 1 unit | 101 101 | 0.250 0.380 0.380 0.380 |
| Second Color Col | OPEN OF APP | 9.2 12.5 | 4.0 5.5 | 110 230 AC | B B | 3RF24 10-1BB24 3RF24 12-1BB24 | | 1 1 | 1 unit 1 unit | 101 101 | 0.250 0.380 0.380 0.380 |
| Second | | voltage II 48 | 8 600 V | | | | | | | | |
| 5.2 2.2 24 DC acc. to EN 61131-2 B 3RF24 10-1BB06 1 1 unit 101 C 12.5 5.5 16 7.5 B 3RF24 12-1BB06 1 1 unit 101 C 10.5 16 7.5 B 3RF24 12-1BB06 1 1 unit 101 C 10.5 16 7.5 B 3RF24 12-1BB06 1 1 unit 101 C 10.5 16 7.5 B 3RF24 12-1BB06 1 1 unit 101 C 10.5 16 7.5 B 3RF24 12-1BB06 1 1 unit 101 C 10.5 16 7.5 B 3RF24 12-1BB06 1 1 unit 101 C 10.5 16 7.5 B 3RF24 10-1BB26 1 1 unit 101 C 10.5 16 7.5 B 3RF24 10-1BB26 1 1 unit 101 C 10.5 16 7.5 B 3RF24 10-1BB26 1 1 unit 101 C 10.5 16 7.5 B 3RF24 10-1BB26 1 1 unit 101 C 10.5 16 7.5 B 3RF24 10-1BB26 1 1 unit 101 C 10.5 16 7.5 B 3RF24 10-1BB26 1 1 unit 101 C 10.5 16 7.5 B 3RF24 10-1BB26 1 1 unit 101 C 10.5 16 7.5 B 3RF24 10-1BB26 1 1 unit 101 C 10.5 16 7.5 B 3RF24 10-1BB26 1 1 unit 101 C 10.5 16 7.5 B 3RF24 10-1BB26 1 1 unit 101 C 10.5 16 7.5 B 3RF24 10-2BB04 1 1 unit 101 C 10.5 16 7.5 B 3RF24 10-2BB04 1 1 unit 101 C 10.5 16 7.5 B 3RF24 10-2BB04 1 1 unit 101 C 10.5 16 7.5 B 3RF24 10-2BB24 1 1 unit 101 C 10.5 16 7.5 B 3RF24 10-2BB24 1 1 unit 101 C 10.5 16 7.5 B 3RF24 10-2BB24 1 1 unit 101 C 10.5 16 7.5 B 3RF24 10-2BB26 1 1 unit 101 C 10.5 16 7.5 B 3RF24 10-2BB06 1 1 unit 10 | blocking voltage | 1600 V | 5 000 V, | | | | | | | | |
| Pu | Many- | 5.2 9.2 12.5 16 | 4.0 5.5 7.5 | acc. to EN 61131-2 | B B B | 3RF24 10-1BB06 3RF24 12-1BB06 3RF24 16-1BB06 | | 1 1 1 | 1 unit 1 unit 1 unit | 101 101 101 | 0.250 0.380 0.380 0.380 |
| Rated operational current I_e and U_e voltage U_s v | | 9.2 12.5 | 4.0 5.5 | 110 230 AC | B B | 3RF24 10-1BB26 3RF24 12-1BB26 | | 1 | 1 unit 1 unit | 101 101 | 0.250 0.380 0.380 0.380 |
| Table Tabl | 0111 24 10 1BB | | | | | | | | | | |
| Table Tabl | | | | | | | | | | | |
| Rated operational voltage \$U_6\$ 48 460 V\$ 5.2 2.2 24 DC 8 3RF24 10-2BB04 1 1 unit 101 101 102 103 | | | | | | | | | | | |
| 5.2 | | | | | DT | Spring-type terminals | | (UNIT, | PS* | PG | Weight per PU approx. |
| 9.2 4.0 acc. to EN 61131-2 B 3RF24 10-2BB04 1 1 unit 101 C 101 C 102 C 1 | | tional current I _e | <i>I</i> _e and <i>U</i> _e 400 V | voltage U _s | DT | | Price | (UNIT, | PS* | PG | per PU approx. |
| 5.2 2.2 110 230 AC B 3RF24 10-2BB24 1 1 unit 101 0 101 101 101 101 101 101 101 101 | Rated operationa | tional current I _e | I _e and U _e 400 V kW | voltage U _s | DT | | Price | (UNIT, | PS* | PG | per PU |
| 12.5 | | A Voltage U _e 48 5.2 9.2 12.5 | I _e and U _e 400 V kW 3 460 V 2.2 4.0 5.5 | voltage $U_{\rm S}$ V | B B B | Order No. 3RF24 05-2BB04 3RF24 10-2BB04 3RF24 12-2BB04 | Price | (UNIT, SET, M) 1 1 1 | 1 unit 1 unit 1 unit | 101 101 101 | per PU approx. kg 0.250 0.380 0.380 |
