

Safety modules

Safety drive controller | Speed and position monitoring for 2 axes | Safety-MSP2



Compact safety control with integrated drive monitoring for two axes and extended encoder interface. This device is freely programmable for the safe processing of drive-related safety functions as well as of EMERGENCY STOP switches, two-hand operator controls, light barriers, operating mode selectors, etc. Complex movement monitoring tasks are also possible when both axes are combined.

The basic version allows achieving 2 safe encoder connections. 14 safe inputs and 3 shut-off channels are available.

1-encoder solutions (Incr-TTL/HTL, Resolver, SinCos, Proxi-SW.) and to a limited extent also 2-encoder solutions (combinations of any encoder technology) are supported for the safe speed and/or position detection.

- Extensive bibliotheca of pre-configured safe sensors and command device
- Complete range of speed- and position-related safe drive monitoring functions as per EN 61800 already integrated
- Encoder interface with many parameters and configuration options for 4 x Incr-TTL / SinCos / SSI / Resolver on front side and 2 x HTL or Proxi-SW by terminals
- Graphical programming interface by SafePLC-SW

- Basic unit comes with 14 safe input lines, 3 cut off channels, hereof 1 safe relay output and 2 standard outputs
- Cross-short-cut monitoring functionality
- Output contact multiplication or increase of power capability by external contactors in connection with the device-internal monitoring function for external contacts
- Extensive diagnostic functionality integrated in FW
- Status monitoring by coded 7-segment-display and status LED's
- Quit- / Start- / Reset button on the front display
- Extendable up to max. 65 safe I/O lines by means of an integrated backplane bus (connector for top hat rail mount)
- Interface modules for all major fieldbus systems available (Profibus, ProfiNet, CANopen, EtherCAT)

Order-No.		Accessories	
Safety-MSP2	Speed and position monitoring for 2 axes	T-bus connector	05.TBMS.000
	8.MSP2.000	Programming cable	8.0010.9000.0020
The programming software SafePLC and the programming cable are required for programming. The T-BUS connector is required for connecting a BUS module or an extension module.		Programming software Safe PLC	05.SP.LC.001
		Parameterising software - Free	05.SP.MT.000

General data	
Max. number of extension modules	2
Interface for extension modules	T-bus connector for top hat rail mount
Safe digital input lines	14 incl. 8 OSSD
Safe digital output lines	2
Safe relay outputs	1
Standard output lines	2
Pulse output lines	2
Type of connection	pluggable terminals
Drive monitoring - number of axis	1 axis / 2 axes
Encoder interface front side	4 x SSI; SinCos; Incr-TTL, Resolver
Max. frequency SinCos; Incr-TTL	200 kHz
Clock frequency / mode SSI	Master Mode 150 kHz / Slave Mode max. 250 kHz
Type of connection	D-SUB 9 pol
Encoder interface terminals	2 x Proxi-Sw.; Incr-HTL
Max. frequency HTL	10 kHz
Type of connection	pluggable terminals

Electrical characteristics	
Supply voltage	24 V DC / 2 A
Tolerance	-15%, +20%
Power consumption	2,4 W
Rated data digital inputs	24 V DC / 20 mA, Typ 1 to EN 61131-2
Rated data digital outputs	24 V DC / 250 mA
Rated data relay outputs	24 V DC / 2 A and 230 V AC / 2 A
Pulse output lines	max. 250 mA
Max. fuse on supply voltage	max. 2 A

Environmental data	
Operating temperature	0°C ... +50°C
Storage temperature	-10°C ... +70°C
Type of protection	IP52
Climate class	3 acc. to DIN 50178
EMI	acc. to EN 55011 and EN 61000-6-2

Safety characteristics	
PL acc. to EN 13849	PLe
PFH / Architecture	6,2 x 10 ⁻⁹ / Architecture Class 4
SIL acc. to EN 61508	SIL 3
Proof-test-interval	20 years = max. period of application

Mechanical characteristics	
Size h x d x w [mm]	100 x 115 x 112,5
Weight	520 g
Mounting	snap-on mounting on standard head rail
Max. terminal cross section	1,5 mm ²

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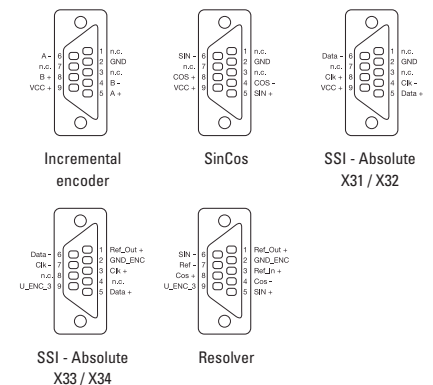
Terminal assignment