| Rated operational voltage U _e 48 600 V, blocking voltage 1600 V 5.2 2.2 24 DC B 3RF24 05-2BB06 1 1 unit 101 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 | | A voltage <i>U</i> _e 48 5.2 9.2 12.5 16 5.2 | I _e and U _e 400 V kW 3 460 V 2.2 4.0 5.5 7.5 | voltage U _s V 24 DC acc. to EN 61131-2 | B B B B | Order No. 3RF24 05-2BB04 3RF24 10-2BB04 3RF24 12-2BB04 3RF24 16-2BB04 3RF24 05-2BB24 | Price | (UNIT, SET, M) 1 1 1 1 | 1 unit 1 unit 1 unit 1 unit 1 unit | 101 101 101 101 | per PU approx. kg 0.250 0.380 0.380 0.380 0.250 |
| Rated operational voltage U _e 48 600 V, blocking voltage 1600 V 5.2 2.2 24 DC B 3RF24 05-2BB06 1 1 unit 101 0 101 | | A voltage U _e 48 5.2 9.2 12.5 16 5.2 9.2 12.5 | I _e and U _e 400 V kW 3 460 V 2.2 4.0 5.5 7.5 2.2 4.0 5.5 | voltage U _s V 24 DC acc. to EN 61131-2 | B B B B B B B | Order No. 3RF24 05-2BB04 3RF24 10-2BB04 3RF24 12-2BB04 3RF24 16-2BB04 3RF24 10-2BB24 3RF24 10-2BB24 3RF24 12-2BB24 | Price | (UNIT, SET, M) 1 1 1 1 1 1 1 1 1 | 1 unit 1 unit 1 unit 1 unit 1 unit 1 unit 1 unit | 101 101 101 101 101 101 | per PU approx. kg 0.250 0.380 0.380 0.380 0.250 0.380 0.380 |
| 5.2 2.2 24 DC B 3RF24 05-2BB06 1 1 unit 101 0 9.2 4.0 acc. to EN 61131-2 B 3RF24 10-2BB06 1 1 unit 101 0 16 7.5 B 3RF24 12-2BB06 1 1 unit 101 0 5.2 2.2 110 230 AC B 3RF24 05-2BB06 1 1 unit 101 0 9.2 4.0 B 3RF24 10-2BB26 1 1 unit 101 0 12.5 5.5 B 3RF24 10-2BB26 1 1 unit 101 0 | | A voltage U _e 48 5.2 9.2 12.5 16 5.2 9.2 12.5 | I _e and U _e 400 V kW 3 460 V 2.2 4.0 5.5 7.5 2.2 4.0 5.5 | voltage U _s V 24 DC acc. to EN 61131-2 | B B B B B B B | Order No. 3RF24 05-2BB04 3RF24 10-2BB04 3RF24 12-2BB04 3RF24 16-2BB04 3RF24 10-2BB24 3RF24 10-2BB24 3RF24 12-2BB24 | Price | (UNIT, SET, M) 1 1 1 1 1 1 1 1 1 | 1 unit 1 unit 1 unit 1 unit 1 unit 1 unit 1 unit | 101 101 101 101 101 101 | per PU approx. kg 0.250 0.380 0.380 0.380 0.250 0.380 |
| 9.2 4.0 B 3RF24 10-2BB26 1 1 unit 101 0 12.5 5.5 B 3RF24 12-2BB26 1 1 unit 101 0 | 3RF24 10-2BB Rated operationa | A voltage U _e 48 5.2 9.2 12.5 16 5.2 9.2 12.5 16 voltage U _o 48 | I _e and U _e 400 V kW 3 460 V 2.2 4.0 5.5 7.5 2.2 4.0 5.5 7.5 | voltage U _s V 24 DC acc. to EN 61131-2 | B B B B B B B | Order No. 3RF24 05-2BB04 3RF24 10-2BB04 3RF24 12-2BB04 3RF24 16-2BB04 3RF24 10-2BB24 3RF24 10-2BB24 3RF24 12-2BB24 | Price | (UNIT, SET, M) 1 1 1 1 1 1 1 1 1 | 1 unit 1 unit 1 unit 1 unit 1 unit 1 unit 1 unit | 101 101 101 101 101 101 | per PU approx. kg 0.250 0.380 0.380 0.380 0.250 0.380 0.380 |
| 16 7.5 B 3RF24 16-2BB26 1 1 unit 101 0 | 3RF24 10-2BB Rated operationa | tional current I _e A Voltage U _e 48 5.2 9.2 12.5 16 5.2 9.2 12.5 16 Voltage U _e 48 1600 V 5.2 9.2 12.5 | I _e and U _e 400 V kW 3 460 V 2.2 4.0 5.5 7.5 2.2 4.0 5.5 7.5 3 600 V, | voltage <i>U</i> _s V 24 DC acc. to EN 61131-2 110 230 AC | BBBB BBBB BBBB | Order No. 3RF24 05-2BB04 3RF24 10-2BB04 3RF24 12-2BB04 3RF24 16-2BB04 3RF24 10-2BB24 3RF24 10-2BB24 3RF24 10-2BB24 3RF24 10-2BB26 3RF24 10-2BB06 3RF24 10-2BB06 3RF24 10-2BB06 3RF24 10-2BB06 | Price | (UNIT, SET, M) 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 | 1 unit 1 unit | 101 101 101 101 101 101 101 101 101 101 | per PU approx. kg 0.250 0.380 0.380 0.380 0.250 0.380 0.380 |