X11	1	● Power supply module +24 V DC	U24 external
	2	● Power supply module +24 V DC	U24 external
	3	● Power supply module 0 V DC	GND external
	4	● Power supply module 0 V DC	GND external
X12	1	● Digital IN 13	DI 13
	2	● Digital IN 14	DI 14
	3	● Pulse output P1	P1
	4	● Pulse output P2	P2
X13	1	● Power supply encoder interface X31	U_ENC_1
	2	● Power supply encoder interface X31	GND_ENC_1
	3	● Messaging and auxiliary output DO 0.1	DO 0.1
	4	● Messaging and auxiliary output DO 0.2	DO 0.2
X14	1	● Digital IN 01 OSSD compatible	DI 01
	2	● Digital IN 02 OSSD compatible	DI 02
	3	● Digital IN 03 OSSD compatible	DI 03
	4	● Digital IN 04 OSSD compatible	DI 04
X15	1	● Power supply encoder interface X32	U_ENC_2
	2	● Power supply encoder interface X32	GND_ENC_2
	3	● NC	NC
	4	● NC	NC
X16	1	● NC	NC
	2	● NC	NC
	3	● NC	NC
	4	● NC	NC
X17	1	● Power supply Encoder 3	U_ENC_3
	2	● Ground Encoder 3	GND_ENC_3
	3	● U_Ref_Encoder 3	U_Ref_3
	4	● NC	NC
X18	1	● NC	NC
	2	● NC	NC
	3	● NC	NC
	4	● NC	NC

X19	1	● Power supply Encoder 4	U_ENC_4
	2	● Ground Encoder 4	GND_ENC_4
	3	● U_Ref_Encoder 4	U_Ref_4
	4	● NC	NC
X20	1	● NC	NC
	2	● NC	NC
	3	● NC	NC
	4	● NC	NC
X21	1	● HISIDE output 0	DO 0-HI
	2	● LOSIDE output 0	DO 0-LO
	3	● HISIDE output 1	DO 1-HI
	4	● LOSIDE output 1	DO 1-LO
X22	1	● Relay output 1	K1.1
	2	● Relay output 1	K1.2
	3	● Relay output 2	K2.1
	4	● Relay output 2	K2.2
X23	1	● Digital IN 05	DI 05
	2	● Digital IN 06	DI 06
	3	● Digital IN 07	DI 07
	4	● Digital IN 08	DI 08
X24	1	● Digital IN 09 OSSD compatible	DI 09
	2	● Digital IN 10 OSSD compatible	DI 10
	3	● Digital IN 11 OSSD compatible	DI 11
	4	● Digital IN 12 OSSD compatible	DI 12
X25	1	● NC	NC
	2	● NC	NC
	3	● NC	NC
	4	● NC	NC
X26	1	● NC	NC
	2	● NC	NC
	3	● NC	NC
	4	● NC	NC

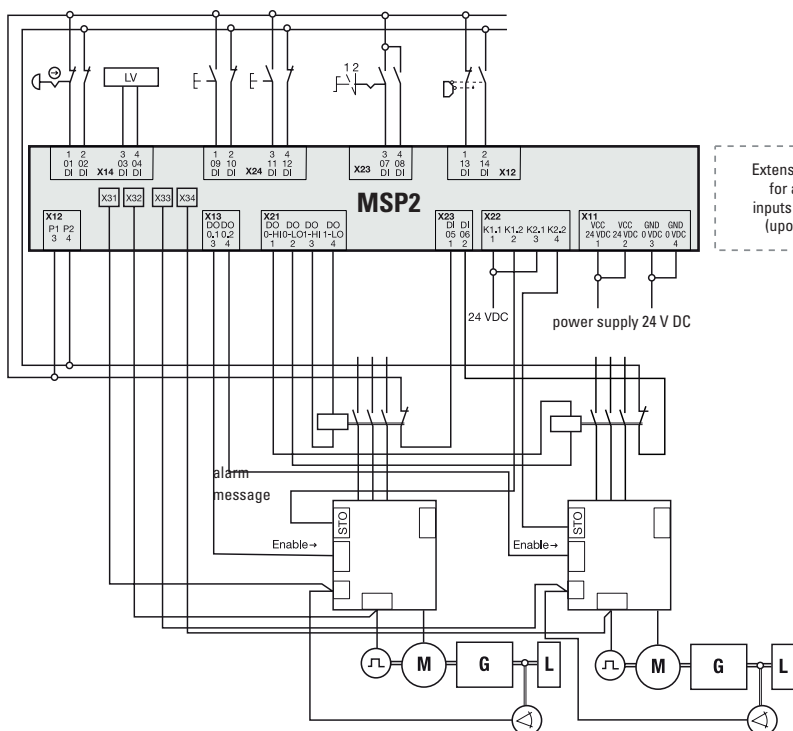
X27	1	● HTL_A_1	HTL_A_1
	2	● HTL_A_2	HTL_A_2
	3	● HTL_A_3	HTL_A_3
	4	● NC	NC
X28	1	● HTL_B_1	HTL_B_1
	2	● HTL_B_2	HTL_B_2
	3	● HTL_B_3	HTL_B_3
	4	● NC	NC
X29	1	● HTL_A_1	HTL_A_1
	2	● HTL_A_2	HTL_A_2
	3	● HTL_A_3	HTL_A_3
	4	● NC	NC
X30	1	● HTL_B_1	HTL_B_1
	2	● HTL_B_2	HTL_B_2
	3	● HTL_B_3	HTL_B_3
	4	● NC	NC

Sensor pin assignment



The variable encoder supply has to be provided external. It will be internal monitored.

Connection example



Standard fieldbus interface

Extension modules for additional inputs and outputs (upon request)

BM

Overview inputs / outputs

14 x	digital inputs
2 x	pulse outputs
2 x	digital outputs relays
2 x	digital outputs LOSIDE
2 x	digital outputs HISIDE
2 x	messaging outputs