¹⁾ For 3RA19 21-1AA00 link modules see next page.

²⁾ For 3RB20 overload relays see Chapter 5.

Solid-State Contactors

SIRIUS 3RF24 solid-state reversing contactors, three-phase

Overview

The integration of four conducting paths to a reverse switch, combined in one enclosure makes this device a particularly compact solution. Compared to conventional systems, for which two contactors are required, it is possible to save up to 50 % width with the three-phase reversing contactors. Devices with 45 mm width cover motors up to 2.2 kW – and those with 90 mm width up to 3 kW.

Due to the integration into the SIRIUS modular system, it is possible to make a connection to a SIRIUS motor starter protector using a link module or with a 3RB20¹⁾ solid-state overload relay without additional steps. It is possible to mount fuseless or fused motor feeders easily and quickly.

Selection and ordering data

Reversing contactors · Instantaneous switching · Two-phase controlled

| | Rated operational current I _e | | Rated control supply voltage $U_{\rm S}$ | DT | Screw terminals | ⊕ | PU (UNIT, SET, M) | PS* | PG | Weight per PU approx. |
|-----------------------|--|-------------------|--|-------------|--|-----------------|-------------------------|----------------------------|-------------------|-------------------------|
| | А | 400 V kW | ٧ | | Order No. | Price per PU | | | | kg |
| Rated operational | voltage U _e 48 | 3 460 V | | | | | | | | |
| 600 | 3.8 5.4 7.4 | 1.5 2.2 3.0 | 24 DC acc. to EN 61131-2 | B B B | 3RF24 03-1BD04 3RF24 05-1BD04 3RF24 10-1BD04 | | 1 1 1 | 1 unit 1 unit 1 unit | 101 101 101 | 0.280 0.280 0.410 |
| 1000 | 3.8 5.4 7.4 | 1.5 2.2 3.0 | 110 230 AC | B B B | 3RF24 03-1BD24 3RF24 05-1BD24 3RF24 10-1BD24 | | 1 1 1 | 1 unit 1 unit 1 unit | 101 101 101 | 0.280 0.280 0.410 |
| 3RF24 03-1BD | | | | | | | | | | |
| 1) For 3RB20 overload | relays see Chap | oter 5. | | | | | | | | |

Accessories

| Accessories | | | | | | | | | |
|----------------|--|-----------------------|-------------|-----------------|-----------------|-------------------------|----------|-----|-----------------------|
| | Version | Packing material | DT | Screw terminals | + | PU (UNIT, SET, M) | PS* | PG | Weight per PU approx. |
| | | | | Order No. | Price per PU | | | | kg |
| Link modules | | | | | | | | | |
| | For mechanical and electrical connection between contactor | Single-unit packaging | > | 3RA19 21-1AA00 | | 1 | 1 unit | 101 | 0.037 |
| | and motor starter protector with screw terminals | Multi-unit packaging | • | 3RA19 21-1A | | 1 | 10 units | 101 | 0.028 |
| 3RA19 21-1AA00 | | | | | | | | | |

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Solid-State Switching Devices for Switching Motors Solid-State Contactors

Notes